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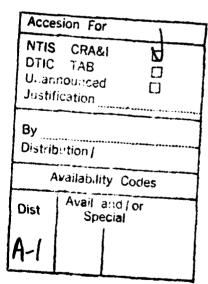
# SEASOAR and CTD Observations During a COARE Surveys Cruise, W9211C, 22 January to 22 February 1993.

A. Huyer, P.M. Kosro, R. O'Malley, J. Fleischbein

College of Oceanic and Atmospheric Sciences

Oregon State University Corvallis, Oregon 97331-5503

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## **Table of Contents**

Introduction	1
Cruise Narrative	6
CTD Data Acquisition, Calibration and Data Processing	13
Seasoar Data Acquisition and Preliminary Processing	15
Seasoar Conductivity Calibration	15
Post-Processing of Seasoar Data Background Procedures	21 21 28
Data Presentation	31
CTD/Seasoar Comparison	31
Acknowledgments	32
References	32
CTD Data	33
Seasoar Trajectories	47
Ensemble Profiles of Seasoar Temperature and Salinity N2S W2E E2N SBN to Equator	99 100 124 136 148
Vertical Sections of Temperature, Salinity and Sigma-t N2S Temperature Salinity Sigma-t S2W Temperature Salinity	149 150 162 174 186 198
Sigma-t	210

Vertical Sections of Temperature, Salinity and Sigma-t (Cont'd)	
W2E Temperature	222
Salinity	234
Sigma-t	246
E2N Temperature	258
Salinity	270
Sigma-t	282
SBN to Equator	294
Appendix A:	
Time Series of Maximum T/C Correlations and Lags for Seasoar Tow	rs 2-6297
Appendix B:	
T-S Diagrams from CTD and Seasoar at Start and End of Tows 2-6.	315

## SEASOAR and CTD Observations During a COARE Surveys Cruise, W9211C, 22 January to 22 February 1993.

#### Introduction

An international Coupled Ocean-Atmosphere Response Experiment (COARE) was conducted in the warm-pool region of the western equatorial Pacific Ocean over a four-month period from November 1992 through February 1993 (Webster and Lukas, 1992). Most of the oceanographic and meteorological observations were concentrated in the Intensive Flux Array (IFA) centered at 1° 45'S, 156°00'E. As part of this experiment, the R/V Wecoma conducted three survey cruises on the R/V Wecoma; each cruise included measurements of the temperature, salinity and velocity distribution in the upper 300 m of the ocean, and continuous meteorological measurements of wind, air temperature, humidity, etc. Most of these measurements were along a butterfly pattern that was sampled repeatedly during the three COARE Surveys cruises, W9211A and W9211B, and W9211C.

Coordinates of the Standard Butterfly Pattern were chosen to measure zonal and meridional gradients across the center of the IFA, spanning the profiling current meter array, while avoiding moorings and stationary ships without frequent deviations from our track (Figure 1). The standard coordinates of the butterfly apexes are:

SBN	1°14'S	156°06'E
SBS	2°26'S	156°06'E
SBW	1°50'S	155°30'E
SBE	1°50'S	156°42'E,

and sampling was done sequentially along the track joining these four points, i.e. along a meridional section (N2S) from SBN to SBS, a diagonal section (S2W) from SBS to SBW, a zonal section (W2E) from SBW to SBE, and a diagonal section (E2N) from SBE to SBN to complete the pattern. Along this track, we measured the upper ocean temperature and salinity by means of a towed undulating Seasoar vehicle (Figure 2) equipped with a SeaBird CTD system, while underway at 7-8 knots. CTD casts were made at the beginning and end of each tow, primarily to check calibration of the Seasoar sensors. Water velocity along the ship's track was measured by means of the ship-borne acoustic Doppler current profiler.

This report summarizes the Seasoar and CTD observations from Wecoma's third COARE Surveys cruise, W9211C. It also provides a cruise narrative, and a brief description of the data processing procedures.

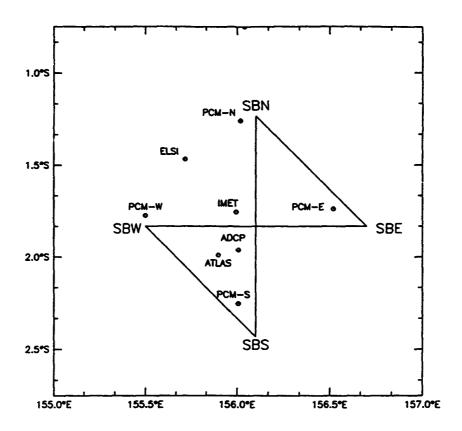


Figure 1. The Standard Butterfly Pattern in relation to the moorings of the COARE Intensive Flux Array.

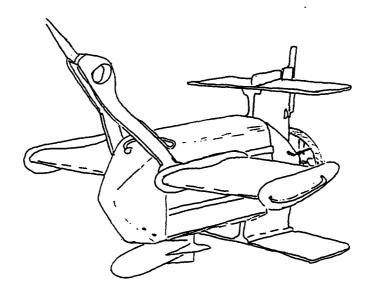


Figure 2. Sketch of the Seasoar vehicle used during W9211C.

Table 1. Summary of CTD stations during W9211C.

Date	Time (UTC)	Station No.	Latitude	Longitude	Wind Dir. (T)	Wind Spd. (kts)	Atmos. P. (mbar)
26 Jan	1439	1	03°07.4'N	156°07.1'E	26 <b>0</b> ´	10	1005.8
27 Jan	0725	2	01°14.0'S	156°06.0'	310	8	1006.8
29 Jan	0540	3	02°27.2'	156°07.8'	300	9	1007.2
29 Jan	0750	4	02°22.0'	156°02.0	320	11	1008.3
3 Feb	2035	5	01°51.3'	155°30.3'	<b>34</b> 0	20	1010.8
3 Feb	2159	6	01°51.2'	155°34.1'	350	19	1012.3
7 Feb	0003	7	01°17.2'	156°09.6'	<b>34</b> 0	10	1010.7
7 Feb	1930	8	01°14.0'	156°06.0'	340	12	1008.4
12 Feb	2059	9	02°00.4'	155°40.4'	335	13	1009.6
12 Feb	2320	10	02°00.3'	155°40.7'	330	15	1010.0
13 Feb	0440	11	01°59.3'	155°43.4'	310	10	1007.2
16 Feb	2130	12	00°08.7'S	156°06.1'E	070	10	1010.3

Table 2. Instruments and sensors used for CTD, Seasoar, and underway salinity sampling, W9211C, and date of most recent manufacturer's pre-cruise calibration.

System (Instrument)	Sensor	Pro	e-Cruise Calibration Date
CTD (SBE 9/11 plus SN 0256)	P	50130	5 Mar 92
·	<b>T</b> 1	1364	6 Oct 92 (modified 2 Dec 92)
	T2	1366	6 Oct 92 (modified 2 Dec 92)
	C1	1018	16 Sept 92
	C2	1021	16 Sept 92
Seasoar (SBE 9/11 plus SN 2843)			
(Tows 1-6)	P	39107	5 Mar 92
	C1	1030	17 Apr 92
	C2	1041	24 Apr 92
(Tows 1-3)	<b>T</b> 1	1367	27 Mar 92 (modified 2 Dec 92)
	T2	1369	27 Mar 92 (modified 2 Dec 92)
(Tows 4-6)	<b>T1</b>	997	6 Oct 92 (modified 2 Dec 92)
	T2	1384	6 Oct 92 (modified 2 Dec 92)
5-m Intake (MIDAS)	T	854	10 Aug 90
· ,	С	1070	23 Sept 92

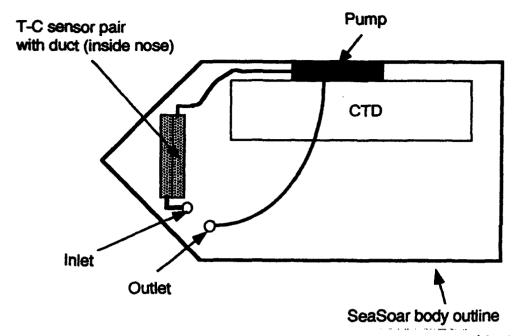


Figure 3. Schematic of the plumbing of the ducted T/C sensors inside the Seasoar vehicle. Primary sensor inlet and outlet ports were on the starboard side of the Seasoar nose; secondary sensor ports were on the port side. During Tow 2, both ducts were disconnected at the outlet from the pump; during Tow 4, the secondary sensor duct was disconnected at the outlet port.

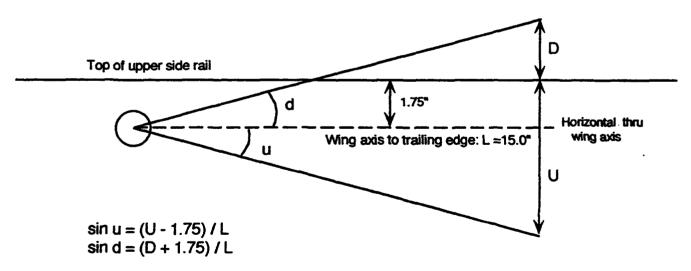
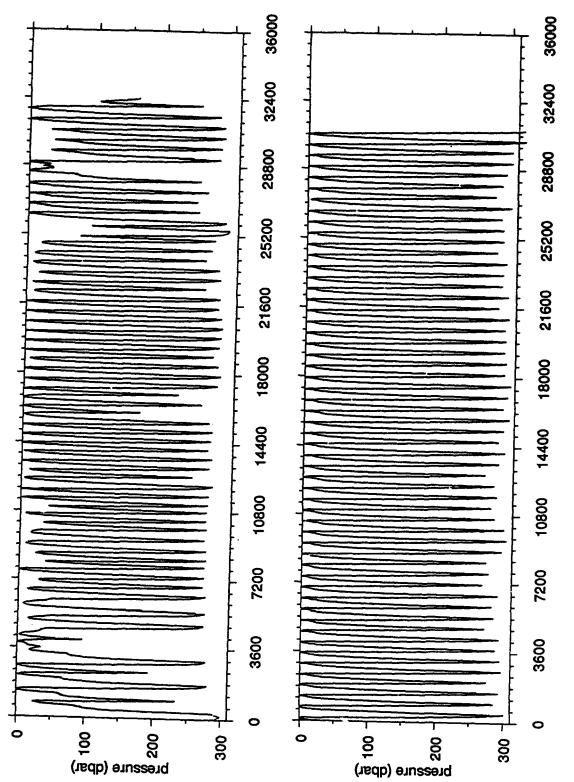


Figure 4. Schematics of Seasoar wing angle settings. During Tows 1 and 2, the value of D was  $2^3/8$ " and U was  $7^5/8$ ", yielding an up-angle of 23° and a down-angle of 16°. During Tows 3 through 6, D was  $2^5/8$ " and U was  $7^3/8$ ", yielding an up-angle of 22° and a down-angle of 17°.



wing angle setting to from a maximum down-angle of 16° to a maximum down-angle of 17°. Top: the N2S section on 28 January during Tow 2. Bottom: the W2E section on 31 January during Tow 3. Figure 5. Examples of Seasoar trajectory (pressure vs. time in seconds) before and after changing the

#### Cruise Narrative, W9211C

Wecoma departed from Guam about 0000 UTC, 22 Jan 1993, and began a transit to 3°N, 156°E where we intended to begin a cross-equatorial Seasoar section. After arrival on 26 January, we made a pre-tow CTD cast (Station 1, Table 1) with an SBE 9/11 plus CTD with dual ducted temperature and conductivity sensors (Table 2). Seasoar was deployed for Tow 1 at about 0600 UTC, 26 Jan at 3°08'N, 156°07'E; the Seasoar vehicle (Figure 2) was equipped with an SBE 9/11 plus CTD (SN 0256) with dual ducted temperature and conductivity sensors (Table 2; Figure 3). Tow 1 began normally, but in about 10 minutes the vehicle stopped responding to the control signal, and Seasoar was recovered on deck about 0845 UTC, 26 Jan. There was no evidence of a leak in the hydraulic unit, but it had definitely lost its power (after working successfully for more than 800 hours of consecutive towing in W9211A and W9211B). We then proceeded directly to the COARE Intensive Flux Array to begin sampling along the Standard Butterfly Pattern (Figure 1).

A new hydraulic unit (SN 011) was installed in the Seasoar vehicle, and the pushrods were adjusted to set the wing-angle so that the maximum up-angle was 23° and the maximum down-angle was 16° (Figure 4).

When we arrived at SBN, the northern apex of the Standard Butterfly Pattern, we made a pre-tow CTD cast to 500 m (Station 2, Table 1) and then deployed Seasoar at about 0845 UTC, 27 January. Tow 2 began southward toward SBS along the N2S line and continued along the Standard Butterfly in the usual direction (Table 3); for a 12-km portion of the line between SBE and SBN, the Seasoar was kept at depths below 30 m to avoid contamination from emptying the ship's tanks. The Seasoar vehicle was very difficult to control in the presence of strong vertical shear, so the resulting trajectories were quite irregular (e.g., Figure 5); we tentatively concluded that the 16° down-angle was too shallow. Preliminary temperature and salinity profiles and T-S diagrams showed there was a flow-rate problem through both T-C ducts from about the beginning of Tow 2, particularly during descent. Seasoar was recovered at SBS at about 0500 UTC, 29 January and we found that the outflow from the pumps was not connected to the tubes leading to the outlet ports through the nose of the vehicle (Figure 3); instead, the outflow from both sensor ducts was about 10 inches above the intake and into the interior of the Seasoar vehicle during Tow 2. CTD Station 3 (Table 1) was completed immediately after recovery.

After Tow 2, we changed the Seasoar wing angle setting to yield a maximum up-angle of 22° and a maximum down-angle of 17° (Figure 4) and reinstalled the CTD, checking the continuity of both sensor ducts with running

Table 3. Times (UTC) of standard waypoints during Tow 2 of W9211C. Positions of these waypoints are: SBN (1°14'S, 156°06'E); SBS (2°26'S, 156°06'E); SBW (1°50'S, 155°30'E); SBE (1°50'S, 156°42'E).

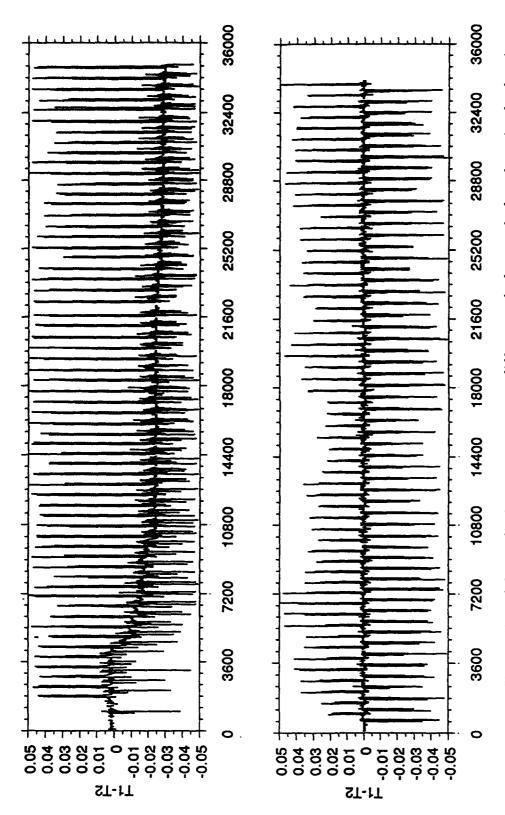
	Begin/End	SBN	SBS	SBW	SBE
27 January 28 January	0846	0917	1827	0143	1207
28 January 29 January		1930	0430		
29 January	0503		0.200		

Table 4. Times (UTC) of standard waypoints during Tow 3 of W9211C.

	Begin/End	SBN	SBS	SBW	SBE
29 January	0920			1646	
30 January					0225
30 January		0945	1926		
31 January				0238	1112
31 January		1827			
1 February			0358	1124	2015
2 February		0320	1221	1925	
2 February	2004				

Table 5. Times (UTC) of standard waypoints during Tow 4 of W9211C.

	Begin/End	SBN	SBS	SBW	SBE
3 February	1306			1410	2304
4 February		0604	1524	2230	
5 February					0719
5 February		1425			
6 February			0015	0747	1641
6 February	2315				



and secondary temperature sensors in Seasoar; high frequency fluctuations seem to be due to vehicle roll, i.e., to small differences in the depth of the two sensors. Top: the difference between sensors SN 1364 and Figure 6. Time series of the preliminary temperature differences before and after changing both primary 1366 during the W2E section on 29 January; sensor 1366 malfunctioned. Bottom: the difference between sensors SN 997 and 1384 during the W2E section on 11 February.

Table 6. Times (UTC) of standard waypoints during Tow 5 of W9211C.

	Begin/End	SBN	SBS	SBW	SBE
7 February	2058	2200			
8 February			0820	1524	
9 February					0114
9 February		0803	1824, 1921		
10 February				0200	1128
10 February		1819			
11 February			0452	1207	2135
12 February		0433	1456		
12 February	2036				

Table 7. Times (UTC) of standard waypoints during Tow 6 of W9211C.

	Begin/End	SBN	SBS	SBW	SBE
13 February 14 February	0551	0151	1139	0845 1833	1856
15 February		0201	1407	1000	0456
15 February		1137			
15 February	2047				

Table 8. Summary of Seasoar Tows, W9211C. Parameter values in the last column (for the T/C alignment offset, and for the amplitude and time constant of the thermal mass of the conductivity cell) were used for the preliminary (at-sea) data processing.

Tow No.	Start Time	Stop Time	Duration (hrs)	Parameters Measured	T/C Pair (and Parameter used for At-Sea Analysis
1	01/26/0605	01/26/0840	0	P, T1, C1, T2, C2	T2, C2 (3.25, 0.045, 8.0)
2	01/27/0846	01/29/0500	50	P, T1*, C1*, T2*, C2*	T2, C2 (3.25, 0.045, 8.0)
3	01/29/0920	02/02/2004	106	P, T1, C1, T2, C2	T2, C2 (3.25, 0.045, 8.0)
4	02/03/1306	02/06/2315	80	P, T1, C1, T2*, C2*	T1, C1 (2.00, 0.045, 5.0)
5	02/07/2059	02/12/2033	118	P, T1, C1, T2, C2	T2, C2 (2.00, 0.045, 5.0)
6	02/13/0551	02/15/2045	62	P, T1, C1, T2, C2	T2, C2 (2.00, 0.045, 9.0)

<sup>\*</sup>Use data from ascending profiles only; outlet of T-C duct was into the interior of the Seasoar vehicle.

water. Tow 3 was deployed at about 0915 UTC, 29 January at 2°22'S, 156°02'E near SBS immediately after CTD Station 4. Tow 3 began northwestward toward SBW along the S2W line, and continued along the Standard Butterfly Pattern in the usual direction (Table 4). The Seasoar trajectory (Figure 5) was greatly improved over the previous tow, presumably because of the 1° change in the wing-angle setting. Preliminary T-S diagrams showed that data quality from both sensor pairs was also greatly improved. Preliminary time series of the temperature difference between T1 and T2 showed both drift and offsets larger than expected from SBE specifications (Figure 6). Tow 3 continued for more than 4 days (Table 4). Seasoar was recovered near SBW at about 2010 UTC, 2 February and CTD Station 5 (Table 1) was completed immediately after recovery.

After Tow 3, we replaced both primary and secondary temperature sensors with sensors without a reed-switch assembly (SN 997 and 1384) to reduce the likelihood of damage from vibration, and reterminated the tow cable. Wecoma ran at full speed for a few hours to clear the exhaust system.

Seasoar was deployed near SBW at about 1300 UTC, 3 February immediately after CTD Station 6, and Tow 4 proceeded along the Standard Butterfly pattern in the usual direction (Table 5). Preliminary salinity data from the secondary sensor pair were very noisy during ascending profiles, and we suspected a problem with the sensor duct. Preliminary time series of the difference between the two temperature sensors showed no evidence of drift or offset (Figure 6). The temperature and conductivity data became intermittent during the E2N section of 6 February, so the vehicle was recovered near SBN at about 2315, 6 Feb and CTD Station 7 was made soon afterward. We found that the outlet tube for the secondary sensors had become detached from the nose, so the actual outlet from these sensors was inside the vehicle.

After Tow 4, we reterminated the Seasoar cable again, using a modified wire grip instead of the standard tapered plastic cow-tail to reduce cable flexing. We also repaired the secondary outlet duct, so that this outlet was once again directly through the nose of the Seasoar vehicle. Seasoar was deployed near SBN at about 2100, 7 February, immediately after CTD Station 8 (Table 1). Tow 5 began southward toward SBS and continued along the Standard Butterfly in the usual direction for almost five days (Table 6), when it was terminated at about 2° on the S2W line to allow the ship to make a high-speed run to clear the exhaust system; CTD Station 9 was made immediately after recovery. The Seasoar vehicle, instrument and termination were apparently in excellent condition. During CTD Station 10, as we were preparing to deploy Seasoar for Tow 6, we found a broken strand in the Seasoar cable adjacent to the loop attached for

crane handling. We therefore cut the cable above this point and reterminated the cable.

Seasoar was deployed for Tow 6 at about 0545 UTC, 13 February at 1°59'S, 155°43'E on the S2W line, immediately after CTD Station 11. Tow 6 began northwestward toward SBW and continued along the Standard Butterfly in the usual direction (Table 7) until 1137 UTC, 15 February, when we turned northward toward the equator. Seasoar was recovered just south of the equator at about 2045 UTC, 15 February, and CTD Station 12 was completed immediately afterward. We then ceased operations in the COARE IFA, and Wecoma proceeded to Pohnpei.

In all, we completed six Seasoar tows during W9211C (Table 8), for a total towing time of 416 hours. The overall Seasoar sampling included 12 occupations each of the N2S and W2E lines (Table 9) and the S2W and E2N lines (Table 10).

Wecoma arrived in Pohnpei at about 2300 UTC, 17 Feb, to disembark some personnel and departed there at about 0600 UTC, 18 Feb for the transit to Guam. En route to Guam, we conducted an 8-hour test of Seasoar flight characteristics with an optical plankton counter attached to the vehicle. Wecoma arrived in Guam at 0400 UTC, 22 Feb.

Underway measurements were made continuously through most of the cruise. These include: Acoustic Doppler Current Profile measurements of water velocity relative to the ship and accompanying GPS position data (contact Eric Firing et al., Univ. of Hawaii); temperature and salinity of water at 5 m depth and 2 m depth (contact Clayton Paulson, Oregon State Univ.); near-surface salinity of water pumped from a buoyant hose (contact Gary Lagerloef, SAIC); microwave radiometer estimates of surface salinity (contact Gary Lagerloef, SAIC); and a broad spectrum of meteorological observations (contact Clayton Paulson, OSU) including sonic inertial dissipation (contact Jim Edson, WHOI).

Members of the scientific party included Marc Willis, Tim Holt (both Wecoma Marine Technicians), Adriana Huyer, Robert L. Smith, Fred Bahr, Pip Courbois, Jane Fleischbein (all from Oregon State University), Eric Firing, Fred Bingham, Tung Le, Dail Rowe, and Joanna Muench, (all from University of Hawaii), Clay Wilson (SAIC) and Jonas Aleksa (University of Massachusetts). Additional persons on the Pohnpei-Guam transit were Mike Hill (Oregon State University), Meng Zhou, and Walter Nordhausen (both from Scripps Institution of Oceanography).

Table 9. Times (UTC) of meridional and zonal sections of the Standard Butterfly pattern. All N2S sections were southward along 156°06'E from SBN (1°14'S) to SBS (2°26'S), and all W2E sections were eastward along 1°50'S from SBW (155°30'E) to SBE (156°42'E). Number in parentheses indicates intake of preferred sensor T/C sensor pair was on port (1) or starboard (0) side of Seasoar)

N2S (SBN to SBS) along 156°06'E	W2E (SBW to SBE) along 1°50'S
0917, 27 Jan to 1827, 27 Jan* (0)	0143, 28 Jan to 1207, 28 Jan* (0)
1930, 28 Jan to 0430, 29 Jan*(0)	1646, 29 Jan to 0225, 30 Jan** (0)
0945, 30 Jan to 1926, 30 Jan (0)	0238 to 1112, 31 Jan (0)
1827, 31 Jan to 0358, 1 Feb (0)	1124 to 2015, 1 Feb (0)
0320, 2 Feb to 1221, 2 Feb (0)	1410 to 2304, 3 Feb (0)
0604, 4 Feb to 1524, 4 Feb (0)	2230, 4 Feb to 0719, 5 Feb (0)
1425, 5 Feb to 0015, 6 Feb (0)	0747 to 1641, 6 Feb (0)
2200, 7 Feb to 0820, 8 Feb (1)	1524, 8 Feb to 0114, 9 Feb (1)
0803 to 1824, 9 Feb1 (1)	0200 to 1128, 10 Feb (1)
1819, 10 Feb to 0452, 11 Feb (1)	1207 to 2135, 11 Feb (1)
0433 to 1456, 12 Feb (1)	0845 to 1856, 13 Feb (1)
0151 to 1139, 14 Feb (1)	1833, 14 Feb to 0456, 15 Feb (1)
to from according modiles only	• •

<sup>\*</sup> Data from ascending profiles only.

Table 10. Times (UTC) of diagonal sections of the Standard Butterfly pattern: S2W between SBS (2°26'S, 156°06'E) and SBW (1°50'S, 155°30'E); and E2N between SBE (1°50'S, 156°42'E) and SBN (1°14'S, 156°06'E). During most E2N sections Seasoar was kept at maximum depth for about 12 km.

S2W (SBS to SBW)	E2N (SBE to SBN)				
1827, 27 Jan to 0142, 28 Jan* (0)	1207, 28 Jan to 1930, 28 Jan* (0)				
1035, 29 Jan to 1646, 29 Jan (0)	0225 to 0945, 30 Jan (0)				
1926, 30 Jan to 0238, 31 Jan (0)	1112 to 1827, 31 Jan (0)				
0358, 1 Feb to 1124, 1 Feb (0)	2015, 1 Feb to 0320, 2 Feb (0)				
1221, 2 Feb to 1925, 2 Feb (0)	2304, 3 Feb to 0604, 4 Feb (0)				
1524 to 2230, 4 Feb (partial) (0)	0719 to 1425, 5 Feb (0)				
0015 to 0747, 6 Feb (0)	1641 to 2315, 6 Feb (partial)** (0)				
0820 to 1524, 8 Feb (1)	0114 to 0803, 9 Feb (1)				
1824, 9 Feb to 0200, 10 Feb (1)	1128 to 1819, 10 Feb (1)				
0452 to 1207, 11 Feb (1)	2135, 11 Feb to 0433, 12 Feb (1)				
1456 to 2036, 12 Feb (partial) (1)	•				
0641 to 0845, 13 Feb (partial) (1)	1856, 13 Feb to 0151, 14 Feb (1)				
1139 to 1833, 14 Feb (1)	0456 to 1137, 15 Feb (1)				

<sup>\*</sup>Data from ascending profiles only.

<sup>\*\*</sup> Includes a 6 second data gap from 20:52:25 through 20:53:30 UTC, 29 January.

<sup>&</sup>lt;sup>1</sup> Section extends past SBS to 2°29'S.

<sup>\*\*</sup> Includes numberous short gaps after 22:06:27 UTC, 6 February.

### CTD Data Acquisition, Calibration and Data Processing

All CTD/rosette casts were made with an SBE 9/11-plus CTD system equipped with dual ducted temperature and conductivity sensors (Table 2). CTD casts were made primarily to monitor the calibration of the Seasoar data, and were therefore made before and after each Seasoar tow, with as little delay as possible. Maximum sampling depth was about 500 m. Raw 24 Hz CTD data were acquired on an IBM compatible PC using the SEASAVE module of SEASOFT version 4.015 (Anon., 1992); temperature and conductivity data were recorded from both pumped sensor ducts. At each station a few salinity samples were collected for in situ calibration of the conductivity sensors; CTD values at the sample depth (calculated from the most recent manufacturer's pre-cruise calibration) were recorded both by pressing the F5 key at the time of rosette firing and manually on the station log sheets. Samples were analyzed on a Guildline Autosal salinometer that was standardized with IAPSO Standard Water P-119 at the beginning and end of each batch of about 36 samples. Sample salinity values were in essential agreement with the calculated CTD salinity values from both sensor pairs (average  $\Delta S1=0.002$ , with standard deviation of 0.004, 36 samples: average  $\Delta$ S2=0.002, with standard deviation of 0.005, 33 samples), and hence no conductivity correction was applied.

CTD data were processed on an IBM-compatible PC using applicable SEASOFT modules. Since there was no significant difference between the data from the two sensor pairs, we fully processed data from the primary sensors only. The DATCNV module of SEASOFT was used with the pre-cruise calibration constants to calculate 24 Hz values of pressure, temperature and conductivity from the raw frequencies. When necessary, the output data file was edited to remove any spikes and any values inadvertently recorded before the pressure minimum at the beginning of the cast. The CELLTM module was used to correct for the thermal mass of the conductivity cell, assumed to have a thermal anomaly amplitude of 0.03 and a time constant of 9 seconds. Ascending portions of the 24-Hz data file were removed by LOOPEDIT with the minimum velocity set to 0.0 m/s. The remaining data were averaged to 1 dbar values using BINAVG. The final processed data files consist of 1 dbar values of pressure, temperature and conductivity. These processed data files were transferred to a SUN computer where we used standard algorithms (Fofonoff and Millard, 1983) to calculate salinity, potential temperature, density anomaly (sigma-theta), specific volume anomaly, and geopotential anomaly (dynamic height).

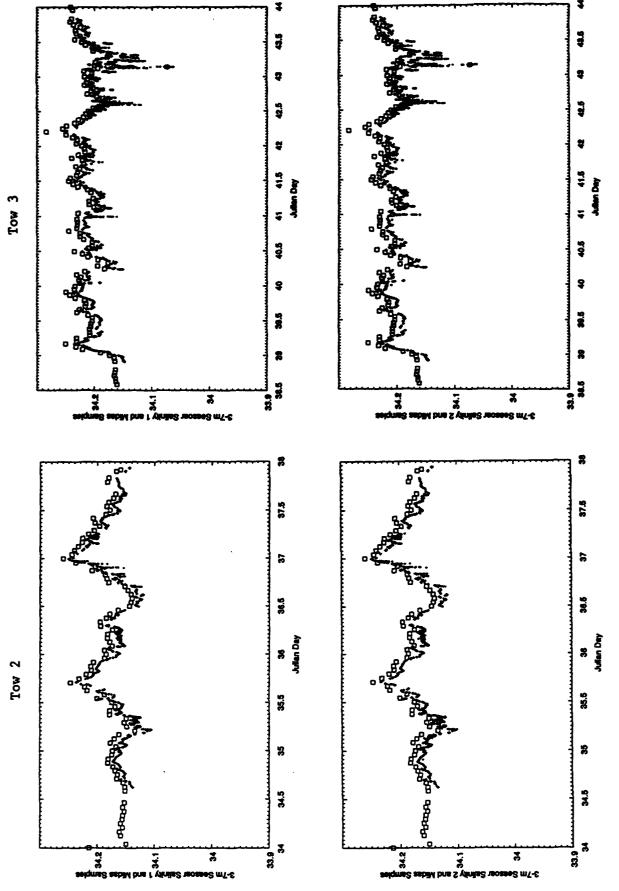


Figure 7(a). Time series of hourly salinity samples from the ship's intake at 5 m (squares), and of preliminary near-surface (3-7.99 m) Seasoar salinity data (dots) from both primary (upper panel) and secondary sensors (lower panel), for each Seasoar tow of W9211C: Tow 2 (left) and Tow 3 (right) of W9211C.

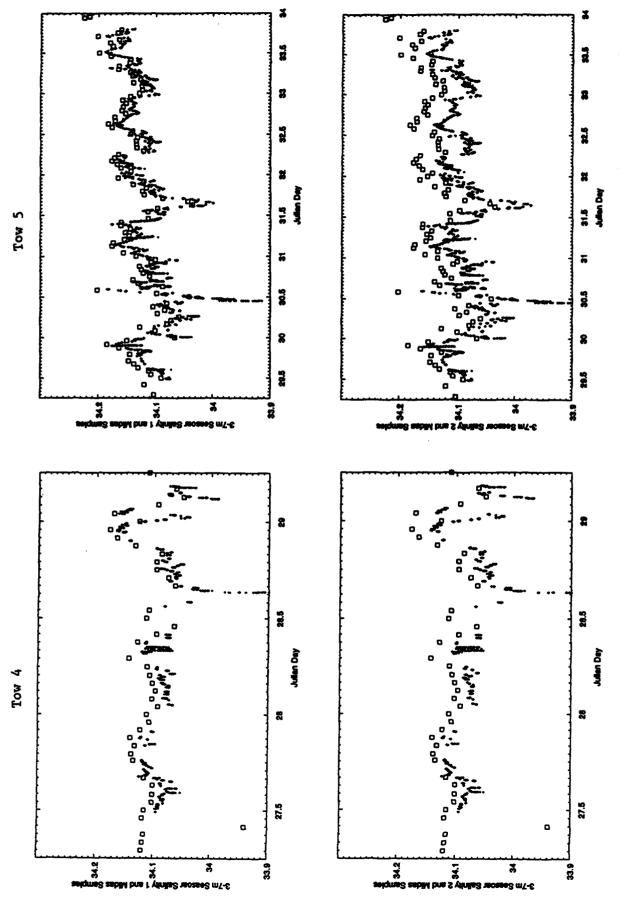
## Seasoar Data Acquisition and Preliminary Processing

Raw 24 Hz CTD data from the Seasoar vehicle and GPS position and time data were acquired by an IBM compatible PC, which also set flags to indicate missing GPS data and to mark the collection of a salinity sample. The raw data were simultaneously recorded on optical disk by PC and on a Sun Sparc workstation. The PC displayed time series of subsampled temperature (both sensors), conductivity (both sensors) and pressure in real time; it also displayed accumulated temperature data for 6-8 hours as a vertical section (color raster). One-second averages of ship's position, CTD temperature (both sensors), conductivity (both sensors), salinity (both sensor pairs), and pressure were calculated on the Sparc workstation, using the most recent manufacturer's calibration (Table 2). For each tow, the preliminary salinity for each sensor pair was calculated using a fixed offset between temperature and salinity, and a fixed value for the amplitude and time constant of the thermal mass of the conductivity cell, but these parameters were changed from one tow to another (Table 8). Time-series and vertical profile plots of the one-second data were made at the end of each hour. The 1-second preliminary data were used to calculate the average temperature and salinity data in bins extending 3 km in the horizontal and 2 dbar in the vertical, and these gridded values were used to plot vertical sections for each leg of the Standard Butterfly pattern.

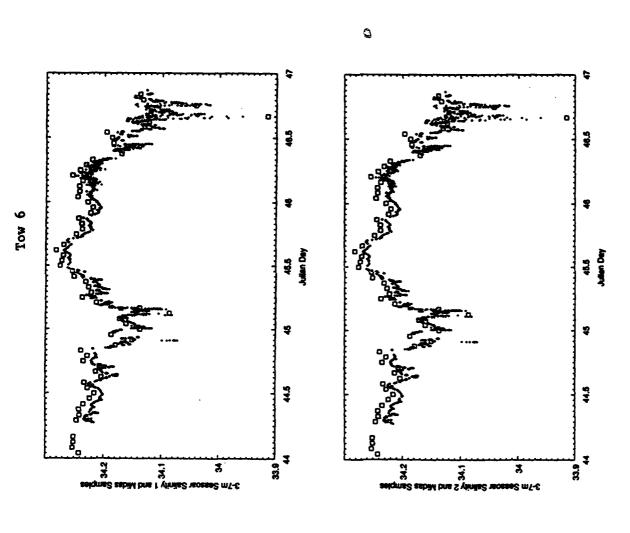
### Seasoar Conductivity Calibration

Salinity samples were collected once per hour from a throughflow system in Wecoma's wetlab from 0000 UTC, 27 January until 2000 UTC, 15 February 1993. This system pumps water from the seachest at a depth of 5 m in the ship's hull, through a tank containing SBE temperature and conductivity sensors; samples are drawn from a point just beyond this tank. The 120 ml glass sample bottles were rinsed three times before filling, and closed with screw-on plastic caps with conical polyethylene liners. Samples were further sealed by wrapping parafilm around the base of the cap. Samples were analyzed at sea on an Autosal salinometer, usually within 2-3 days after collection; the salinometer was standardized with IAPSO Standard Water P-119 at the beginning and end of each batch of about 24 samples. Time series of these hourly salinity samples and time series of the preliminary Seasoar data from the 3-7 m depth range (Figure 7) show very similar variations, especially during Tows 4-6.

For a quantitative comparison between the salinity samples and the Seasoar data, we selected Seasoar values that were both within 7 minutes of the time of the salinity sample and within a depth range of 3.0 to 5.5 m. For each salinity sample, we calculated a bottle conductivity using the measured salinity and the temperature from each Seasoar sensor duct, and then compared this sample conductivity to the directly



preliminary near-surface (3-7.99 m) Seasoar salinity data (dots) from both primary (upper panel) and secondary sensors (lower panel), during Tow 4 (left) and Tow 5 (right) of W9211C. Figure 7(b). Time series of hourly salinity samples from the ship's intake at 5 m (squares), and of



preliminary near-surface (3-7.99 m) Seasoar salinity data (dots) from both primary (upper panel) and secondary sensors (lower panel), during Tow 6 of W9211C. Figure 7(c): Time series of hourly salinity samples from the ship's intake at 5 m (squares), and of

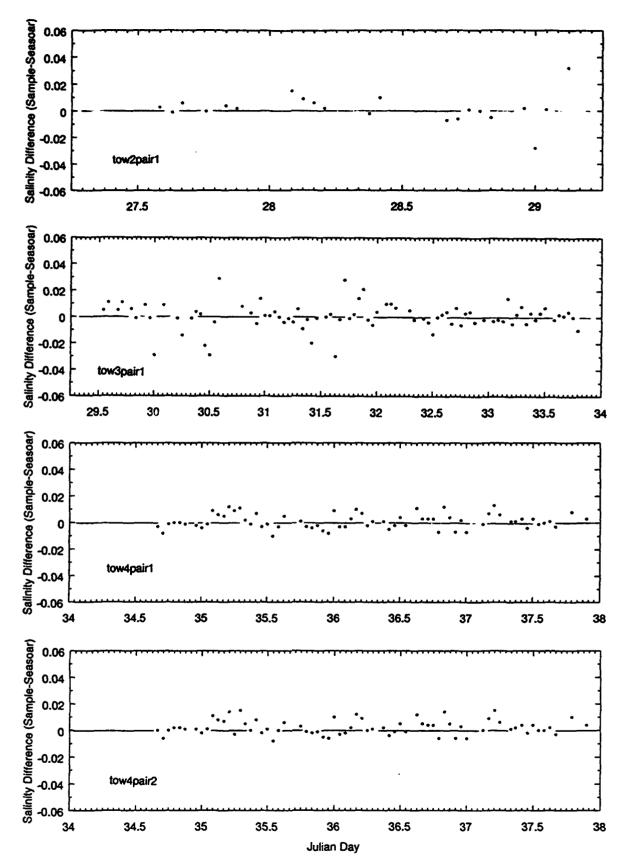


Figure 8 (a). Time series of salinity differences between the 5-m samples and the matching corrected Seasoar data, for the primary T/C sensor pair during Tows 2 and 3, and for both primary and secondary sensors during Tow 4 of W9211C.

measured conductivity from the same sensor duct; a very few pairs with very large differences (only 5 out of a total of 329) were eliminated from the comparison. Assuming, as usual, that the measured conductivity should be corrected by a multiplier alone, we calculated the slope (m) of the zero-intercept regression line between the measured conductivity and the sample conductivity separately for each sensor pair and for each Seasoar tow.

Between Tows 2 and 3, we found no significant difference in the multiplier for the primary sensor pair, and therefore we pooled the data, and used the same correction factor (k) for both tows (Table 11). Since the secondary temperature sensor malfunctioned during Tows 2 and 3, we used the primary temperature data to determine the multiplier for secondary conductivity for these tows. Both primary and secondary sensors were replaced after Tow 3.

Between Tows 4, 5 and 6, we found no significant difference in the multiplier (m) for either the primary or secondary conductivity data, and therefore we adopted the values determined from the pooled data as the correction factors (Table 11).

Applying these multipliers to the Seasoar conductivity data before recalculating salinity allows us to compare the corrected Seasoar salinity values from both primary and secondary sensor ducts to the sample salinity (Figure 8, Table 11). The time series of the differences (Figure 8) show reasonable agreement between sample and near-surface Seasoar data for the primary sensor pairs during Tows 2 and 3, and for both sensor pairs during Tows 4, 5 and 6. In general, largest sample-Seasoar differences occur when the surface layer is stratified, so the standard deviations of the salinity differences (Table 11) primarily reflect sampling errors rather than instrumental noise.

Table 11. Conductivity multipliers (m1 and m2) for primary and secondary sensors, determined (separately for each tow) from comparison of near-surface Seasoar data with 5-m intake samples, and the conductivity correction factors (k1 and k2) adopted for reprocessing the Seasoar conductivity data. Also shown are the average and standard deviations of the salinity differences between the sample values and the corrected Seasoar data.

						Average		Std. Dev.	
Tow	N	m1	m2	k1	k2	S1	S2	S1	S2
1	0		-	1.000433	1.000449	-	-	_	
2	21	1.000470	-	1.000433	1.000449	0.001	_	0.007	_
3	84	1.000424	_	1.000433	1.000449	0.000	_	0.009	_
4	67	1.000388	1.000460	1.000368	1.000418	0.001	0.002	0.004	0.004
5	100	1.000354	1.000396	1.000368	1.000418	-0.001	-0.001	0.007	0.008
6	52	1.000396	1.000420	1.000368	1.000418	0.002	0.000	0.012	0.012

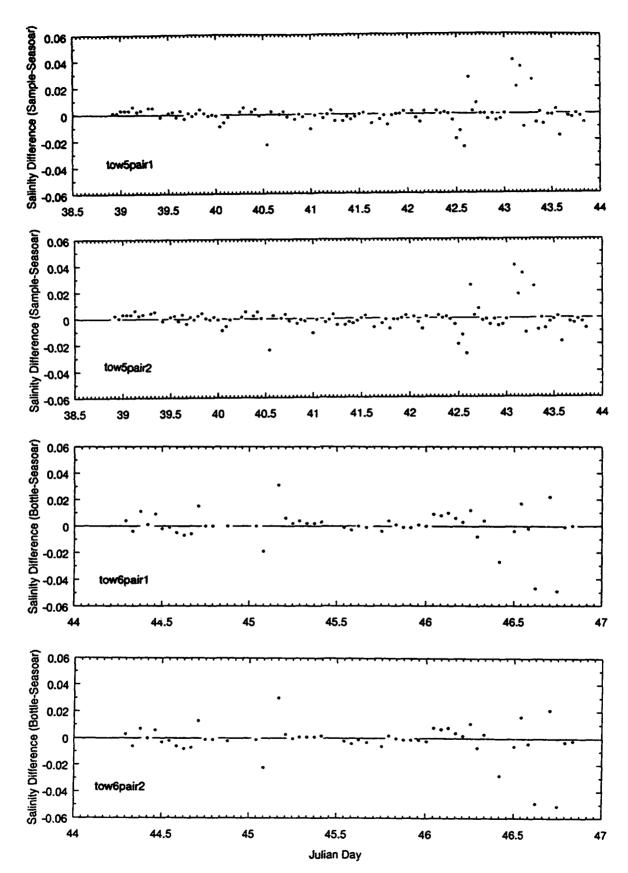


Figure 8 (b). Time series of salinity differences between the 5-m samples and the matching corrected Seasoar data, for both primary and secondary sensor pairs during Tows 5 and 6 of W9211C.

### Post-processing of Seasoar Data

Background Salinity data derived from SeaBird ducted temperature and conductivity sensors are subject to errors from three separate sources (Larson, 1992): (1) poor alignment of the 24 Hz temperature and conductivity data, (2) poor compensation for the transfer of heat between the mantle of the conductivity cell and the water flowing through it, and (3) mismatch of the effective time constants of the temperature and conductivity measurements. These sources of error are minimized in a normal SeaBird CTD, by pumping the water through the ducted pair at a fixed rate, by software algorithms for changing the T/C alignment and the thermal mass parameters, and by matching the thermistor to the effective time constant of the conductivity measurement through the fixed-length duct. With sensors mounted inside a towed Seasoar vehicle, these error sources need to considered anew.

While at sea, we noticed that there was often a significant difference in data quality between ascending and descending profiles, with salinity data from descending profiles generally noisier than salinity data from ascending profiles; descending profiles frequently showed a large and variable positive salinity bias (e.g. Figure 9). These systematic up/down differences were observed in data from both sensor pairs, though sometimes more pronounced in one of the sensor pairs. We therefore suspected that there might be variations in the flow-rate of water through the pumped T/C sensor ducts, leading to variations in the optimum alignment offset between the 24-Hz temperature and conductivity data.

To check this hypothesis, we applied the general procedures outlined by Nordeen Larson (1992) to a segment of raw data from the hour beginning at 0000 UTC, 9 February. We first reprocessed the data from both sensor pairs without applying any T/C offset, retaining 24-Hz output; data from the first ascending profile (about 0001 to 0006 UTC) and the first descending profile (0006 to 0010 UTC) were read into separate files. These served as input to a program which realigns the temperature and conductivity data from both sensor pairs by a specified offset and recalculates salinity; for each scan it also determines a "median salinity",  $S_{\rm m}$ , using a centered nine-point median filter, and a "spike salinity", S', as the anomaly from the median salinity. The time integral of this spike salinity, normalized by the sign of the temperature gradient,

$$ISS = \sum (S'_n/sgn(T_{n+1}-T_{n-1})),$$

changes sign at the optimum offset value (Larson, 1992). Calculations were repeated for a range of offsets, and spike salinity profiles were plotted for each (e.g., Figure 10). For these profiles, we found that the optimum alignment offset,  $\xi$ , during

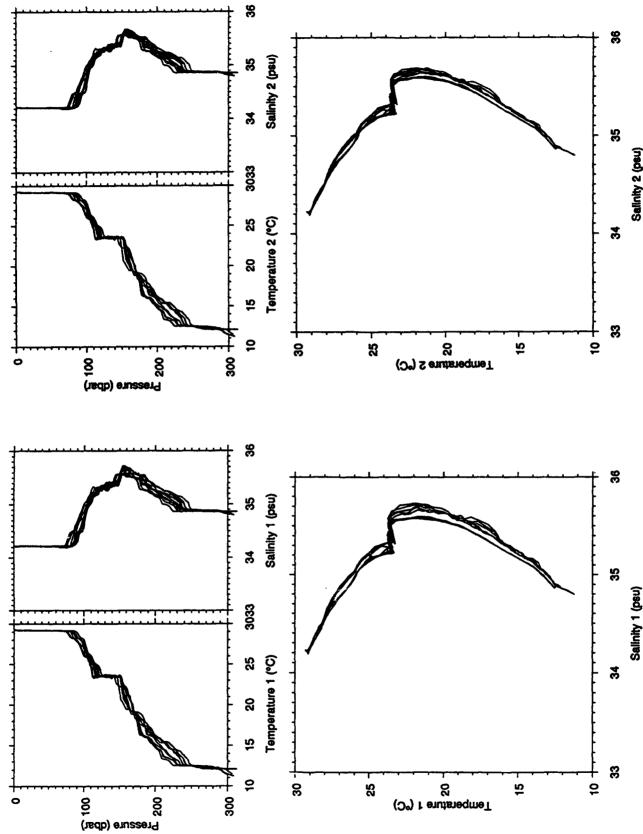


Figure 9. Preliminary profiles and T-S diagrams for both Seasoar T/C sensor pairs, for the hour beginning 0000 UTC on 9 February 1993. Data were processed with constant values of the T/C offset ( $\xi_1 = 0.0$  and  $\xi_2 = 2.0$ ) and thermal mass parameters ( $\alpha = 0.045$  and  $\tau = 5$  sec). For both sensor pairs, splitting of the T-S characteristics into two groups reflects systematic differences between ascending and descending profiles.

ascent was essentially the same as those for ducted sensors in a normal profiling SBE9/11 plus CTD, i.e. 0.0 scans for primary sensors and 1.75 scans for secondary sensors. (The SBE 11/plus deck unit previously applies a T/C alignment offset of 1.75 scans to data from primary sensors but not secondary sensors). Optimum values of the offset during descent were larger: 1.75 scans for primary sensors, and 2.75 scans for secondary sensors (Figures 10, 11).

We independently calculated lagged correlation coefficients between the temperature and conductivity data from each sensor pair, using first differencing to remove low frequency trends in both, and obtained the same results, and found that the lag of maximum correlation was in essential agreement with the alignment offset determined by Larson's spike salinity method. Alternating between two values of the alignment offset (one for descent, one for ascent) significantly improved the processed salinity data, but systematic up/down differences remained during portions of some Seasoar tows (e.g. Figure 12).

Further study of the 24-Hz Seasoar CTD data has shown that the optimum T/C alignment offset, \( \xi\$, varies on several different time scales: within each undulation, from section to section, gradually over the length of a tow, and from one tow to another (e.g., Figure 13). In most cases, the optimum alignment offset during ascent is near the default values of 0.0 scans for T1/C1 and 1.75 scans for T2/C2, while the optimum offset during descent is longer. We attribute these variations in optimum offset to reductions in the rate of pumped flow through the sensors, and believe these variations in flow rate are the result of dynamic pressure differences, partly between the inside and outside of the vehicle, and partly along the exterior of the vehicle nose (though inlet and outlet ports are separated by only a few centimeters). Possible sources of such pressure gradients include high rates of ascent and descent (sometimes >3 m/s, superimposed on a horizontal tow speed of 4 m/s), and local small perturbations of the flow field around the vehicle, associated perhaps with a persistent roll angle or strong cross-currents. Whatever their source, the variations in offset alignment are a major source of potential error in calculating salinity, and must be taken into account in reprocessing the data. After some trial and error, we chose to determine the optimum lag in three depth ranges (excluding the surface mixed layer) for each ascending and descending profile; calculating lags for successive 10-second segments proved to be less satisfactory in minimizing salinity noise and bias.

Still further study of the preliminary Seasoar data showed that systematic up/down salinity differences were particularly strong near sharp thermoclines, even though we had attempted to correct for the thermal mass of the conductivity cell (Lueck, 1990), using constant values for the time constant ( $\tau$ ) and amplitude ( $\alpha$ ) parameters in the recursive algorithm provided by SeaBird:

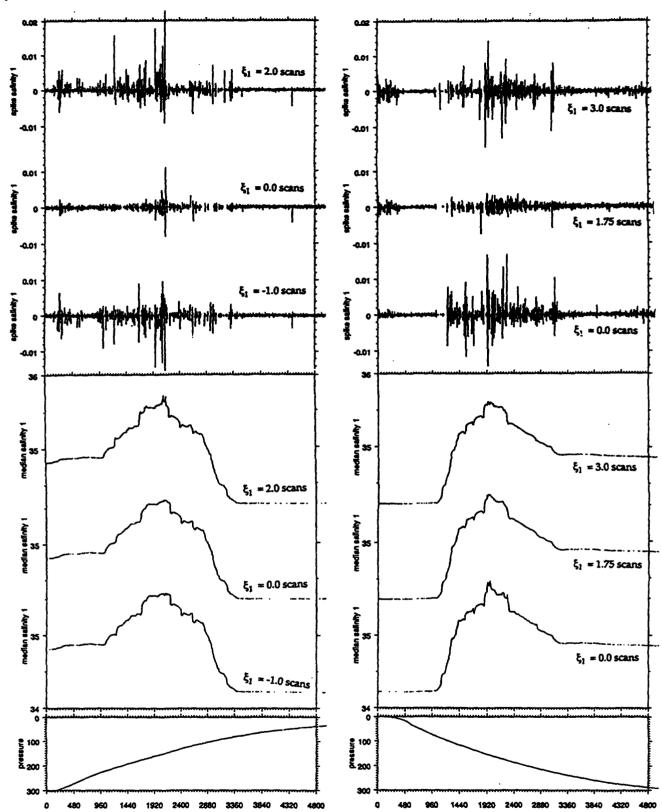


Figure 10. Time-series of 24-Hz "median salinity" and "spike salinity" from ascending (left) and descending (right) segments of Seasoar data between 0001 and 0010 UTC, 9 February, calculated for three different values of T/C alignment offsets  $\xi_1$ . The "median salinity" is the median of 9 scans, and the "spike salinity" is the anomaly from this median.

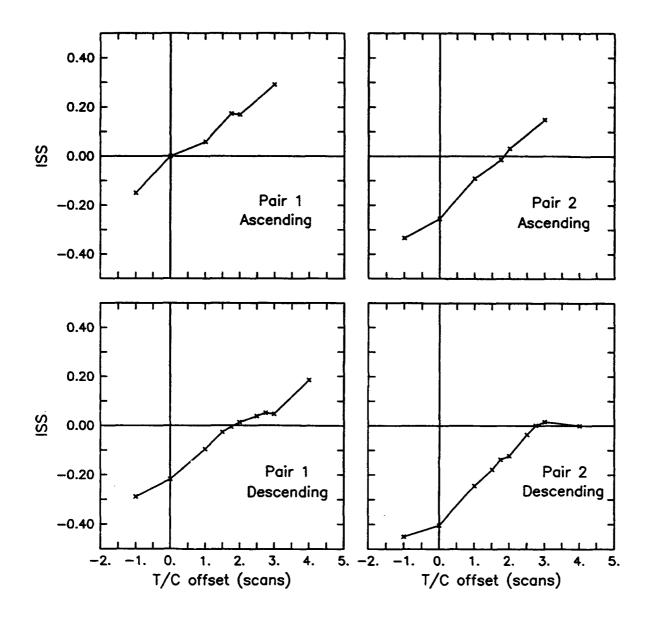


Figure 11. Values of the integral of spike salinity, ISS, for ascending and descending segments of data from both T/C sensor pairs, during 0001 and 0010 UTC, 9 February 1993; note that the value of the optimum offset (at ISS = 0) is larger during descent.

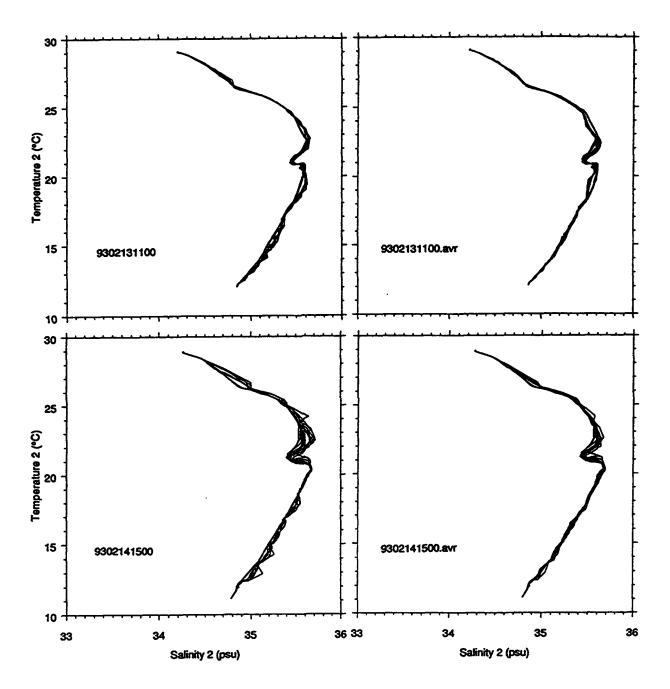


Figure 12. T-S characteristics for Seasoar data from two different hours, processed by two different methods: with constant values of the T/C alignment offset (left,  $\xi_2 = 2.0$  scans), and with alternating values of the offset (right;  $\xi_2 = 2.5$  scans during ascent and  $\xi_2 = 5.0$  scans during descent). In both methods, we used constant values of the thermal mass parameters ( $\alpha = 0.045$  and  $\tau = 9$  sec).

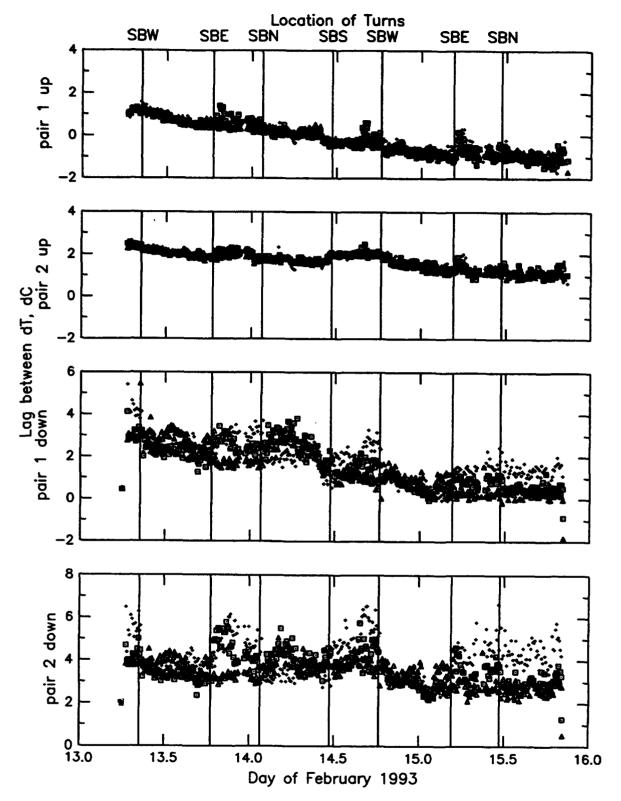


Figure 13. Time series of the lag at maximum cross-correlation between 24-Hz temperature and conductivity data (detrended by first-differencing), for both primary and secondary sensor pairs during Seasoar Tow 6. Correlations were calculated for three different layers (50-120 dbar, plus signs; 120-180 dbar, squares; 180-240 dbar, triangles), and separately for ascending and descending profiles; times of turns in the ship's track are indicated by vertical lines.

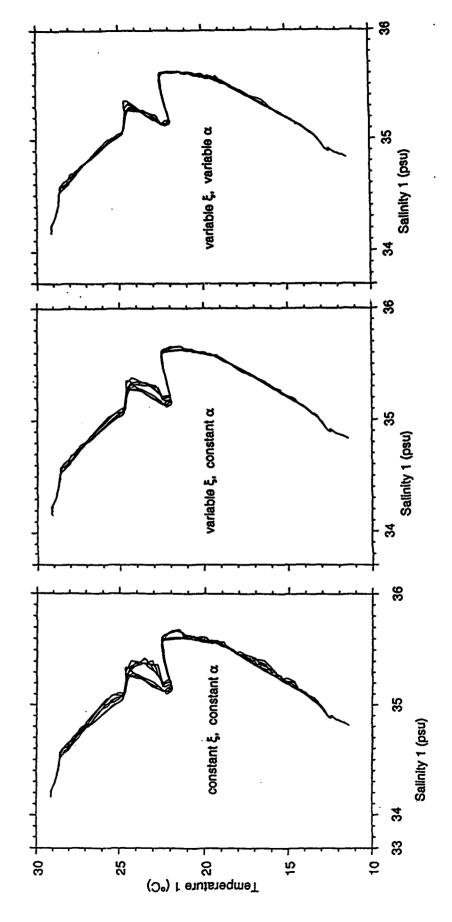
dt = temperature - previous temperature ctm = -b\* previous ctm + a\* dcdt\* dtcorrected conductivity = conductivity + ctm

where a=2  $\alpha$  / (0.0417  $\beta$  + 2), dcdt=0.1+0.0006 (temperature - 20),  $\beta=1/\tau$  and b=1-2  $a/\alpha$ . Constant values of  $\alpha$  and  $\tau$  had been chosen by two different methods: by comparing CTD casts with Seasoar deployment and recovery profiles, and by minimizing differences between ascending and descending salinity data near the top of the thermocline for some data segments with exceptionally steep gradients at the bottom of the surface mixed layer; both methods indicated the best constant values were  $\alpha=0.04$  for the thermal anomaly amplitude and  $\tau=10$  sec for the time constant. The association of residual salinity bias with sharp thermoclines suggested that variations in flow rate through the ducted sensors effectively altered the rate of heat transferred from the walls of the conductivity cell. Experimenting with different values of  $\alpha$  indicated that larger values of  $\alpha$  are appropriate for larger values of the alignment offset (Figure 14).

Finally, we considered the effect of elongating the intake duct (from about 1 cm on a standard SeaBird T/C ducted pair to about 5 cm) by adding Tygon tubing between the sensor duct and inlet in the Seasoar nose. In principle, elongating the intake could slow the response time of the conductivity measurement through turbulent mixing within the duct (Nordeen Larson, personal communication). We compared conductivity spectra from conventional CTD casts with those from the Seasoar deployment and recovery profiles, and found no significant difference: both were similar to the temperature spectra. We conclude that any change in sensor time constant due to intake elongation is negligible, at least with the present choice of tubing.

<u>Procedures</u> The first step in reprocessing is to incorporate temperature and conductivity corrections determined from in-situ calibration or post-cruise calibration in a new configuration file for each tow. Except for temperature sensor #1369, which clearly malfunctioned during the cruise, the post-cruise temperature calibrations of the Seasoar sensors showed little or no drift from the pre-cruise calibrations, so no temperature corrections were applied. The conductivity correction factors determined from the *in situ* calibration data (Table 11) were incorporated in the configuration files for each tow.

The next step is to compute lagged correlations between temperature and conductivity for each sensor pair, separately for ascending and descending profiles, and separately for three depth ranges: 50 to 120 dbar, 120 to 180 dbar, and 180 to 240 dbar, provided the segment contains at least 72 scans. Cross-correlations are calculated after detrending both temperature and conductivity by first-differencing



center, using variable  $\xi$  determined from T-C cross-correlation and constant  $\alpha$ ; right, using both variable  $\xi$  and a variable different methods: left, using a constant T/C offset ( $\xi_1 = 0.0$ ), and a constant thermal anomaly amplitude ( $\alpha = 0.045$ ); Figure 14. T-S characteristics for Seasoar data from the same hour (2000-2100 UTC, 13 Feb 1993), processed by three  $\alpha$  which increases with  $\xi$ .

the 24-Hz data. Correlations are calculated for  $\pm 12$  lags; the maximum correlation is almost always  $\geq 0.85$ . The fractional value of the lag at maximum correlation is determined by fitting a parabola to the cross-correlation values. The resulting time series of the optimum primary and secondary alignment offsets ( $\xi_1$  and  $\xi_2$ ) for each tow are shown in Appendix A. Lag values greater than 12 and other outliers (obtained occasionally for data segments lasting <10 seconds) were not used in processing the data. Very large lags were obtained for many descending profiles of Tow 2) when the pump outlets were not properly connected, and hence data from descending profiles from this tow were discarded.

The edited values of the alignment offset were applied sequentially in reprocessing the 24-Hz T/C data. To reprocess data from depths shallower than 50 m, we used the  $\xi$  value determined from the preceding 120 to 50 dbar layer; for data deeper than 240 m, we used the  $\xi$  value determined from the preceding 180 to 240 dbar layer. Short segments with unreasonably large lags were processed with the lag obtained for the succeeding data segment.

To correct the 24 Hz conductivity data for the thermal mass of the conductivity cell, we used the standard algorithm with a fixed value for the thermal anomaly time constant ( $\tau = 10$  sec), and variable values for the thermal anomaly amplitude depending on the alignment offset:

$$\begin{array}{ll} \alpha_1 = 0.03 & \text{if } \xi_1 \leq 0 \\ \alpha_1 = 0.03 + 0.03(\xi_1/2.75) & \text{if } \xi_1 > 0 \\ \alpha_2 = 0.03 & \text{if } \xi_2 \leq 1.75 \\ \alpha_2 = 0.03 + 0.03(\xi_2\text{-}1.75)/2.75)) & \text{if } \xi_2 > 0, \end{array}$$

where the subscripts denote primary or secondary sensors. The corrected and realigned 24 Hz temperature and conductivity data are used to calculate 24-Hz salinity, and these are averaged to yield 1-second averages stored in hourly files. These procedures greatly reduce the systematic salinity differences (both bias and noise) between ascending and descending profiles (e.g. Figure 14). However, salinity data from descending profiles remains somewhat noisy, while the ascending data is almost always free of significant noise.

The reprocessed data from both sensor pairs were plotted to determine which pair provided the better data for each Seasoar tow. During Tow 2, with both sensor ducts disconnected from the outlet, there is evidence of stalling in the pumped sensor ducts during descent, but data from ascending profiles is apparently of good quality. For both Tows 2 and 3, with the malfunctioning secondary temperature sensor, data from the primary sensors is clearly preferable. During Tow 4, the

secondary sensor duct was disconnected from the outlet, and data from the primary sensors is clearly preferable. For Tows 5 and 6, the data from the two sensor pairs was of essentially the same quality, with only very subtle reasons to prefer the secondary sensors over the primary sensors.

#### **Data Presentation**

Successive hourly files of the reprocessed one-second average data were joined and clipped to yield a single data file for each section of the Standard Butterfly Pattern (Tables 9 and 10). Final processed data files contain unfiltered GPS latitude and longitude; pressure; temperature, salinity and sigma-t from the better sensor pair; date and time; and an integer representing flags (to indicate collection of a water sample from 5-m intake (thousands digit set to 1), missing GPS data filled by linear interpolation (tens digit set to 1), and to indicate port or starboard intake for the T/C sensor pair (ones digit set to 1 or 0, respectively)). We present consecutive figures of the Seasoar trajectory (time series of pressure, latitude and longitude) along each section. We also present summary figures of all of the 1second data for each of the four standard sections as follows: ensembles of temperature profiles (both ascending and descending, except for Tow 2), salinity profiles (ascending profiles only), and T-S diagrams (for ascending profiles only). Vertical distributions of the temperature, salinity and sigma-t along each section were plotted using Don Denbo's PPlus program with a vertical grid spacing of 2 dbar and a horizontal spacing of 1 nm, and with a value of CAY= 5 for the smoothing parameter (combined spline and laplacian filter). For the temperature sections, we used both ascending and descending data, for all tows except Tow 2 where we used ascending data only. For the salinity and sigma-t sections, we used only ascending data for all tows.

## CTD/Seasoar Comparison

T-S diagrams for the beginning and end of each Seasoar Tow are shown in Appendix B. Each diagram shows the T-S curve from both the conventional CTD cast and the preferred Seasoar sensors during Seasoar deployment or recovery. Seasoar deployment profiles are generally noisier than either the CTD profiles or Seasoar recovery profiles, probably because the Seasoar vehicle is tilted nose-upward during both deployment and recovery; since the ship is moving very slowly, observations during deployment are sometimes within the turbulent wake of the descending vehicle.

#### Acknowledgments

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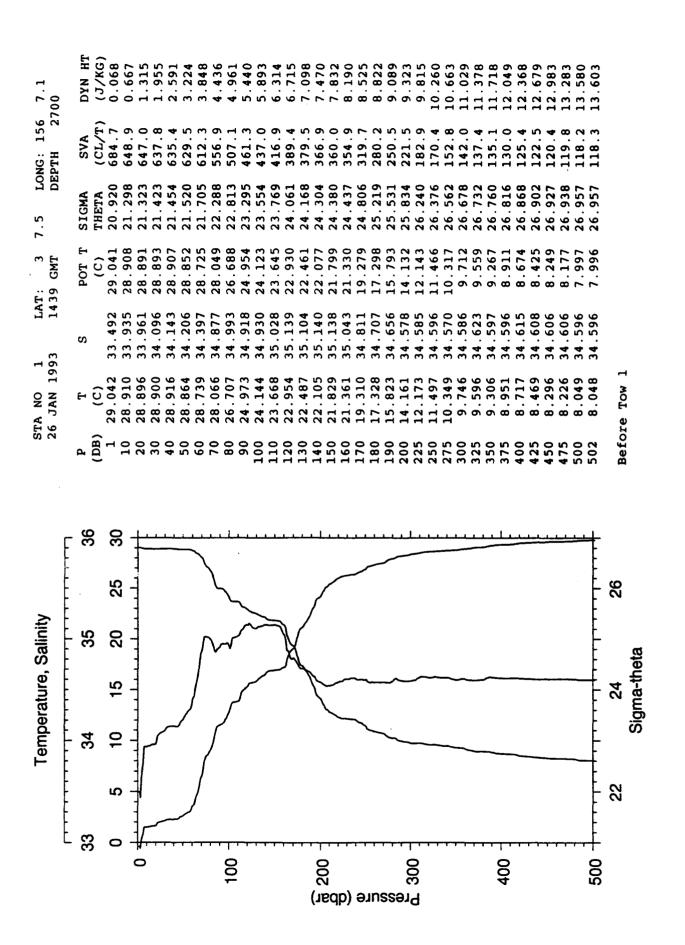
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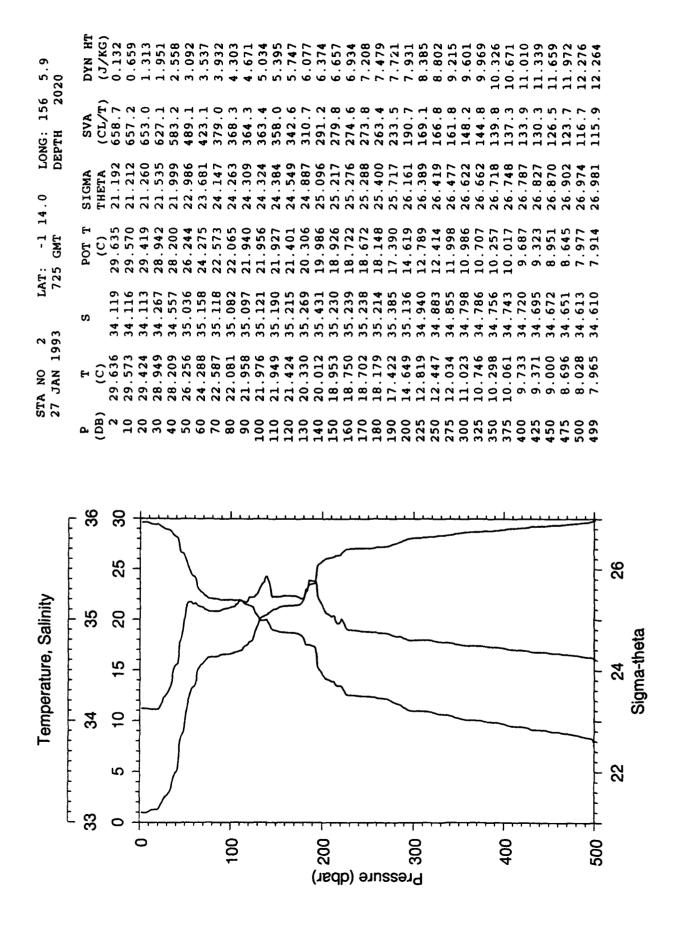
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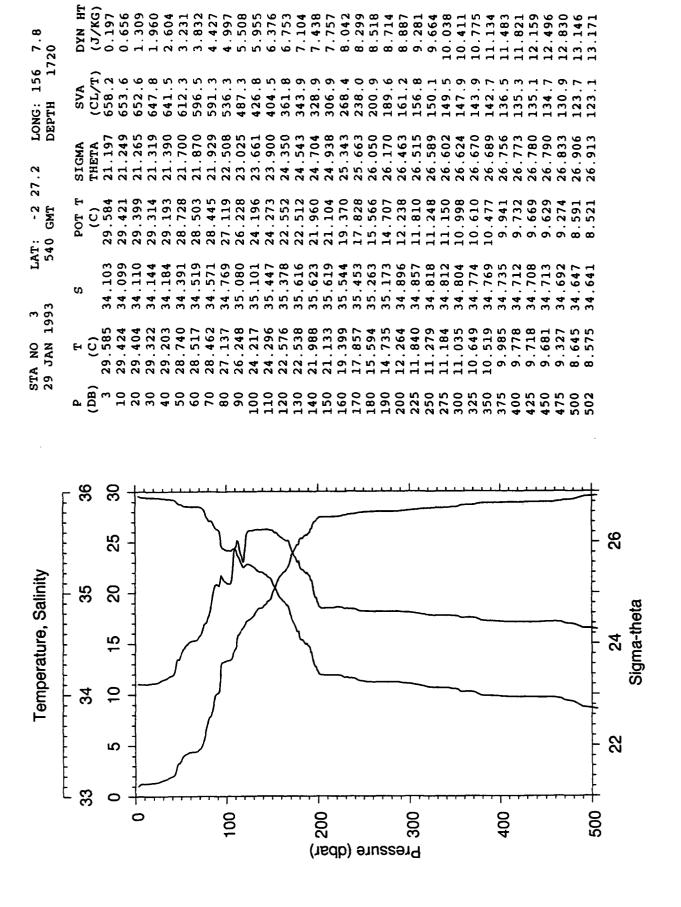
CTD DATA

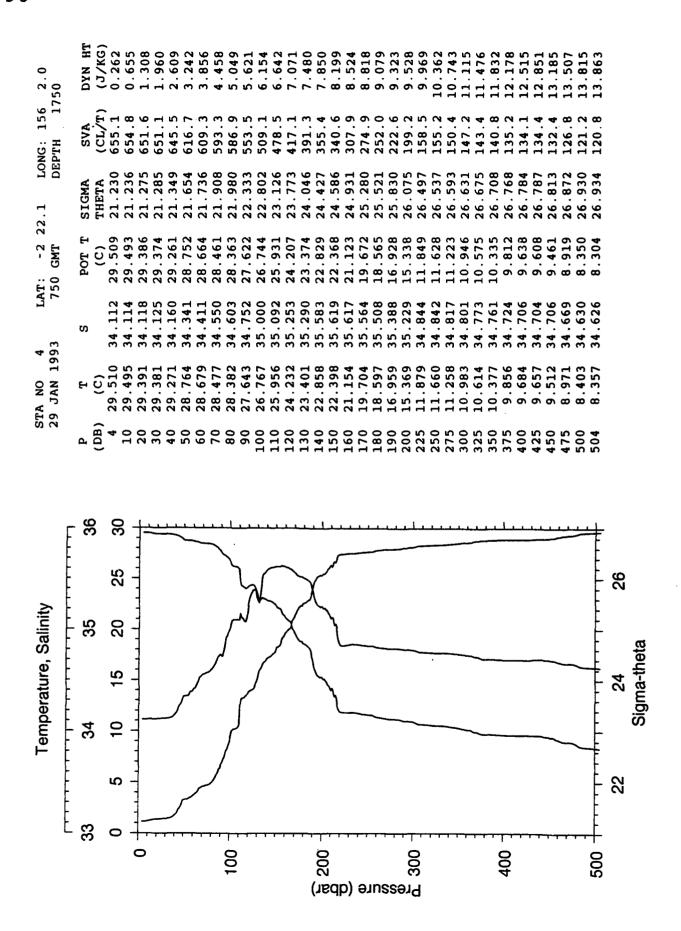
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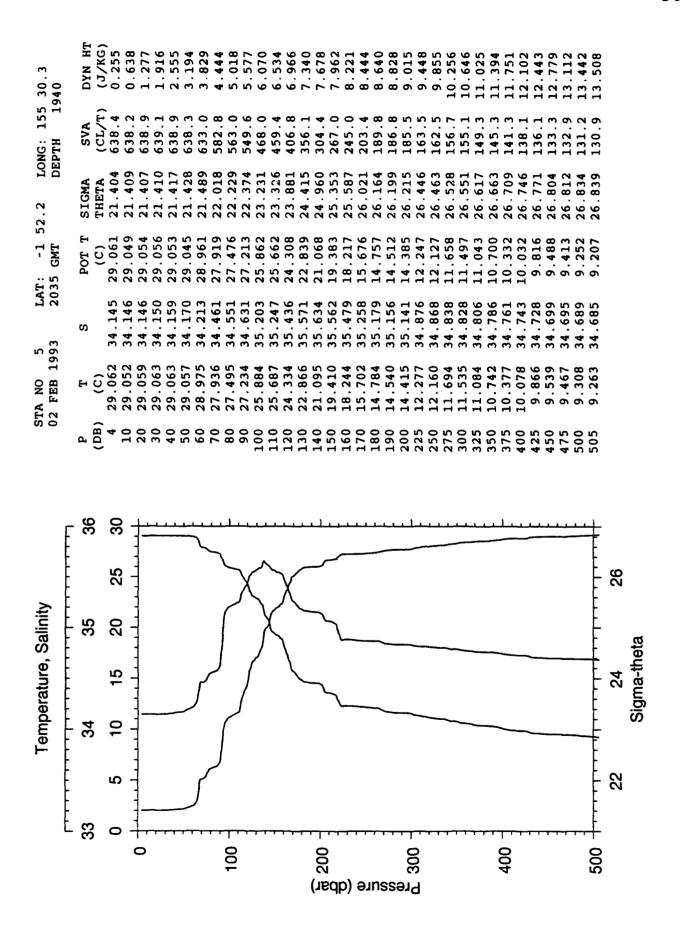
For each station, we present a plot of the vertical temperature, salinity, and sigma-t profiles, and a listing of the observed and derived variables at standard pressures. Header data includes the CTD Station Number, Latitude (in degrees and minutes; a negative degree integer indicates southern hemisphere), Longitude (degrees and minutes East), Date and Time (UTC), and Bottom Depth (in meters).

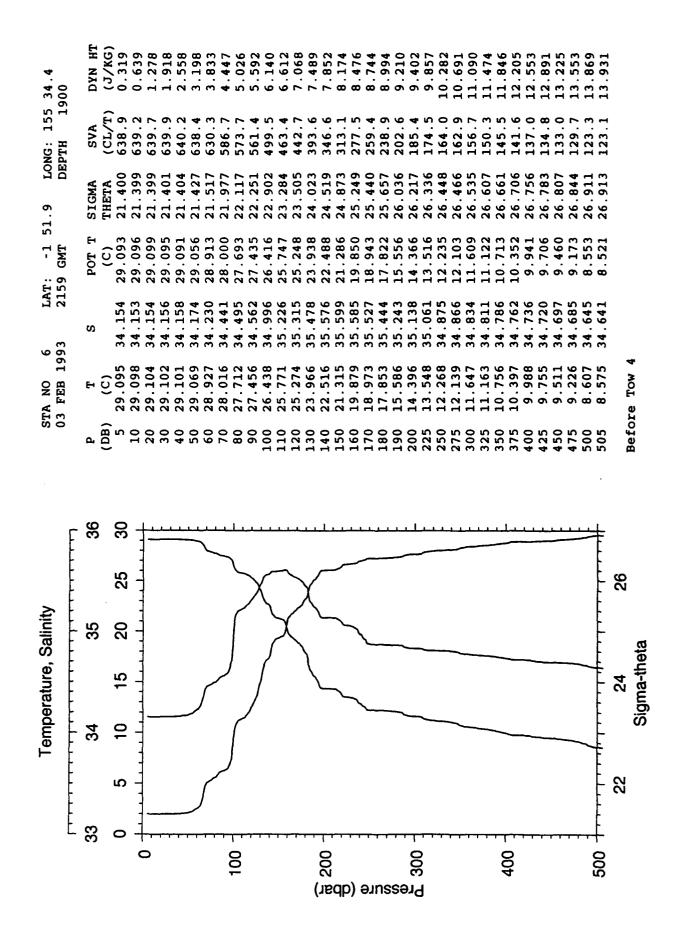


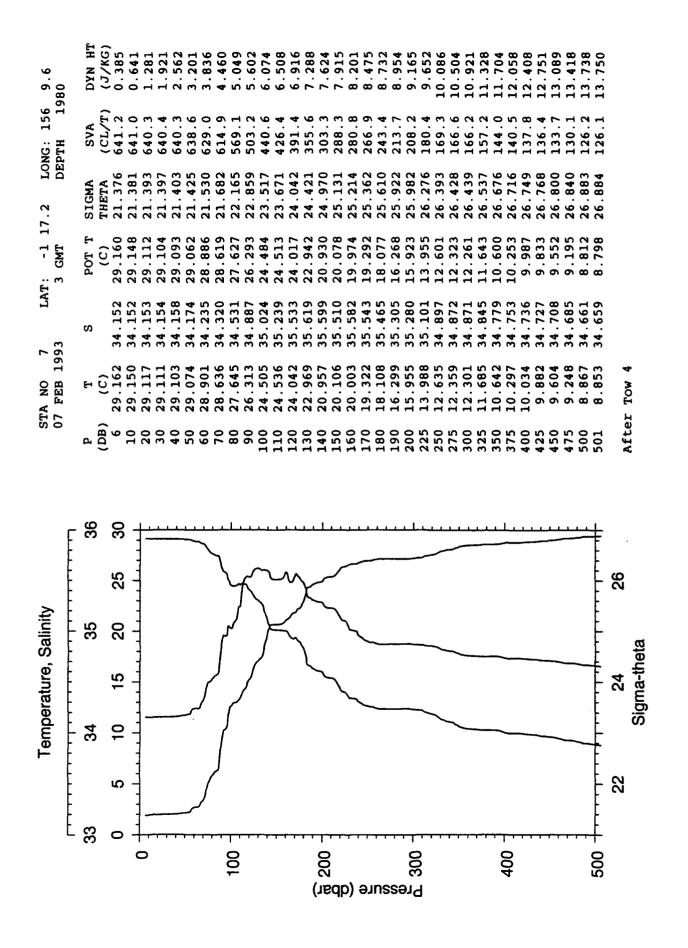


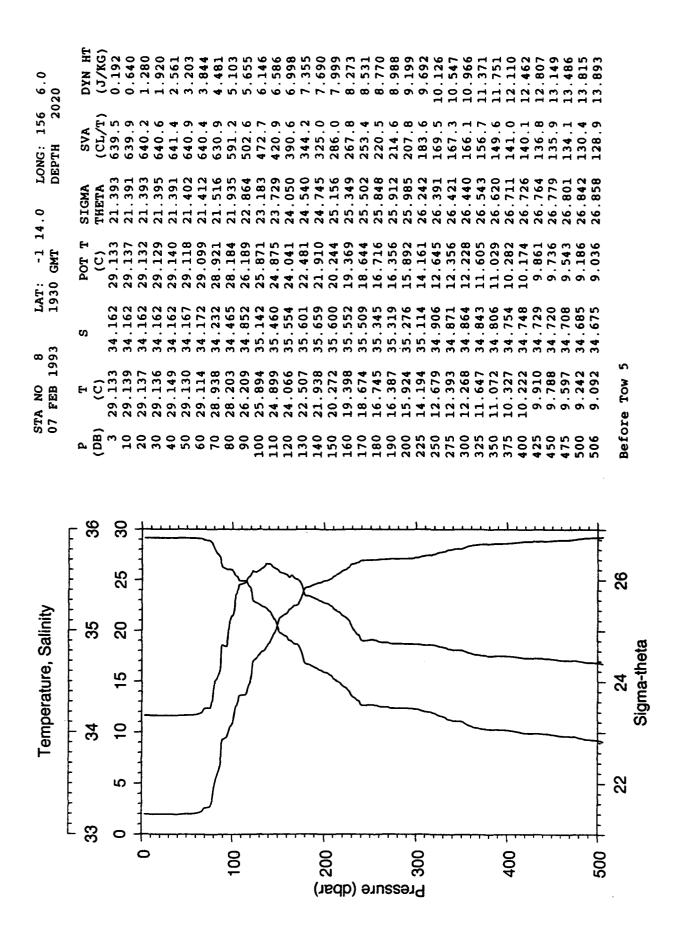


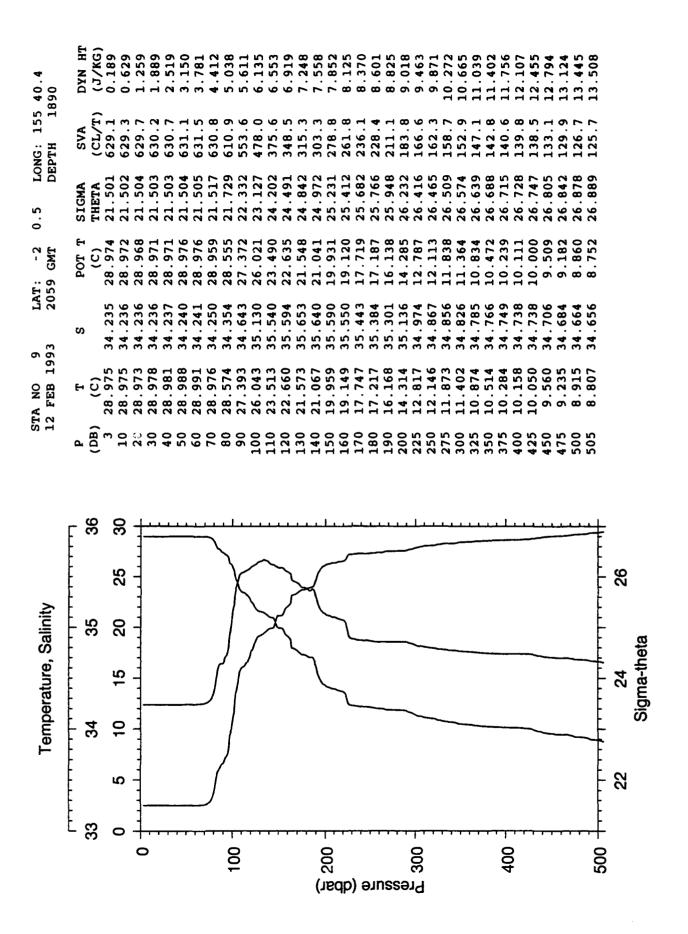


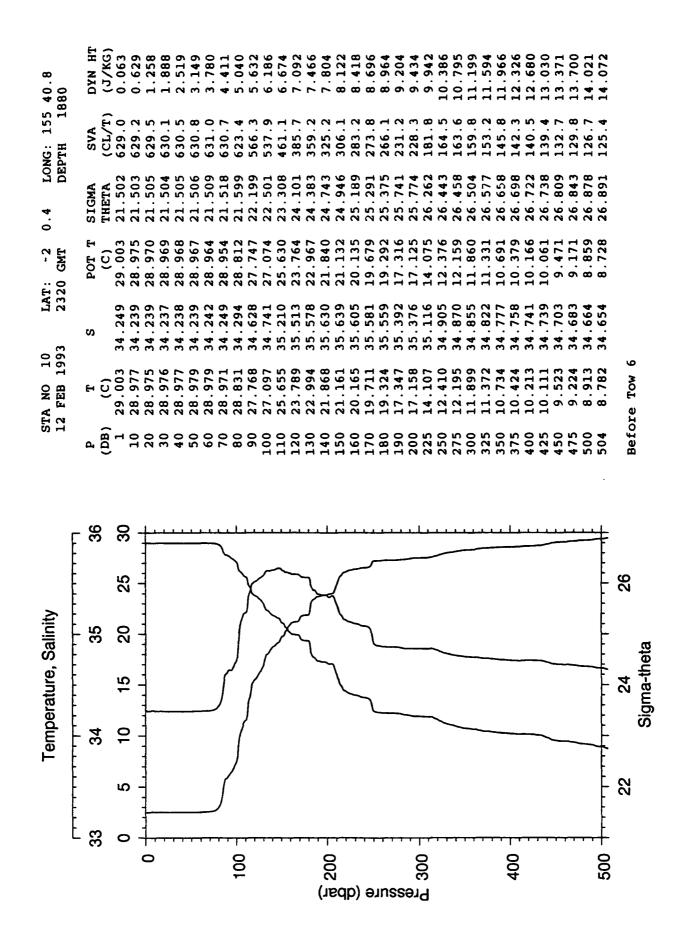


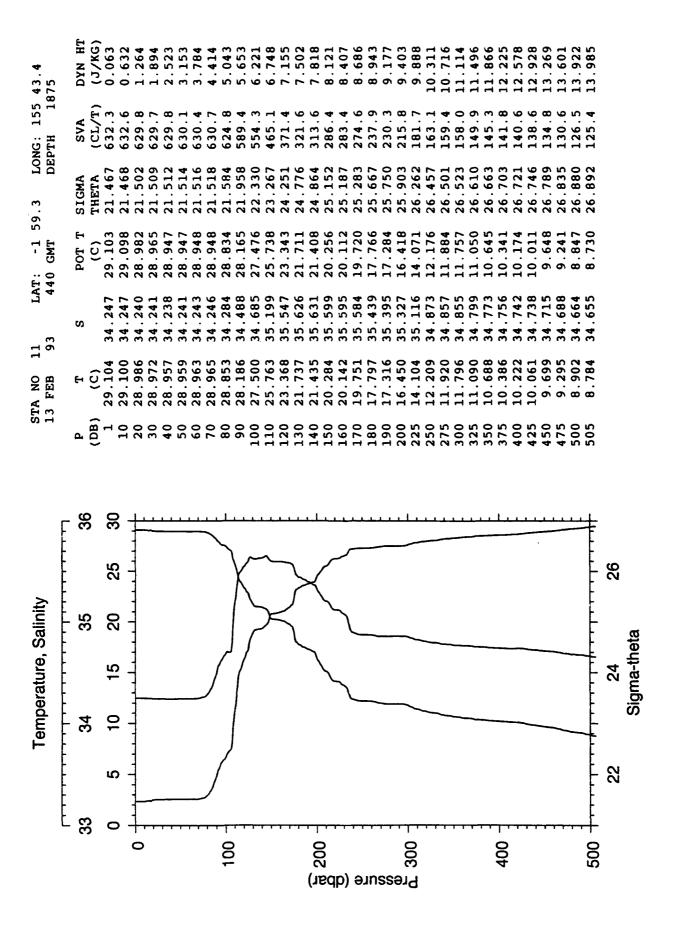


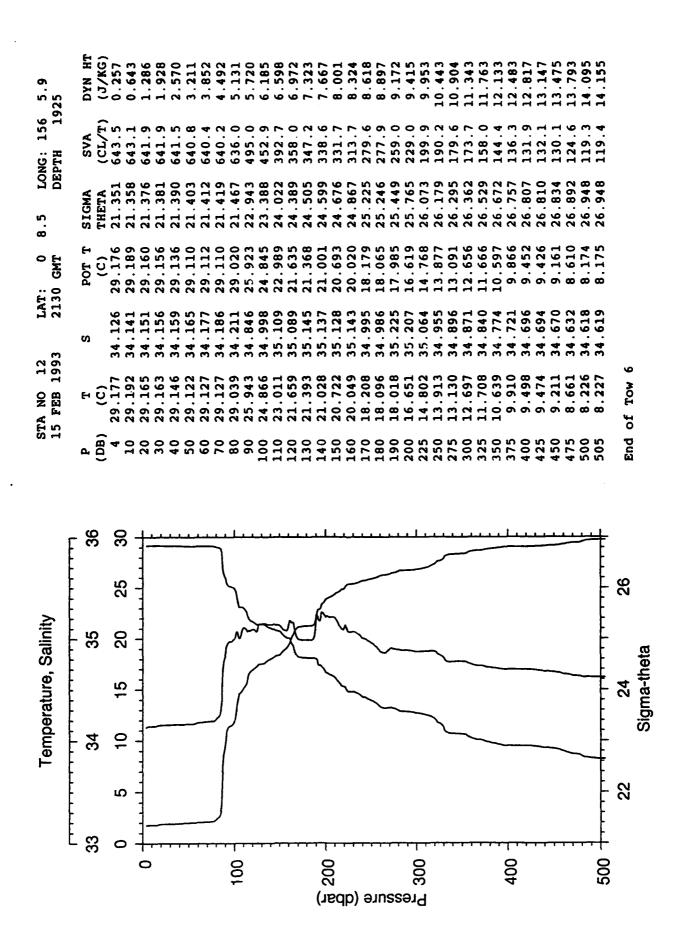




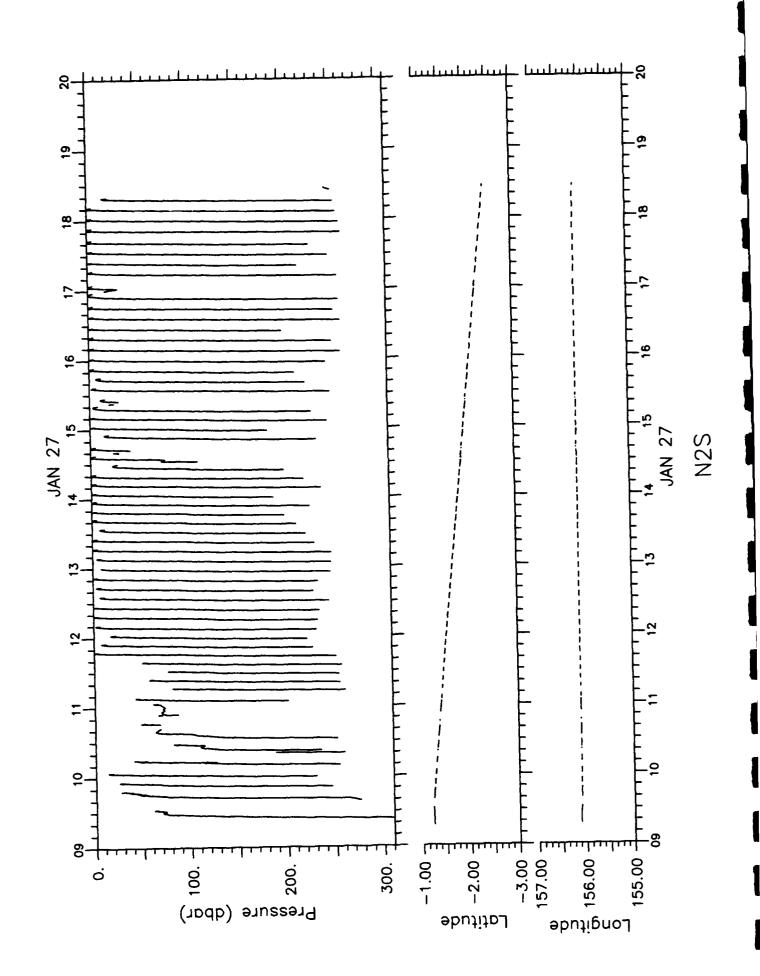


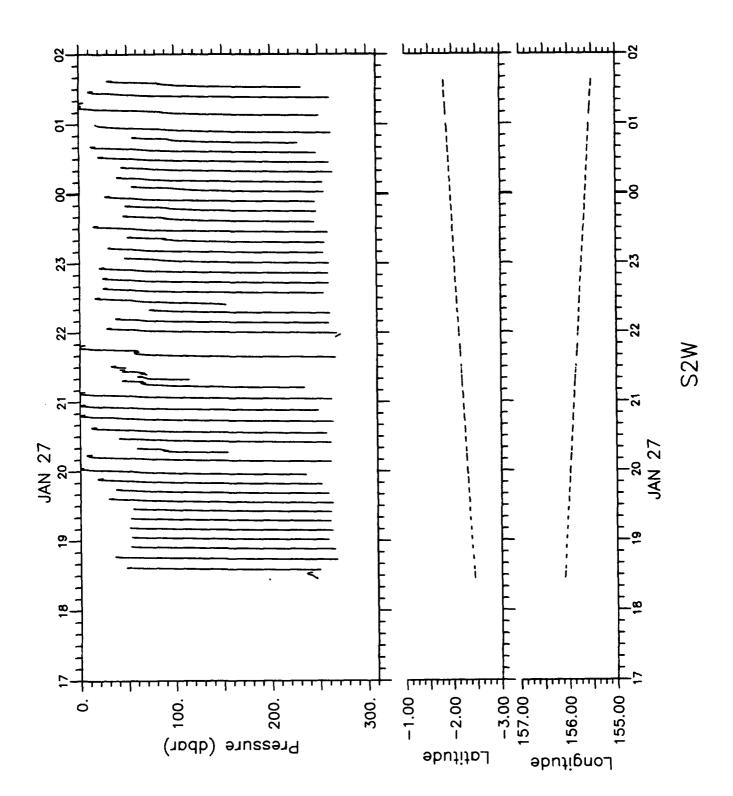


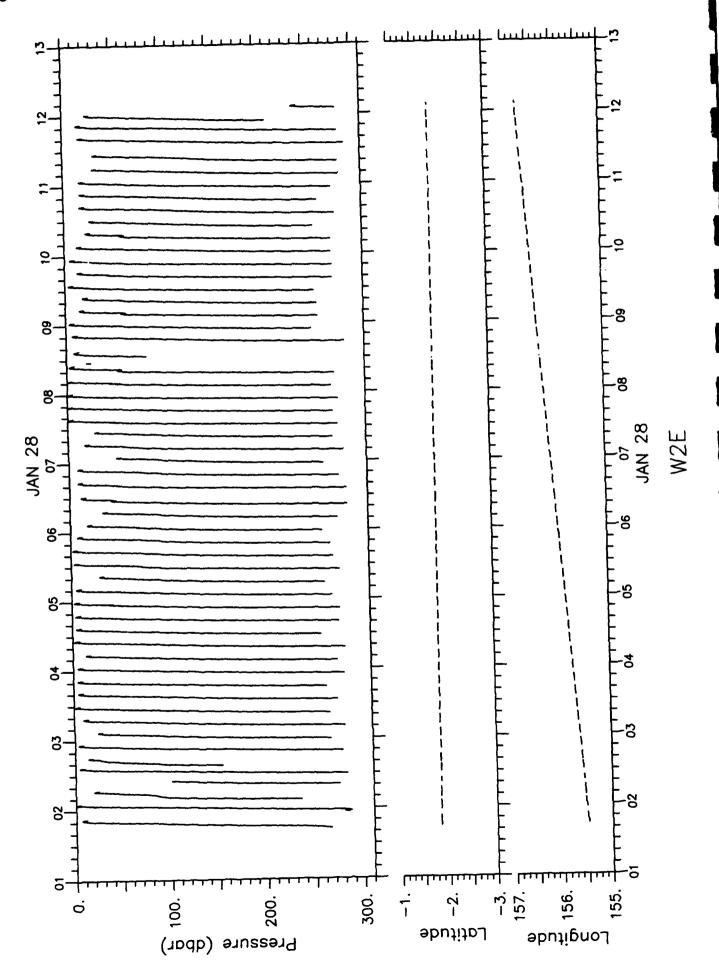


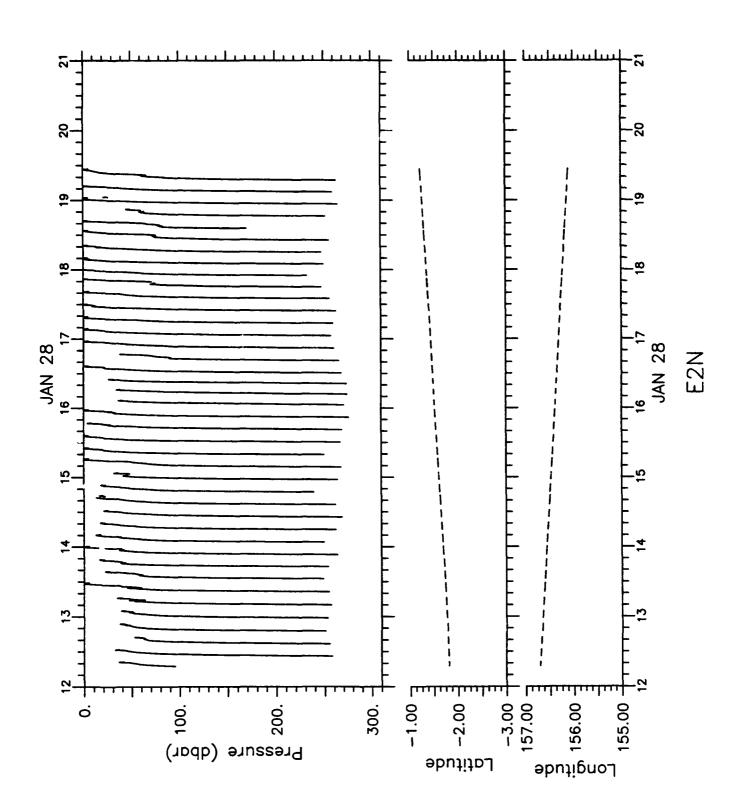


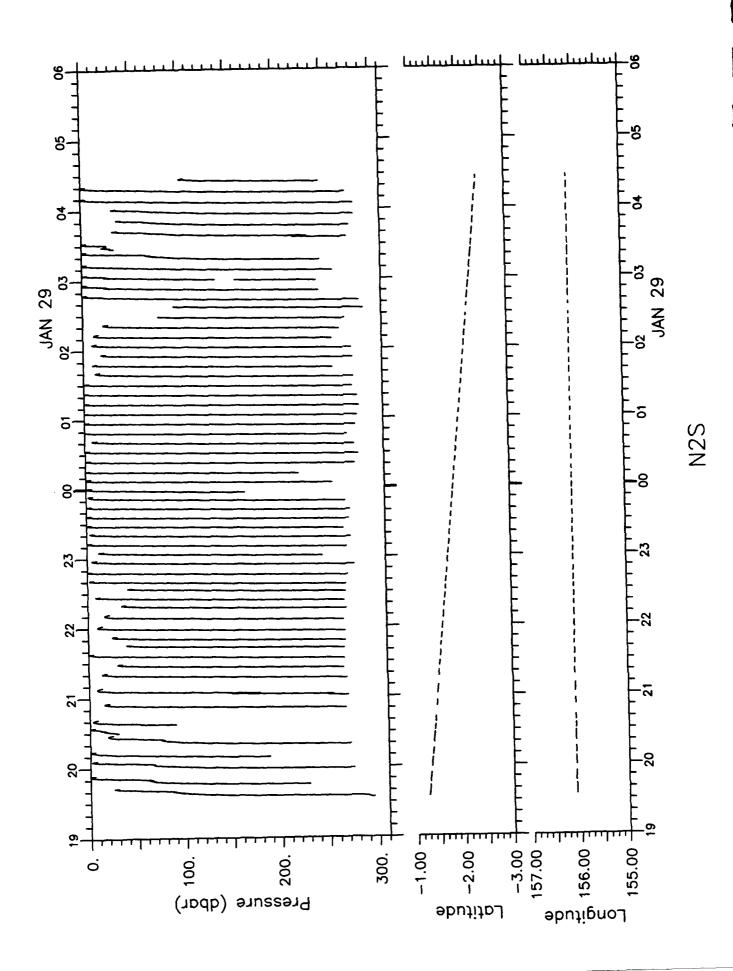
SEASOAR TRAJECTORIES

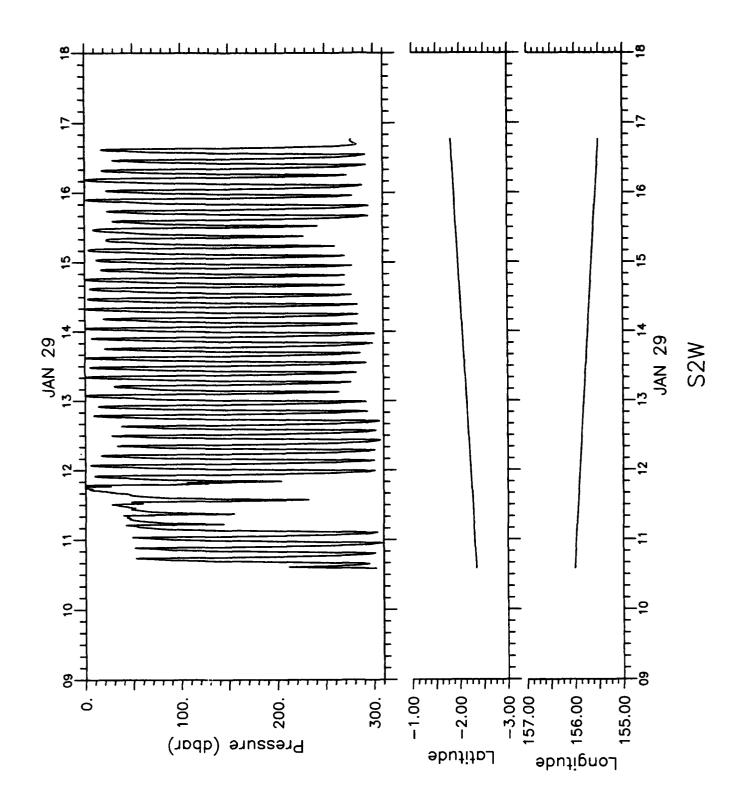


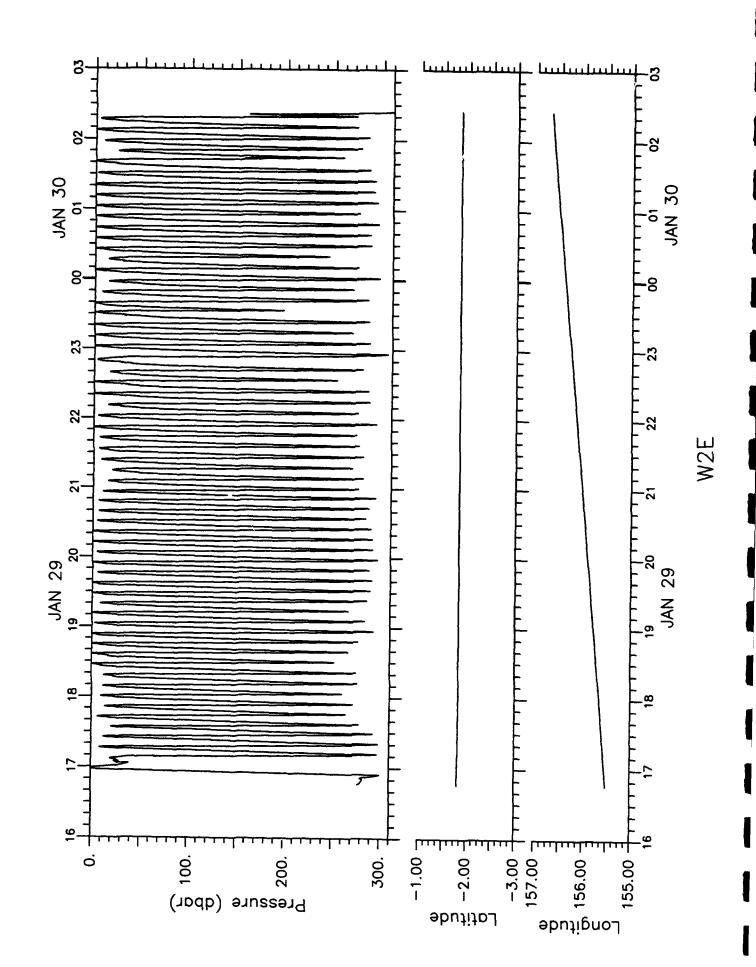


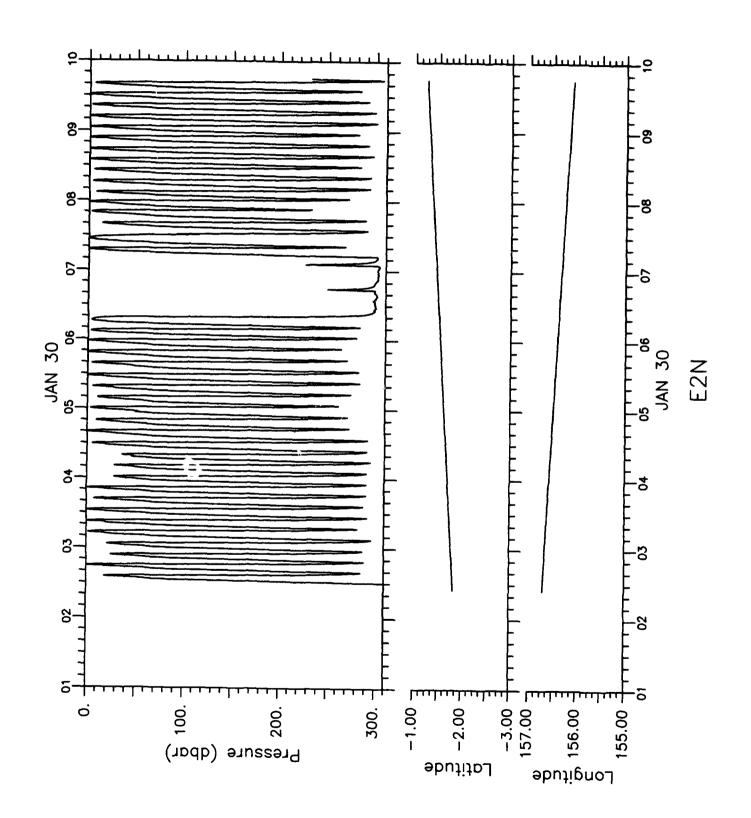


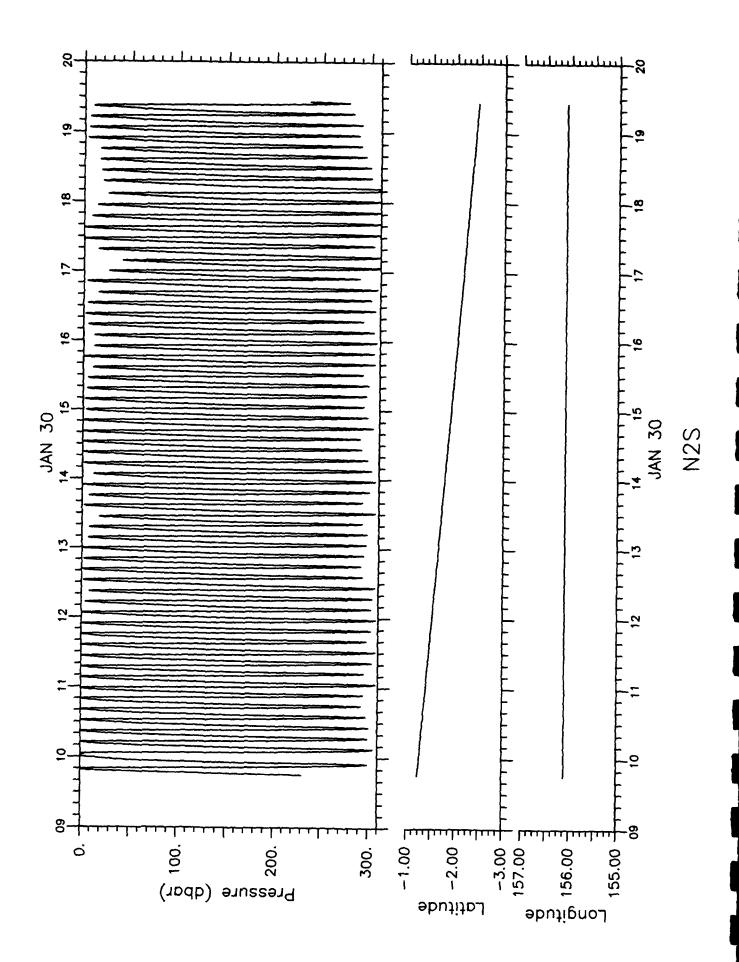


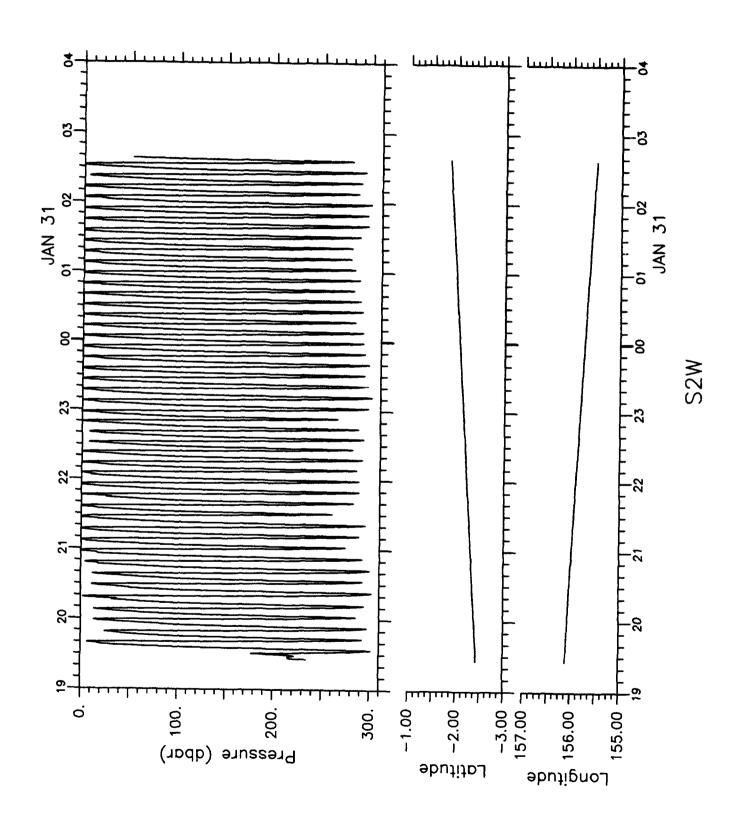


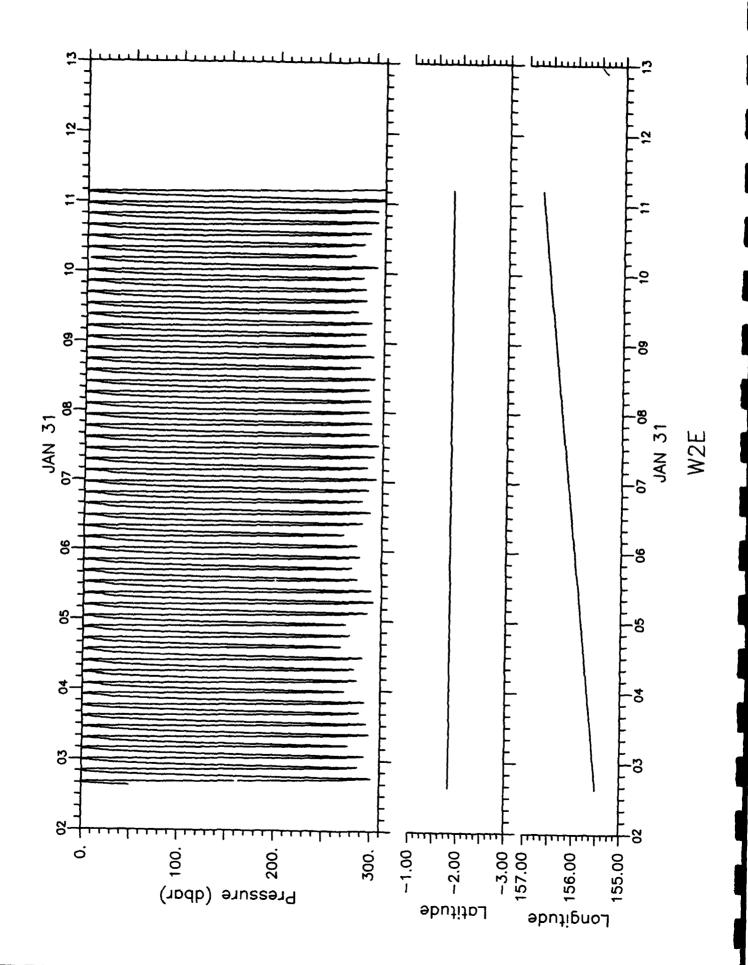


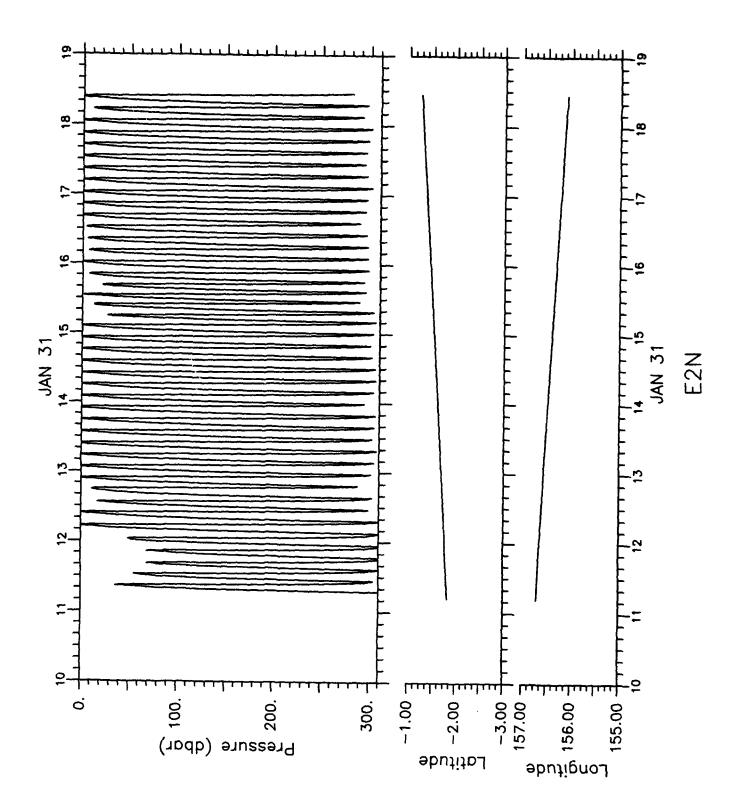


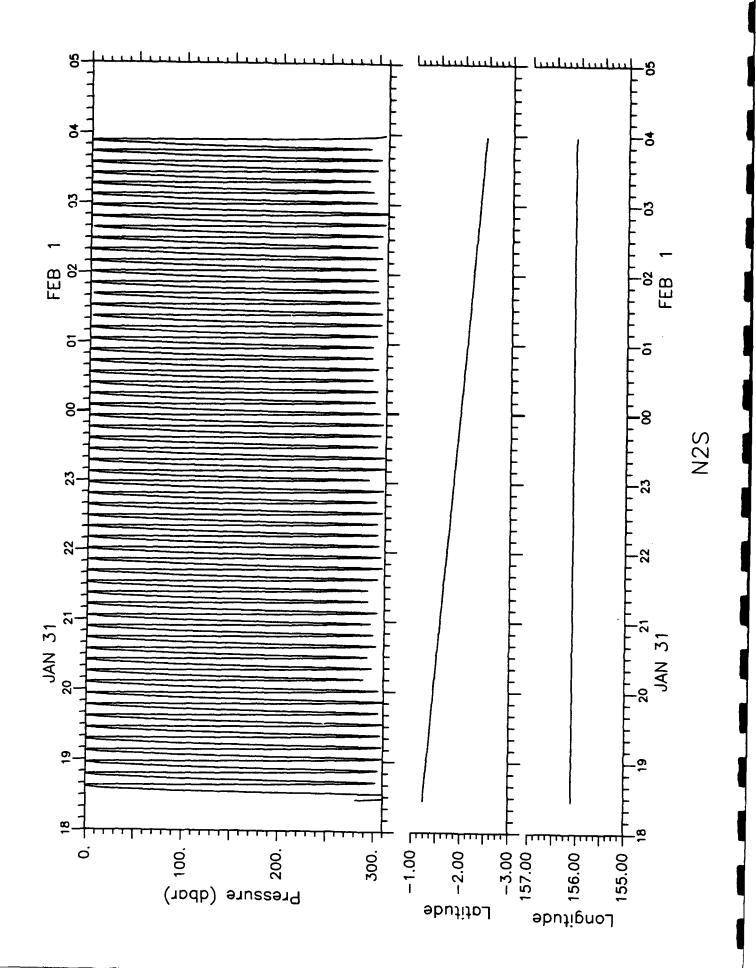


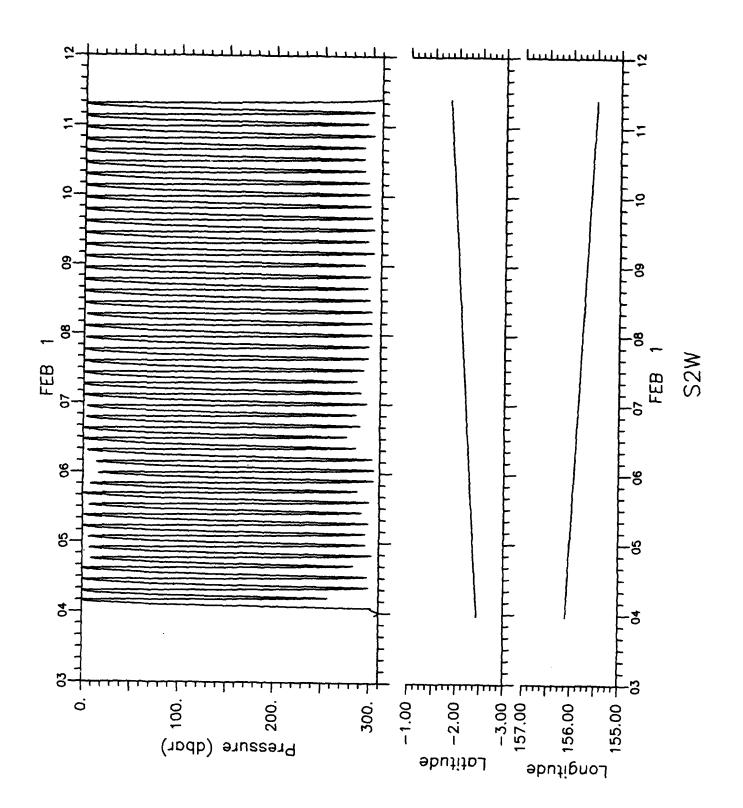


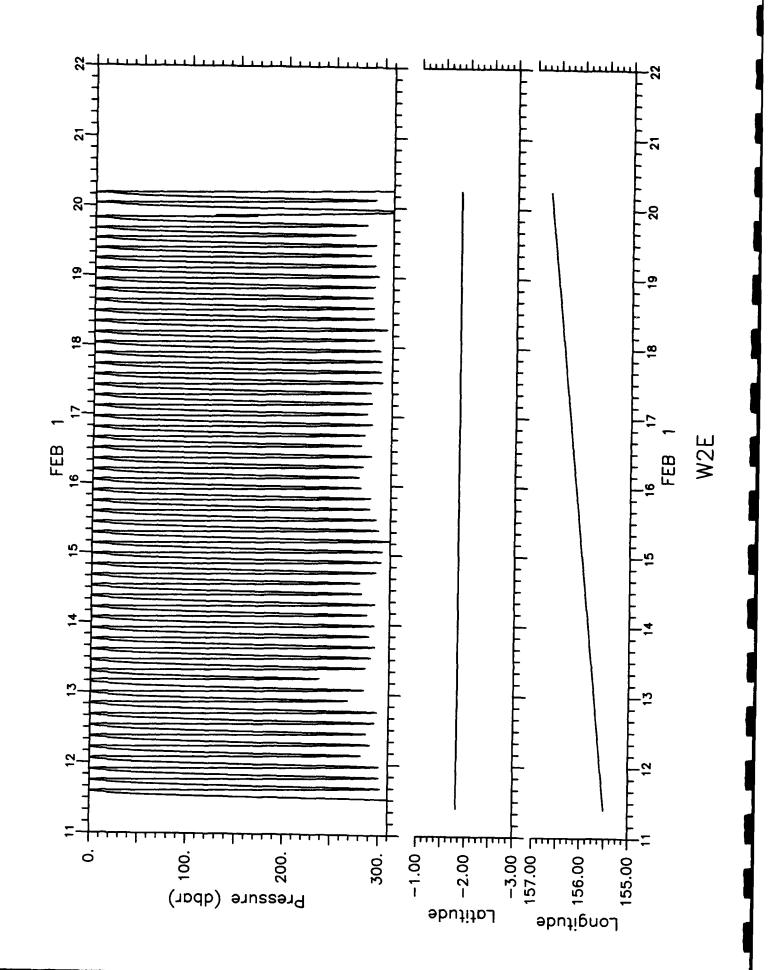


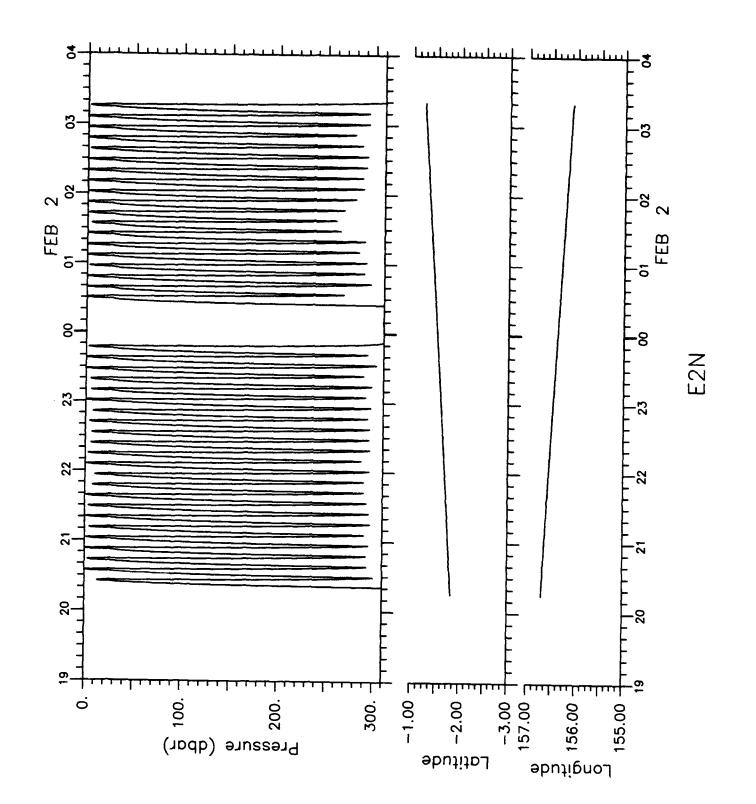


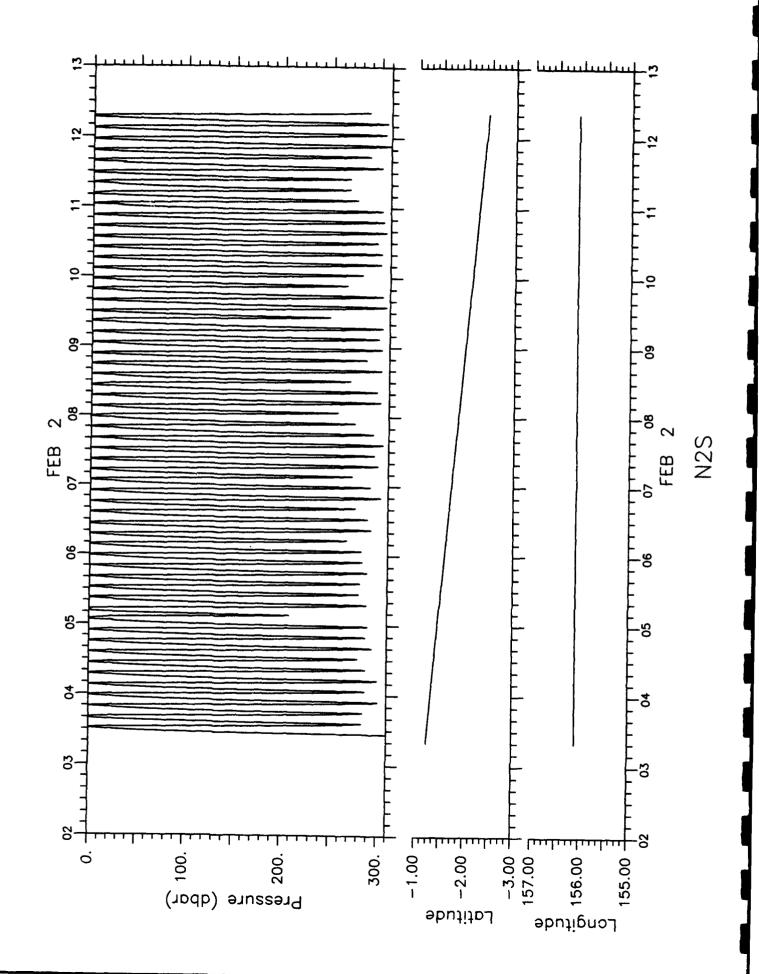


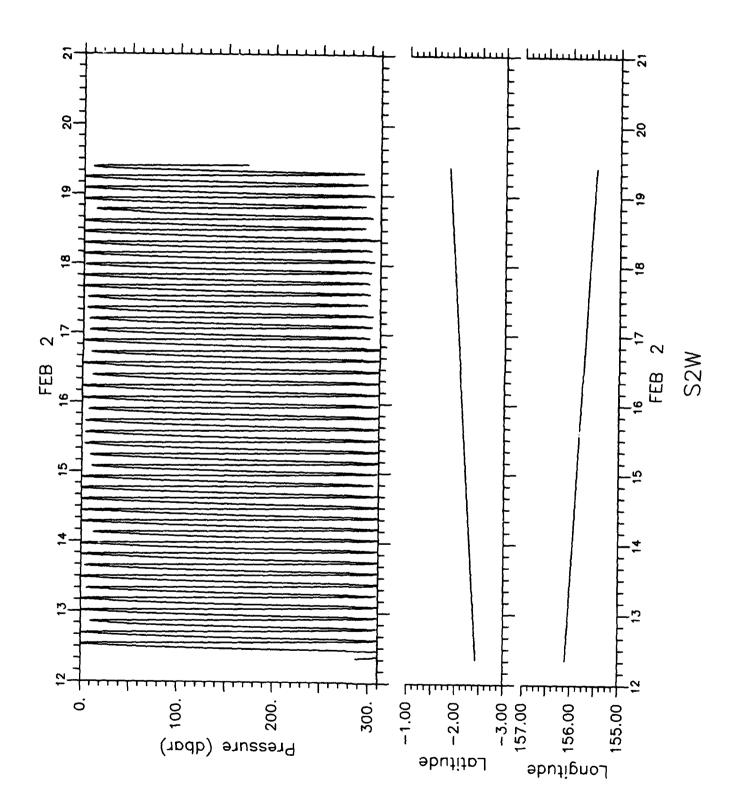


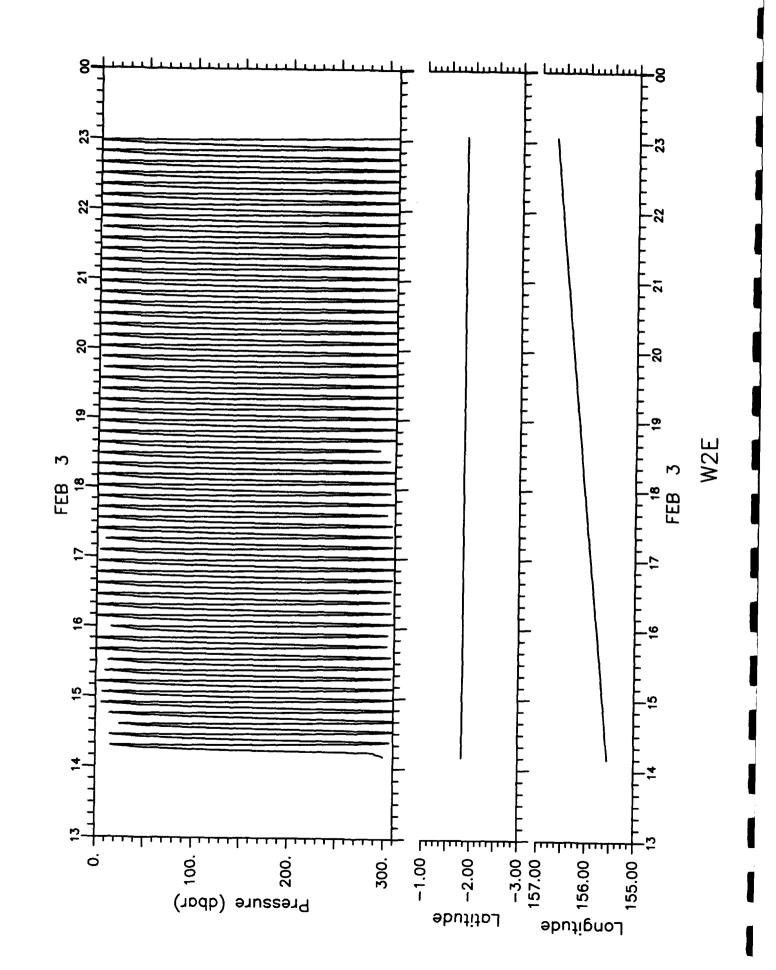


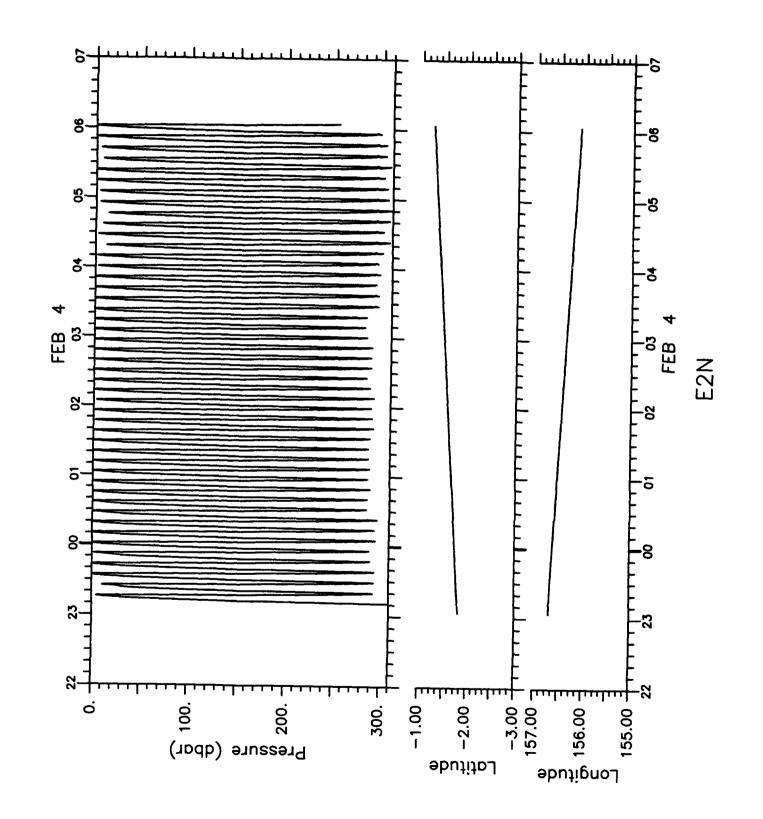


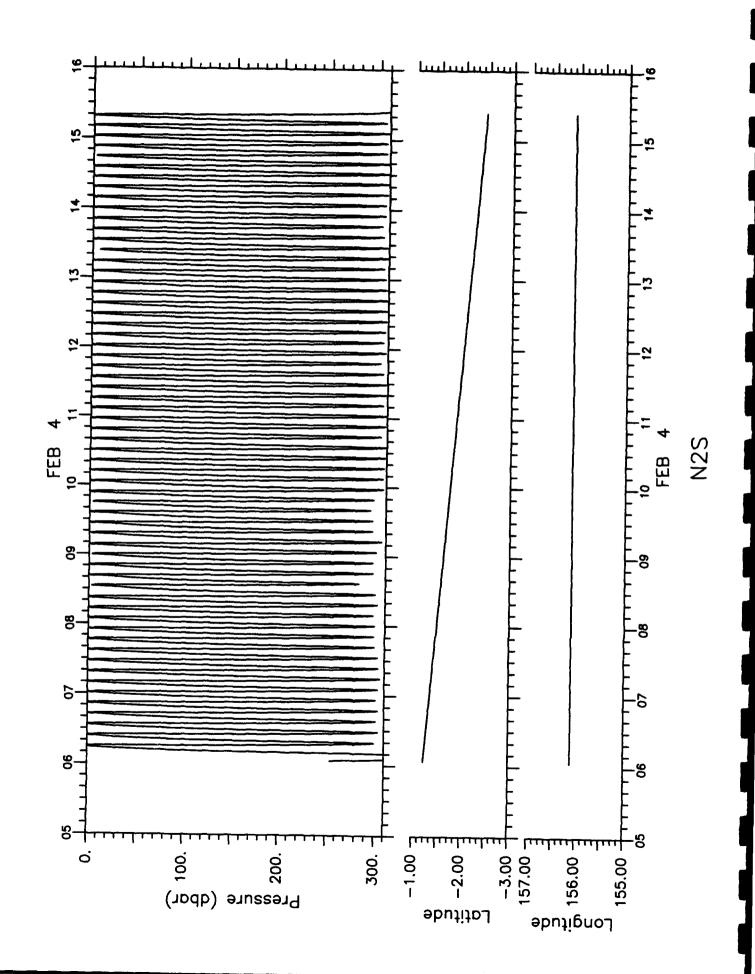


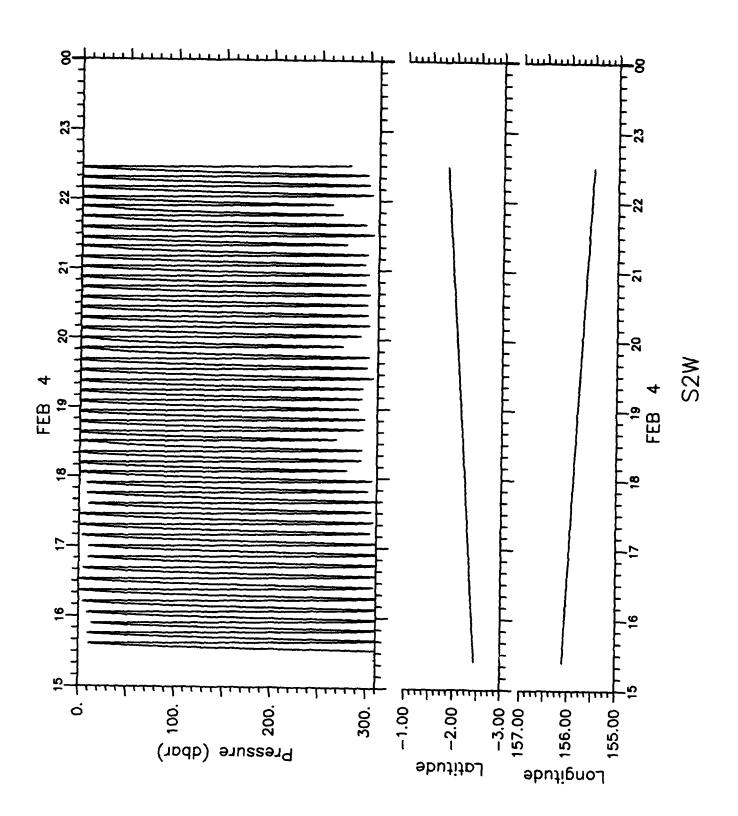


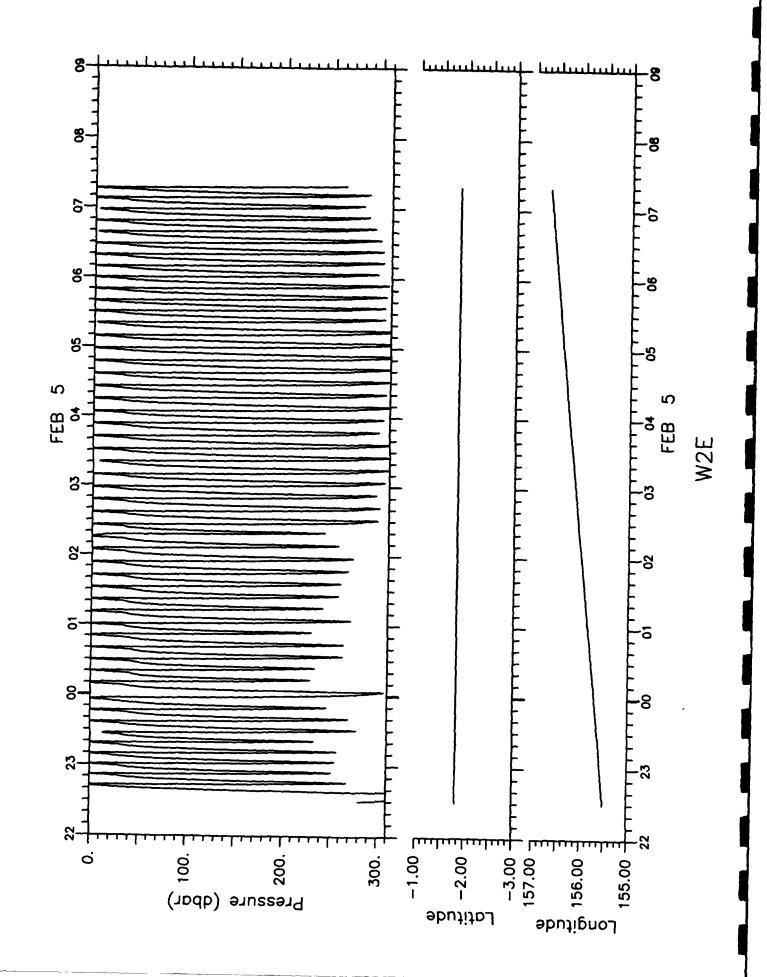


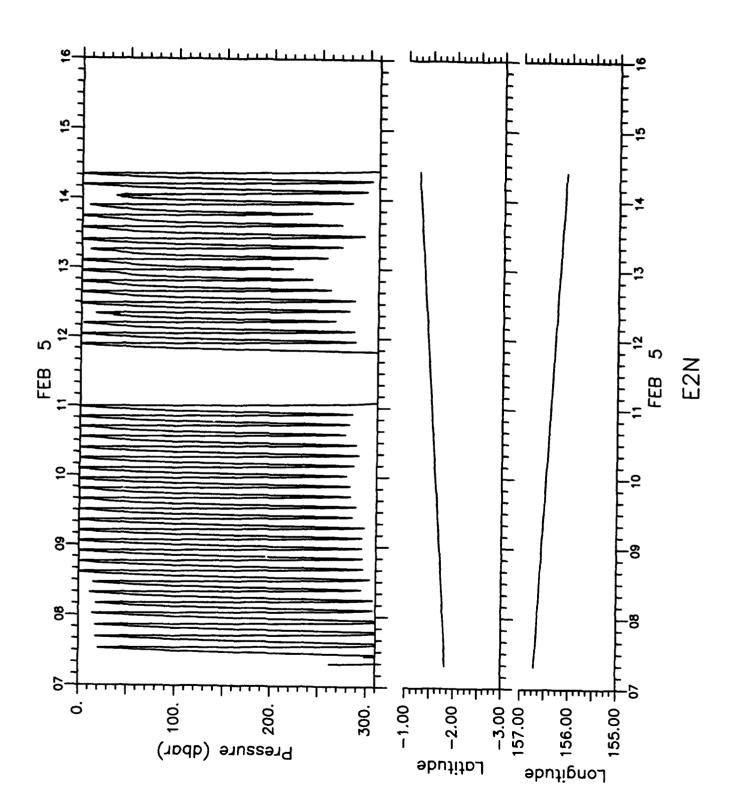


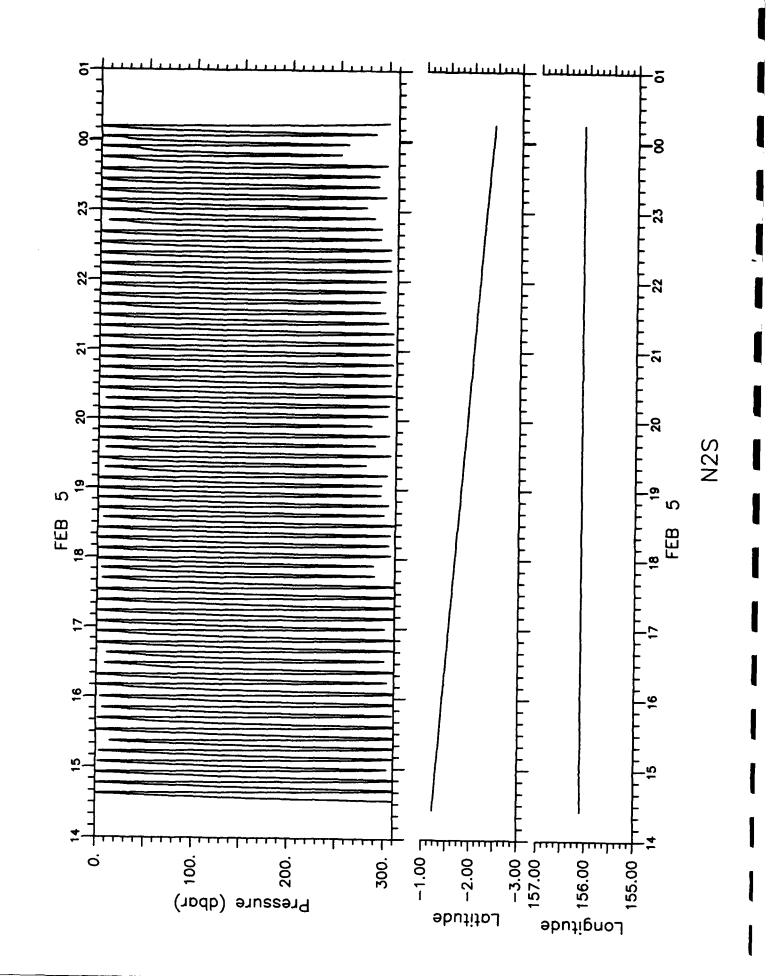


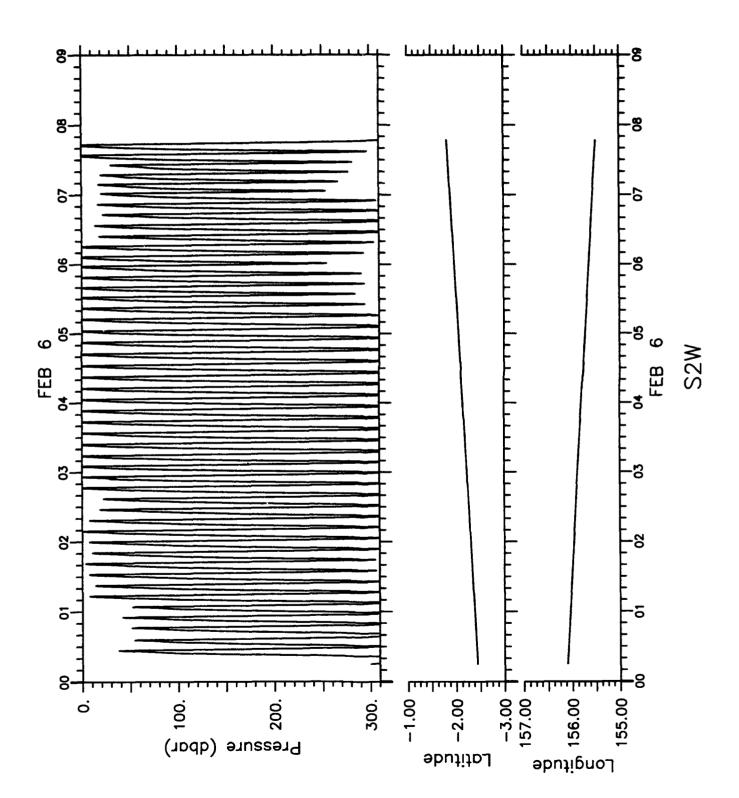


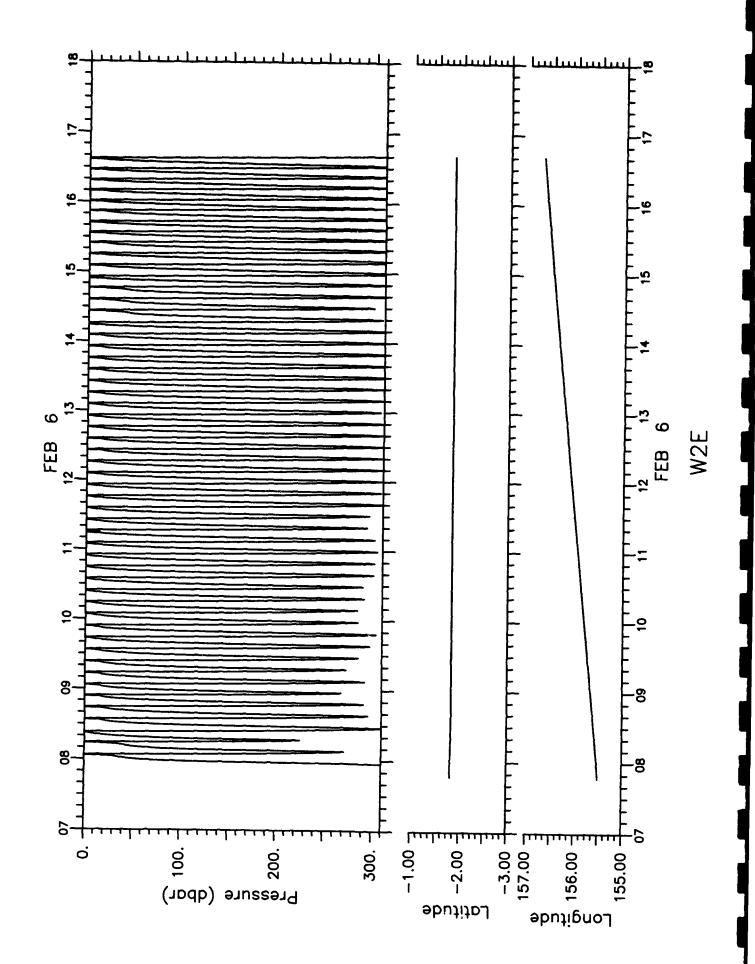


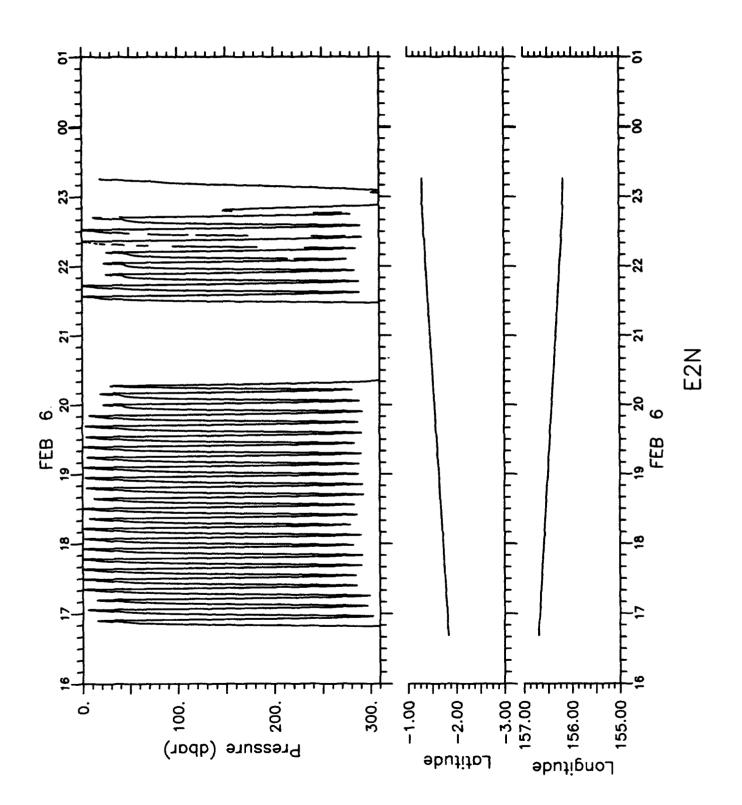


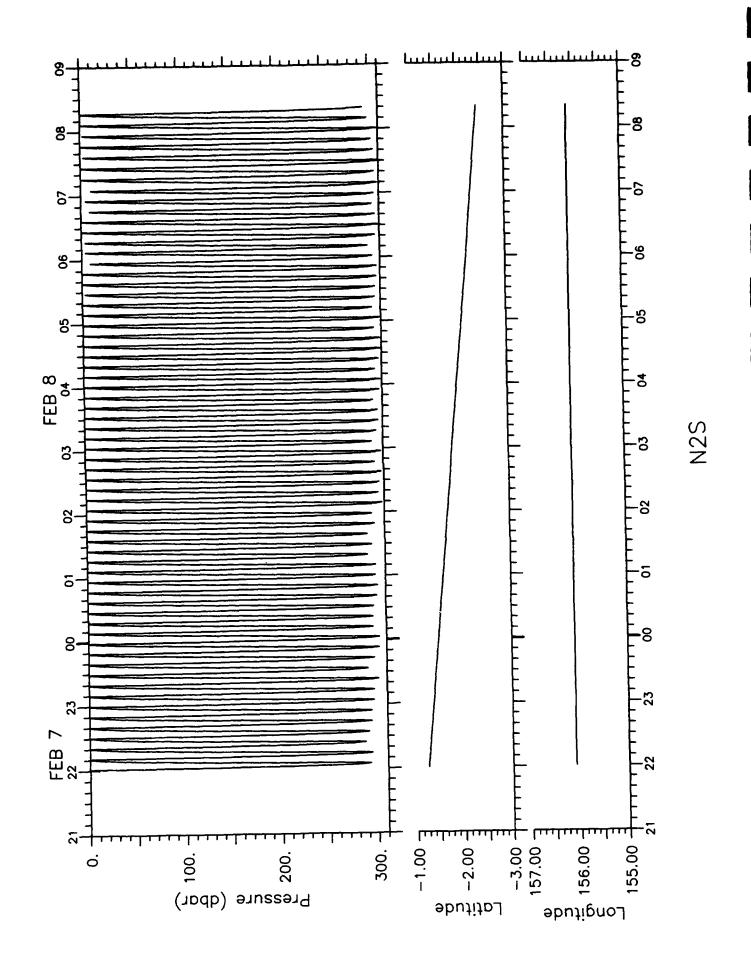


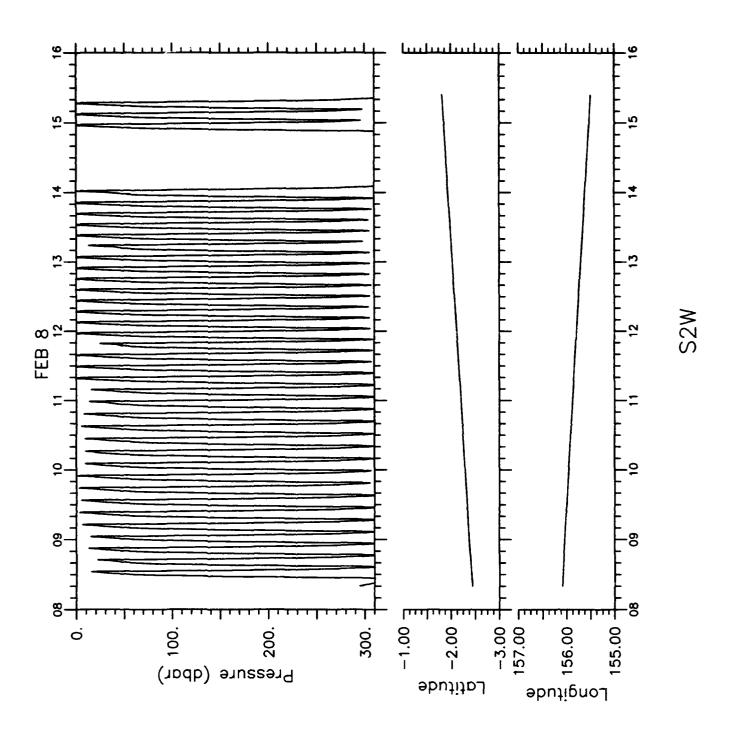


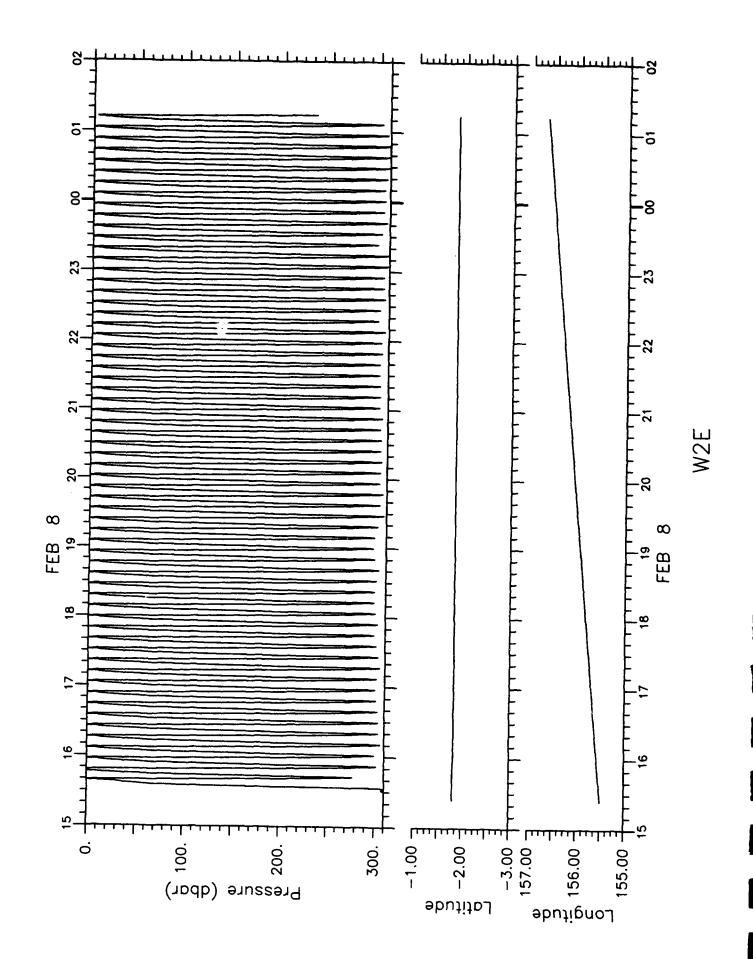


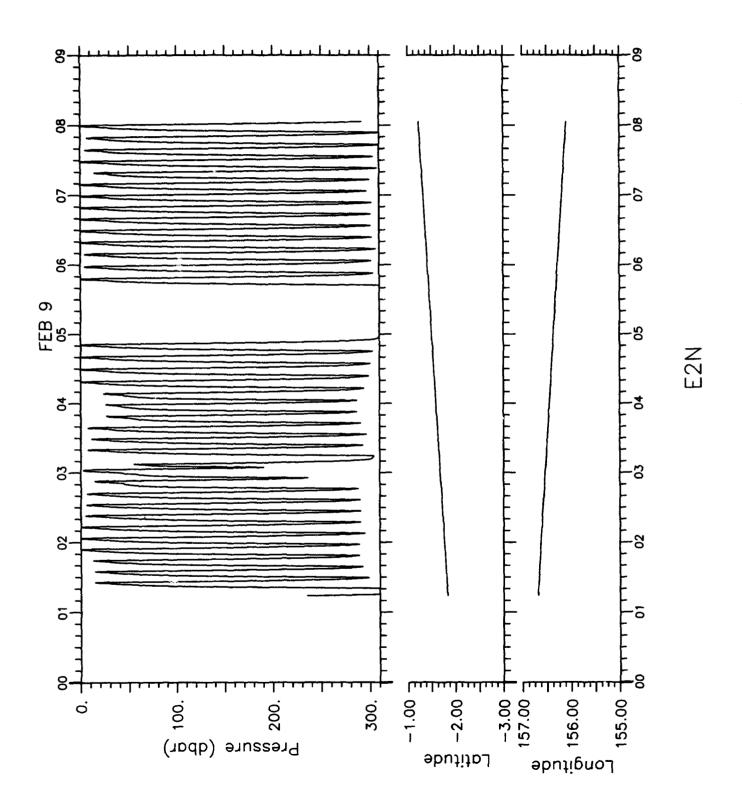


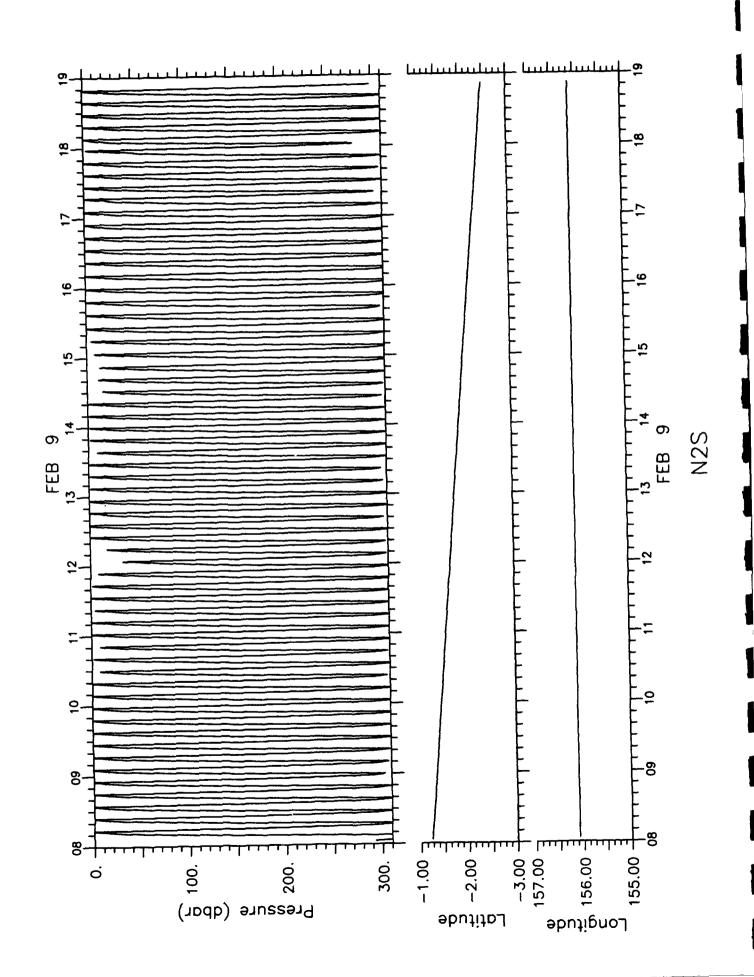


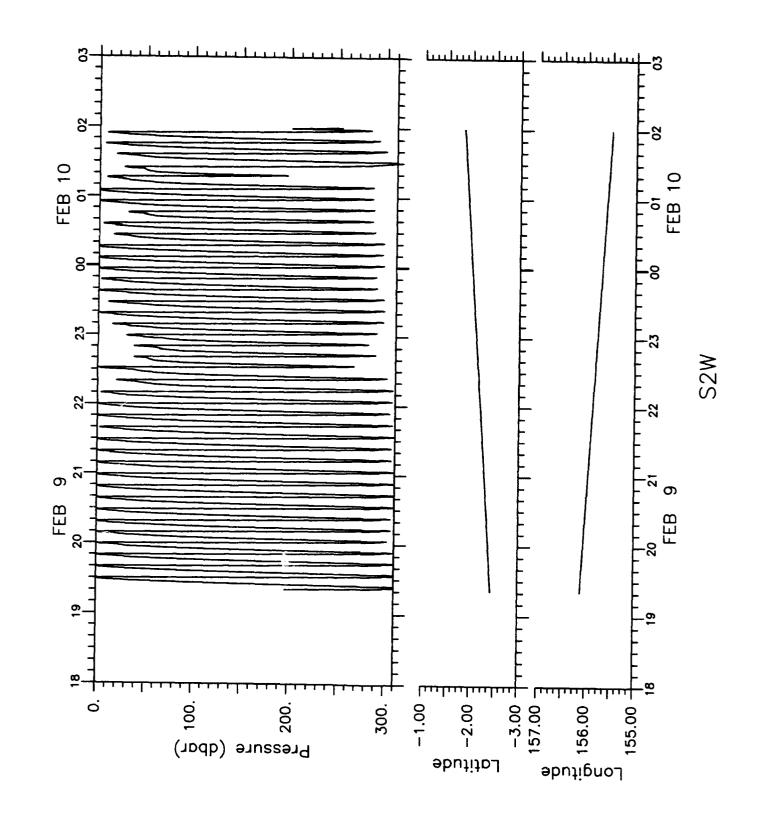


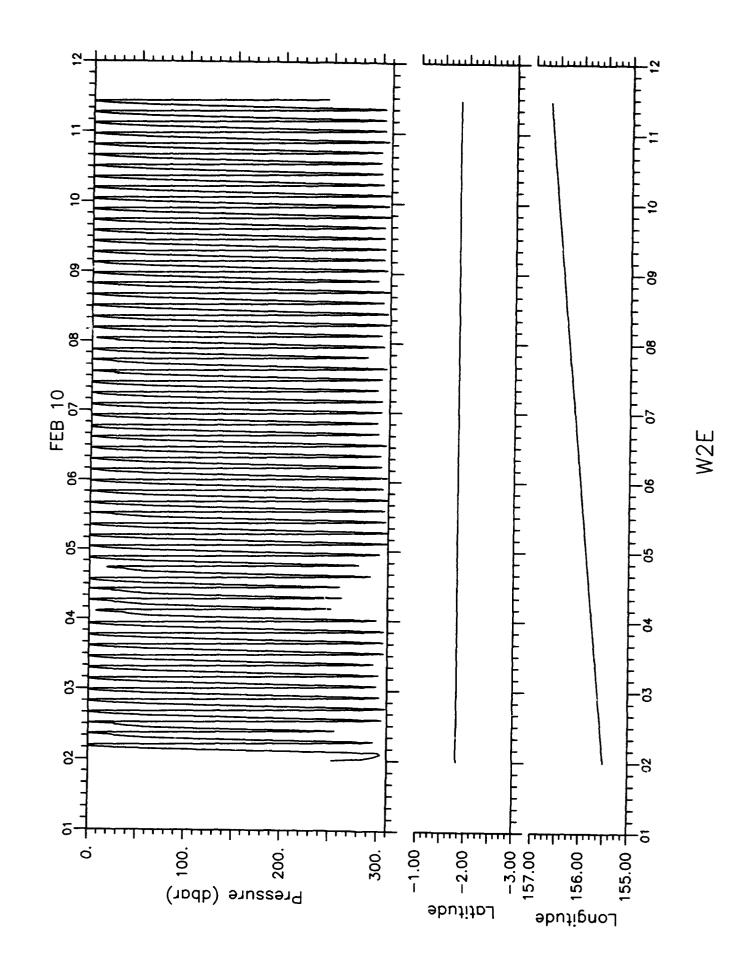


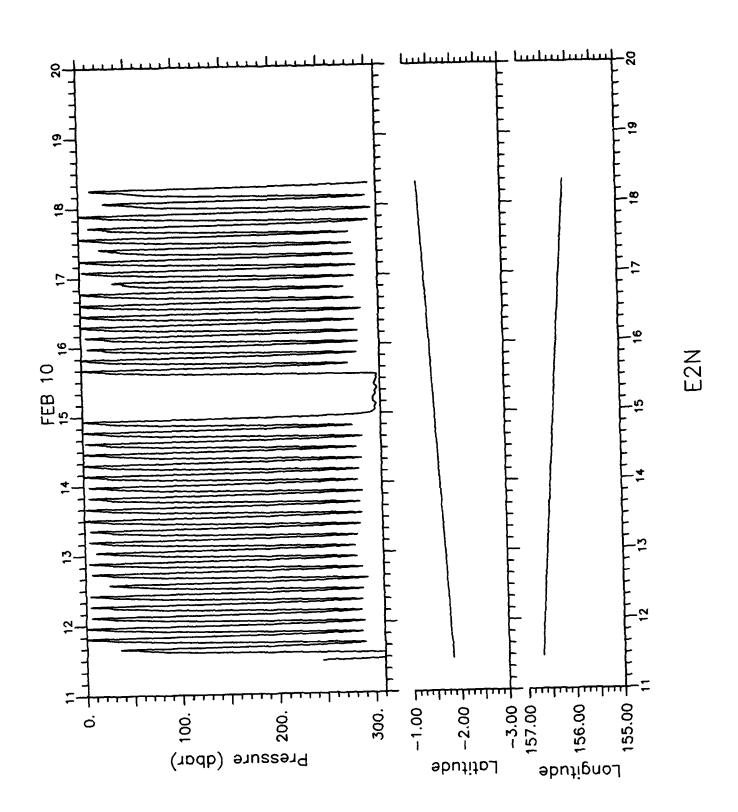


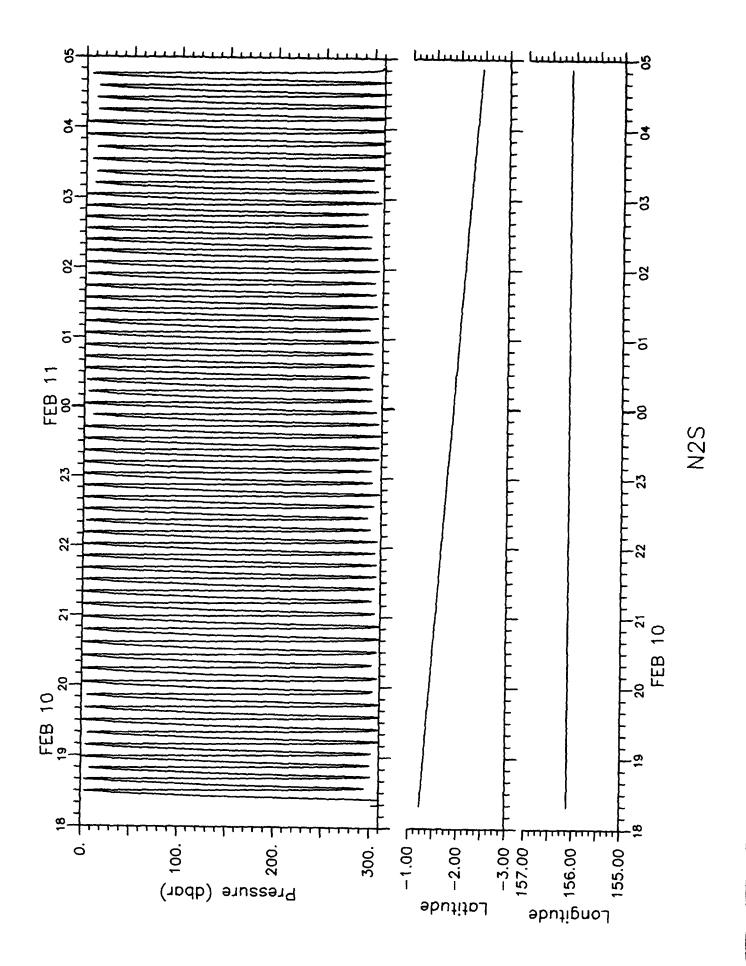


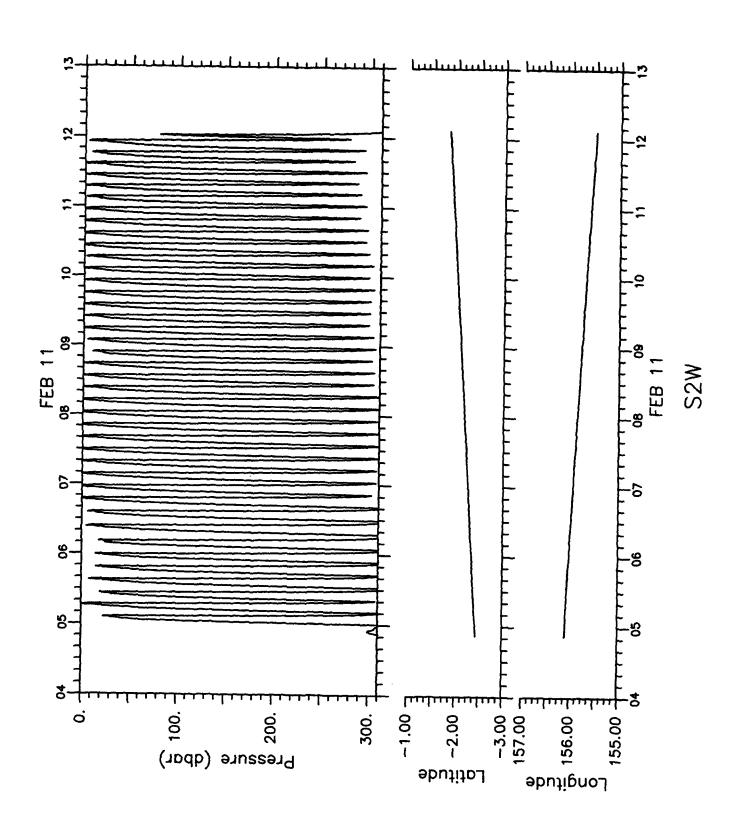


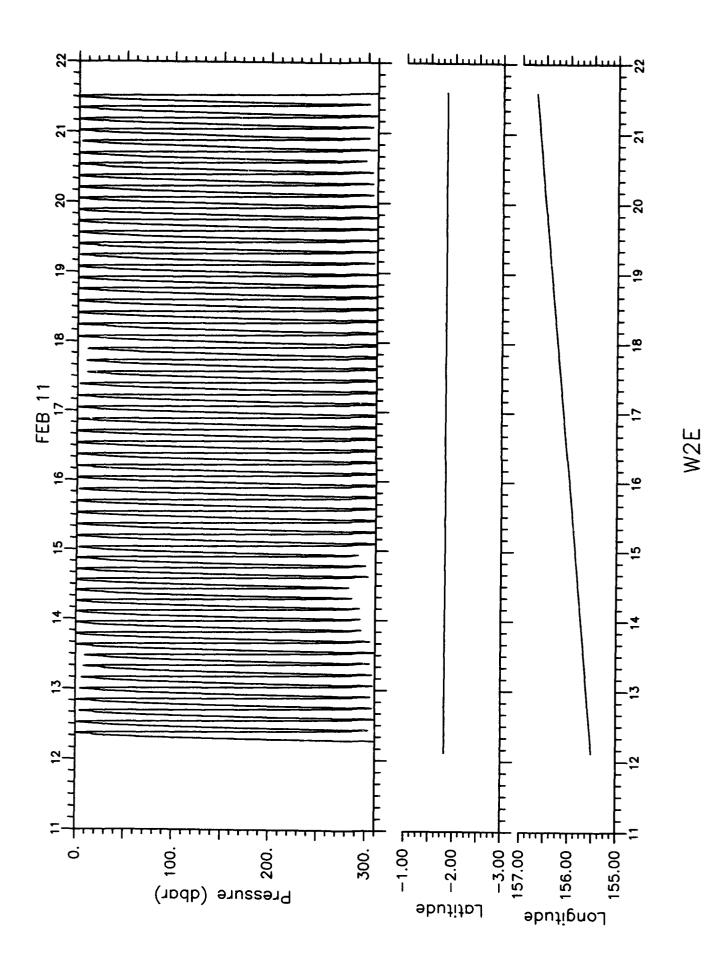


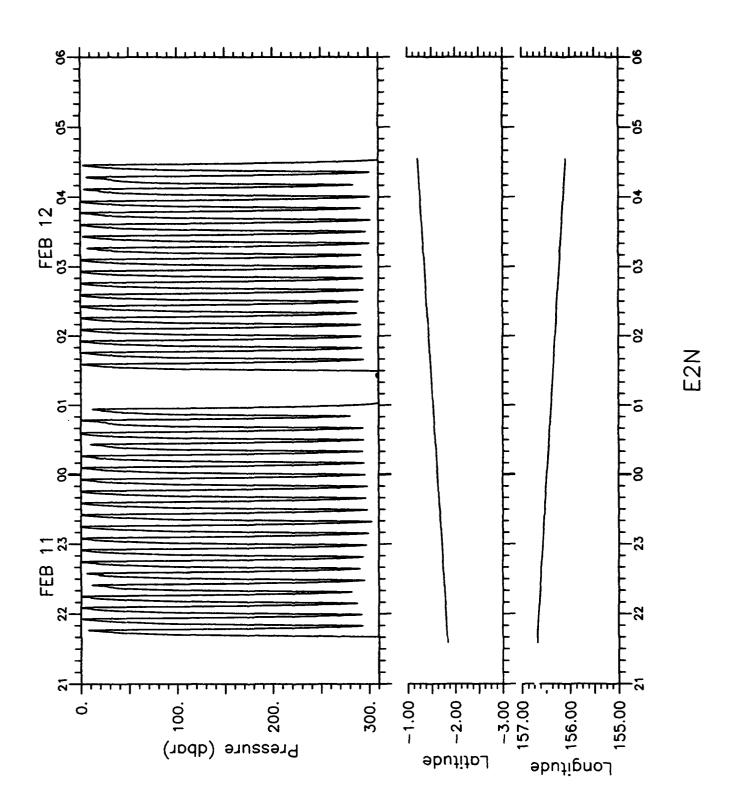


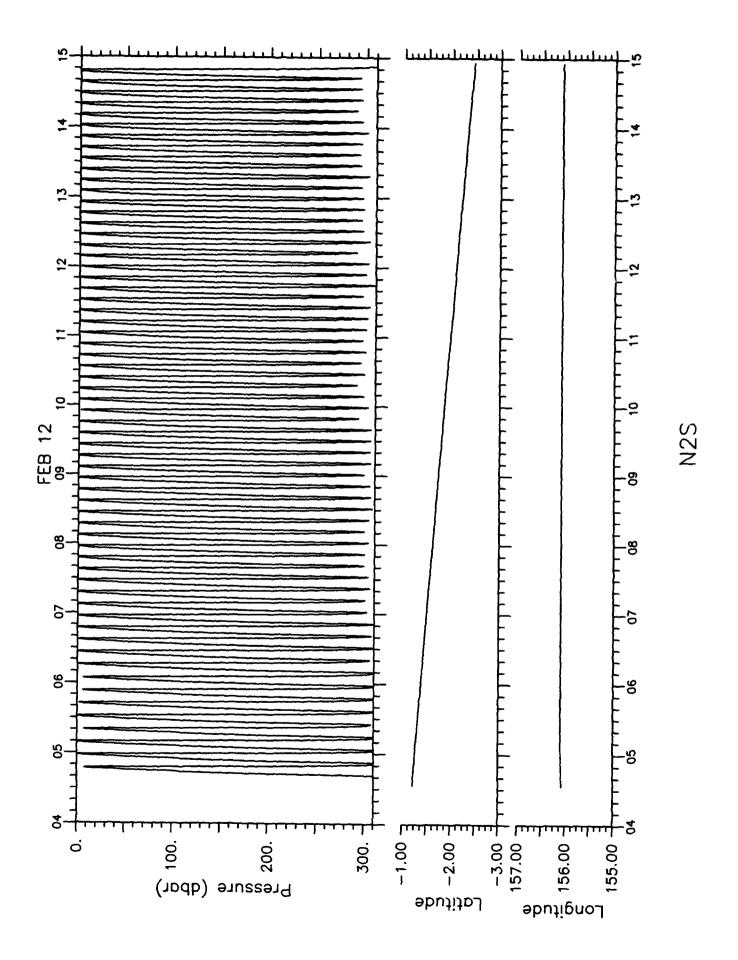


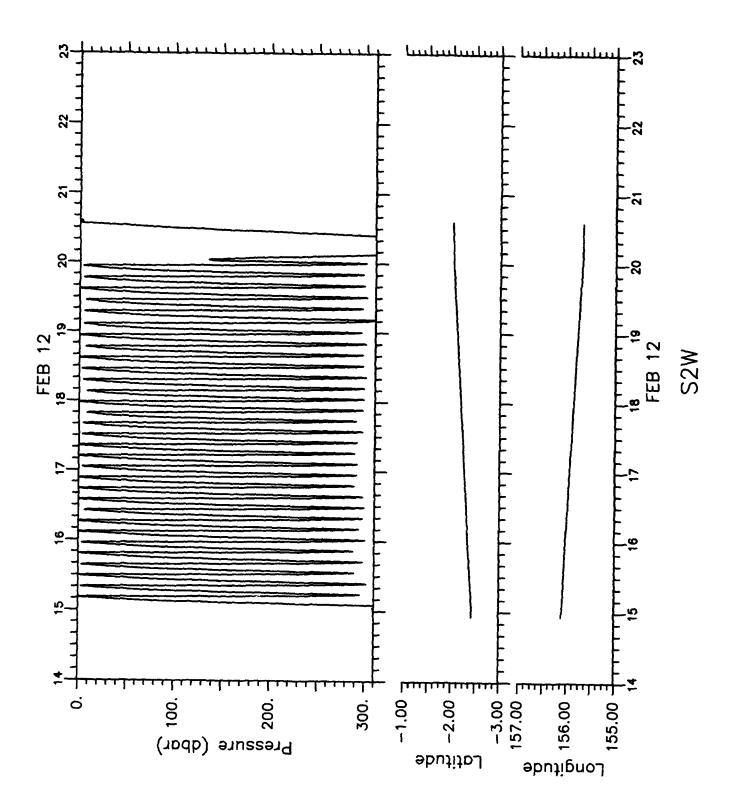


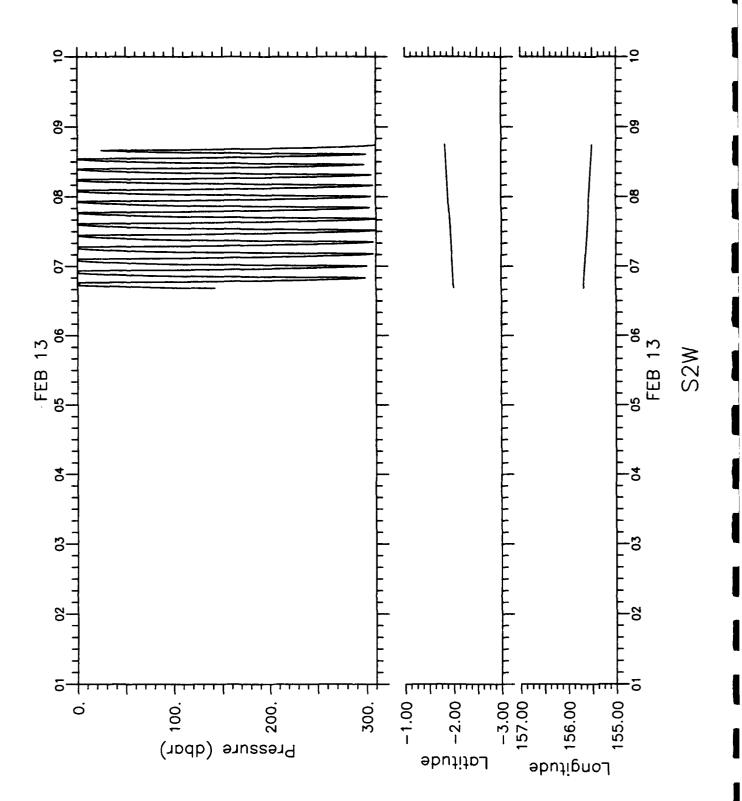


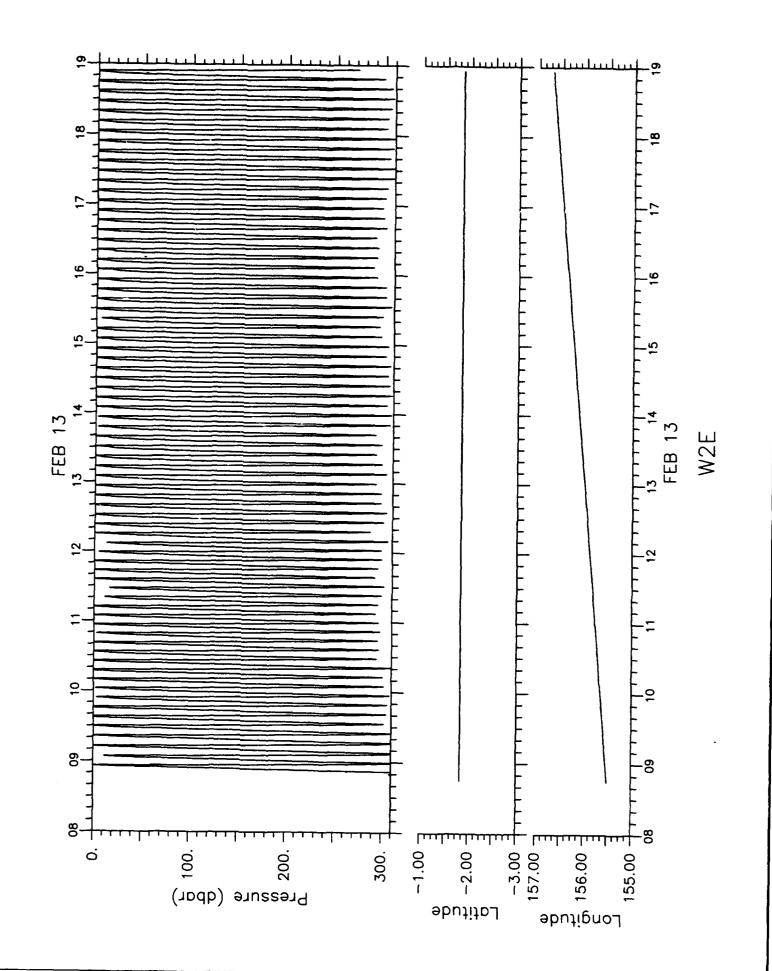


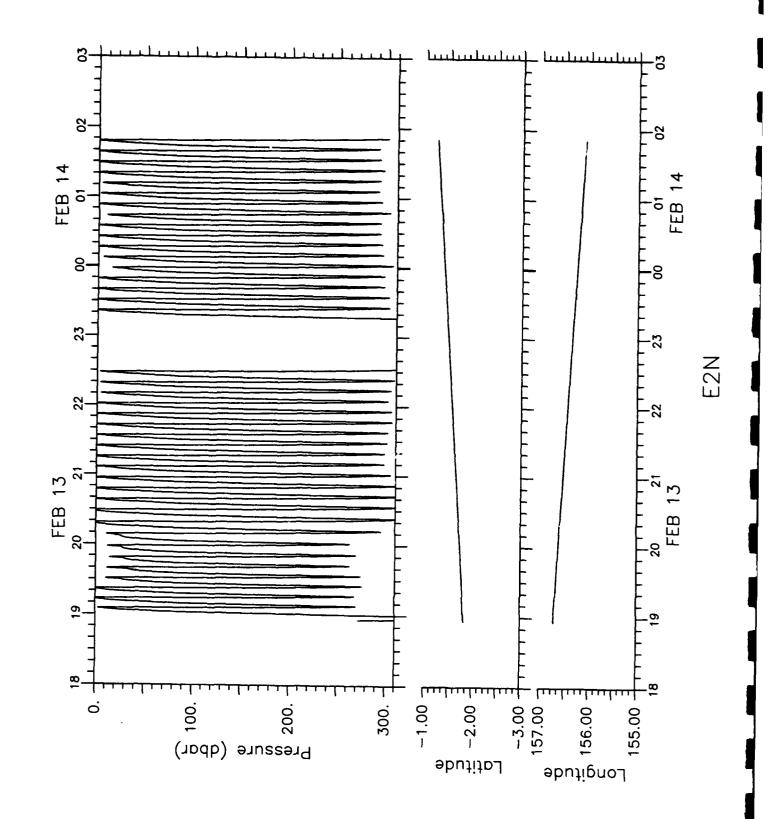


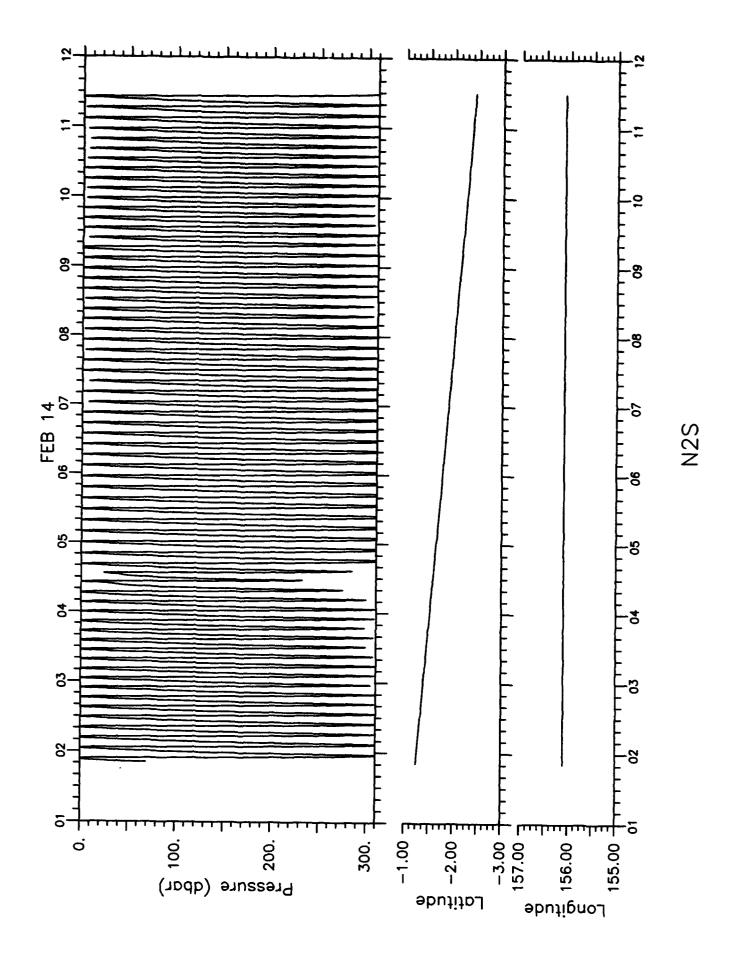


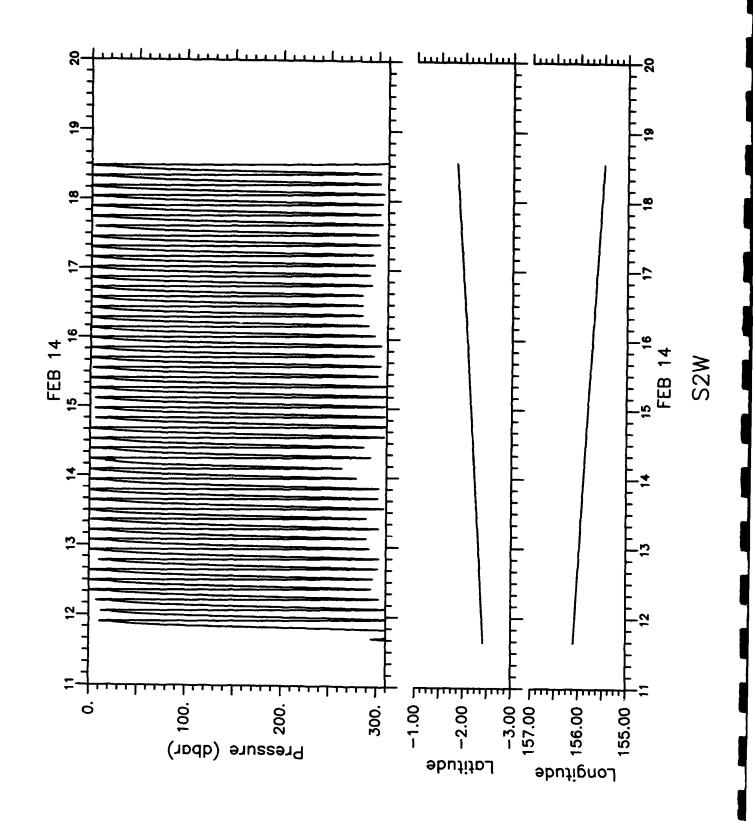


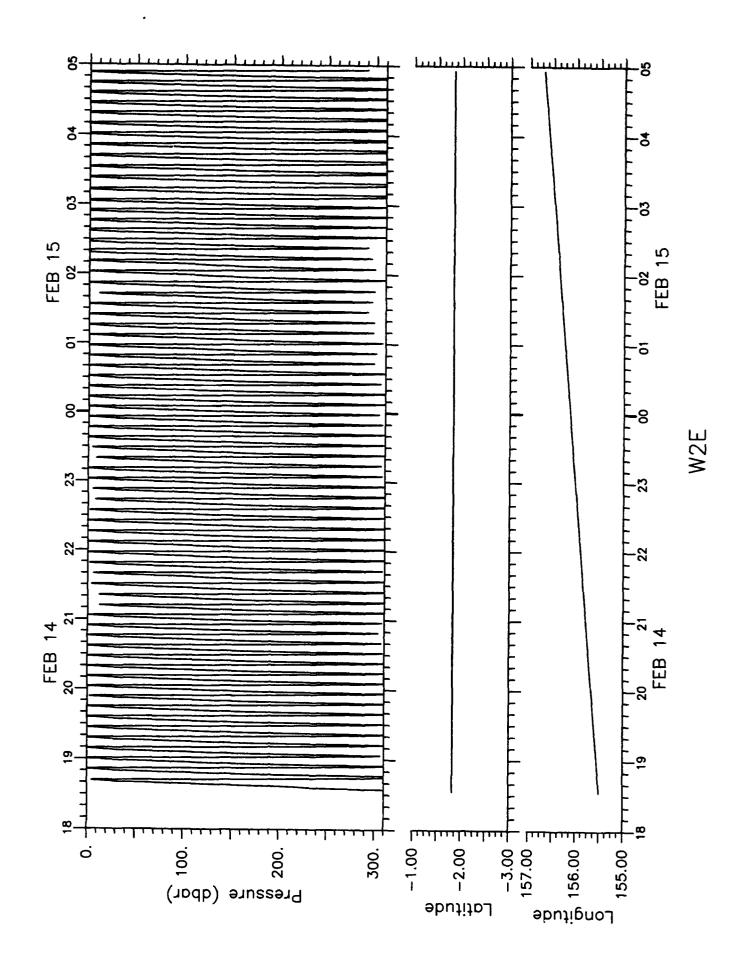


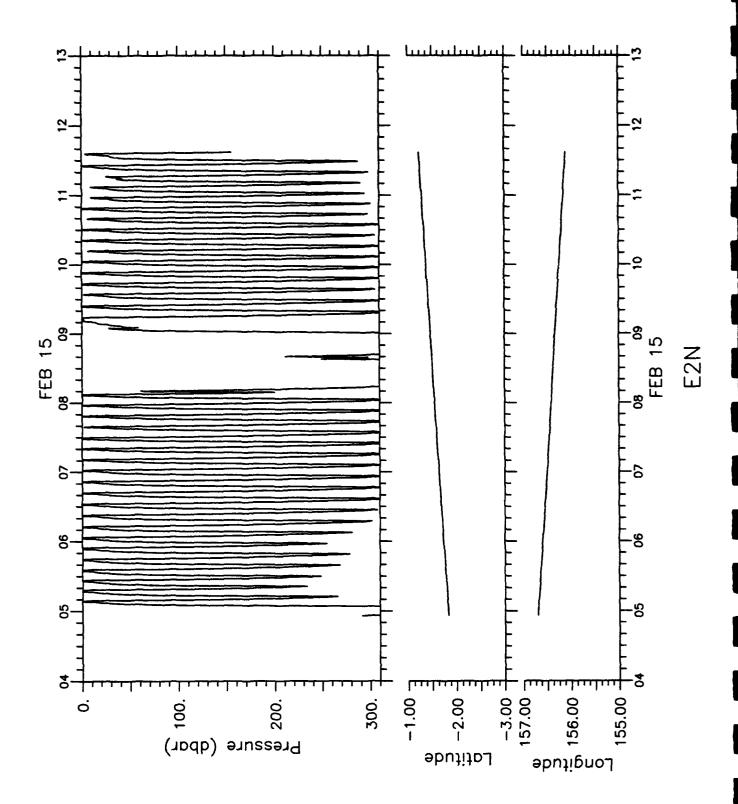


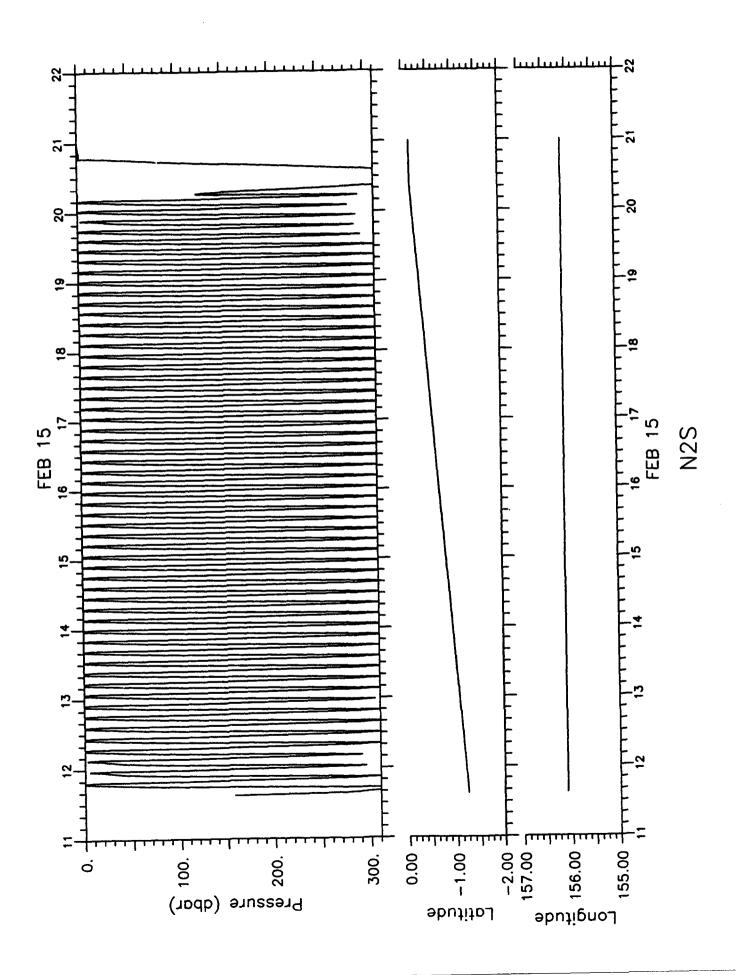








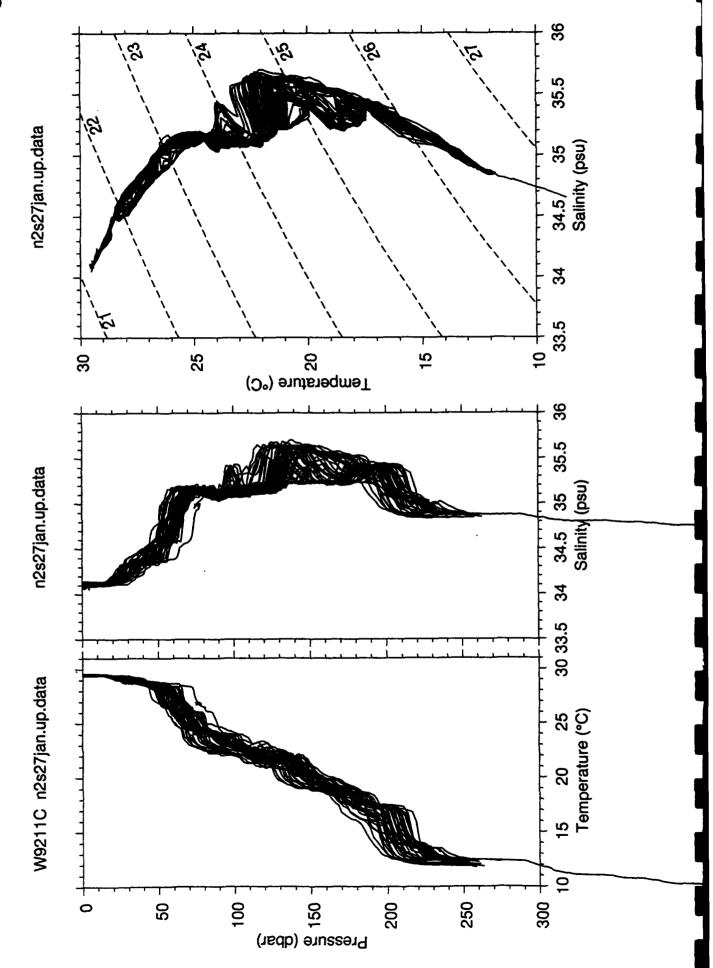


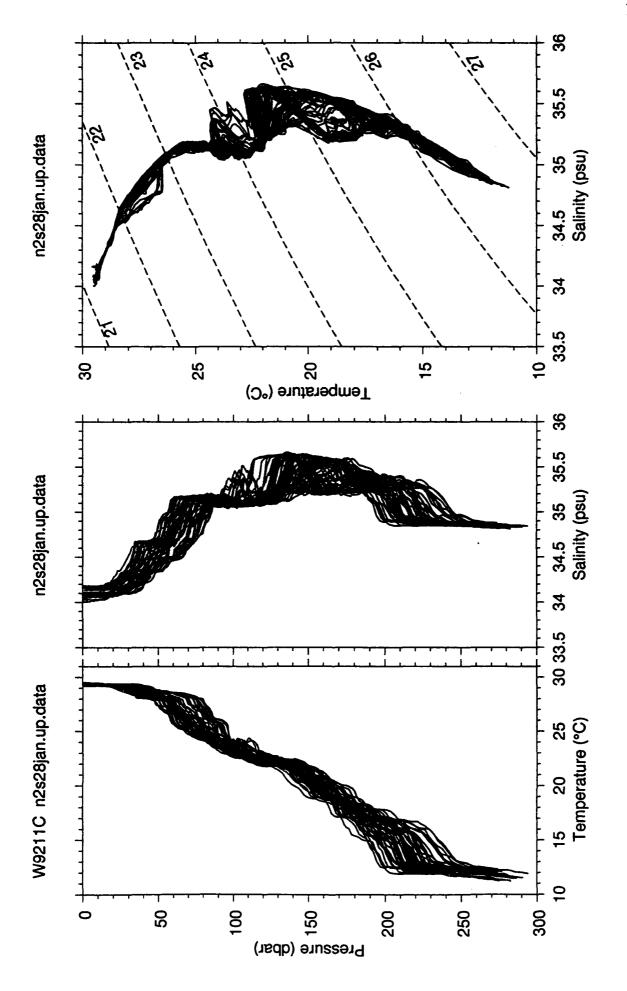


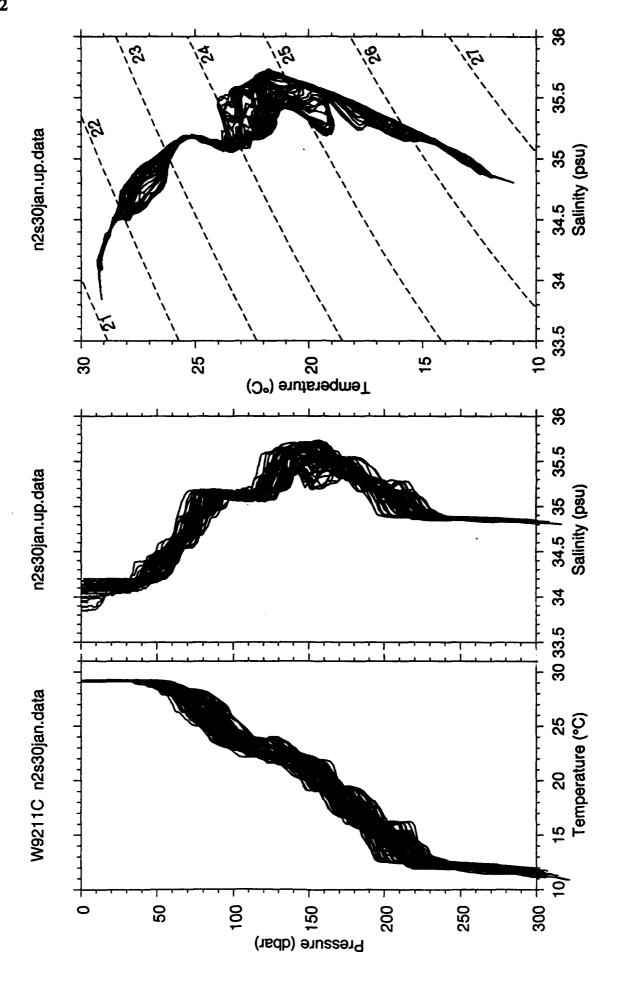
**ENSEMBLE PROFILES** 

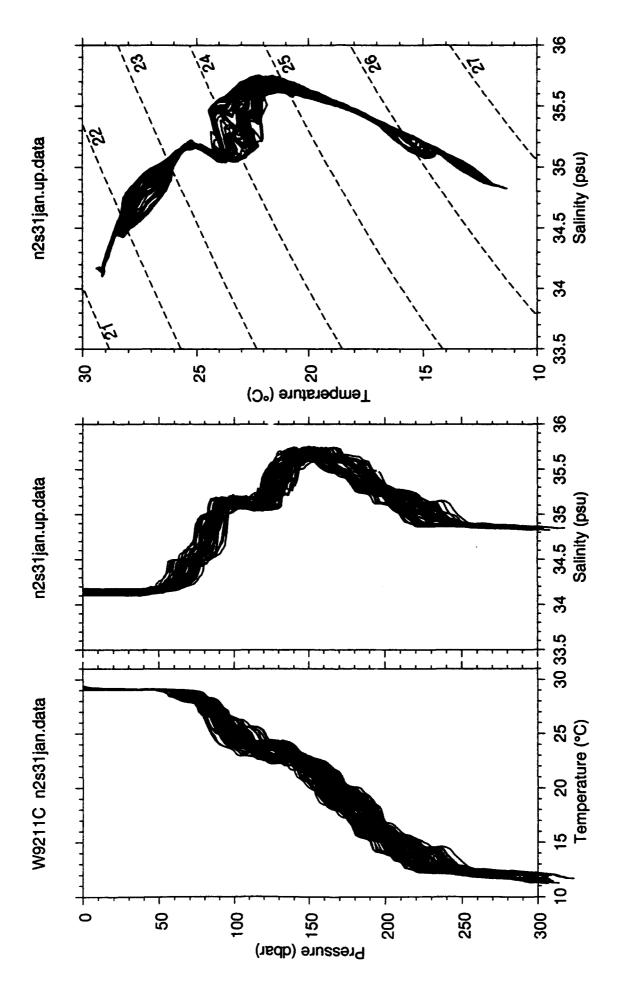
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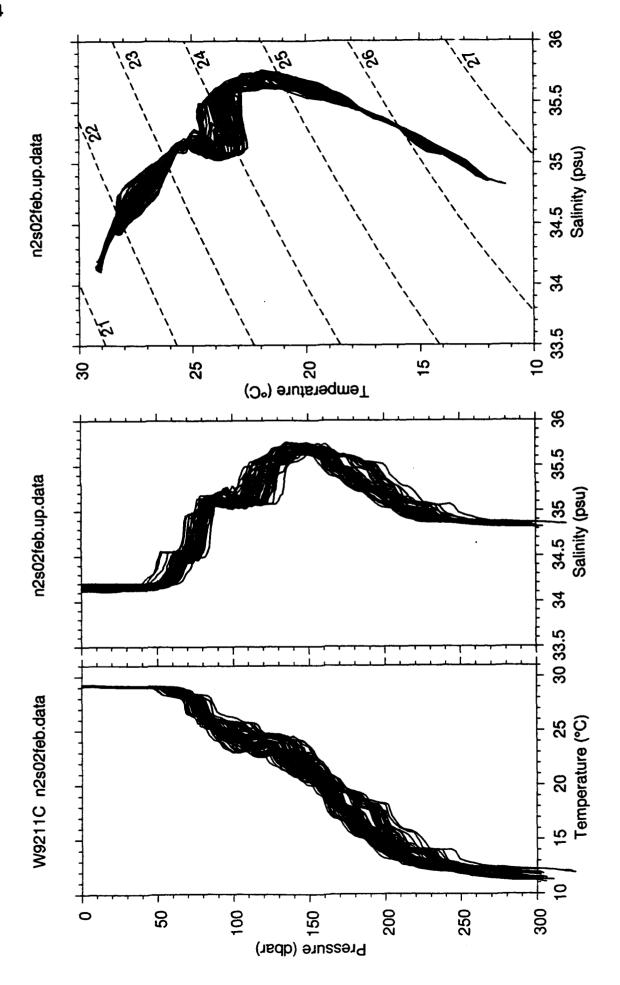
SEASOAR TEMPERATURE AND SALINITY

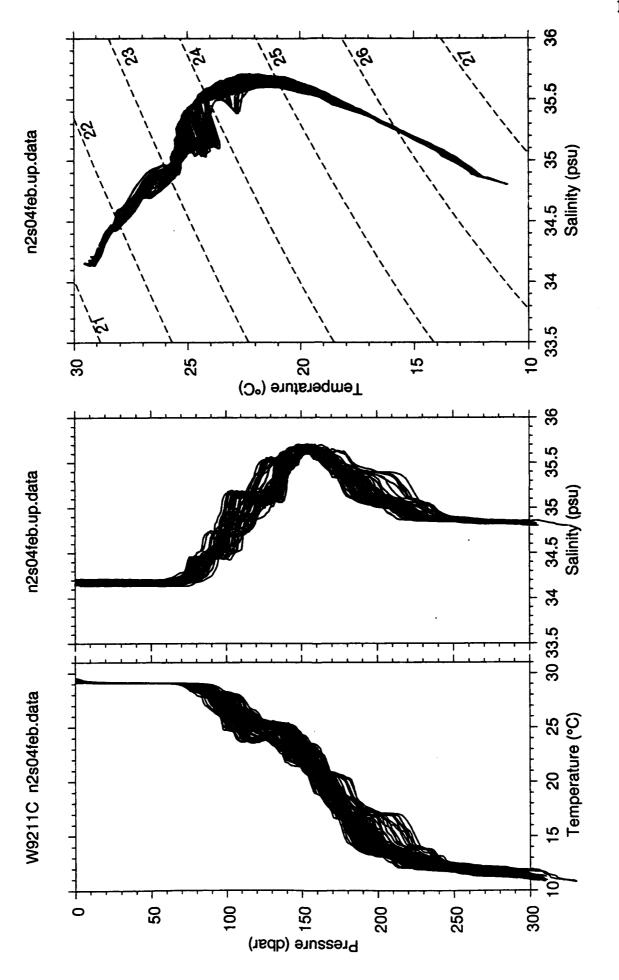


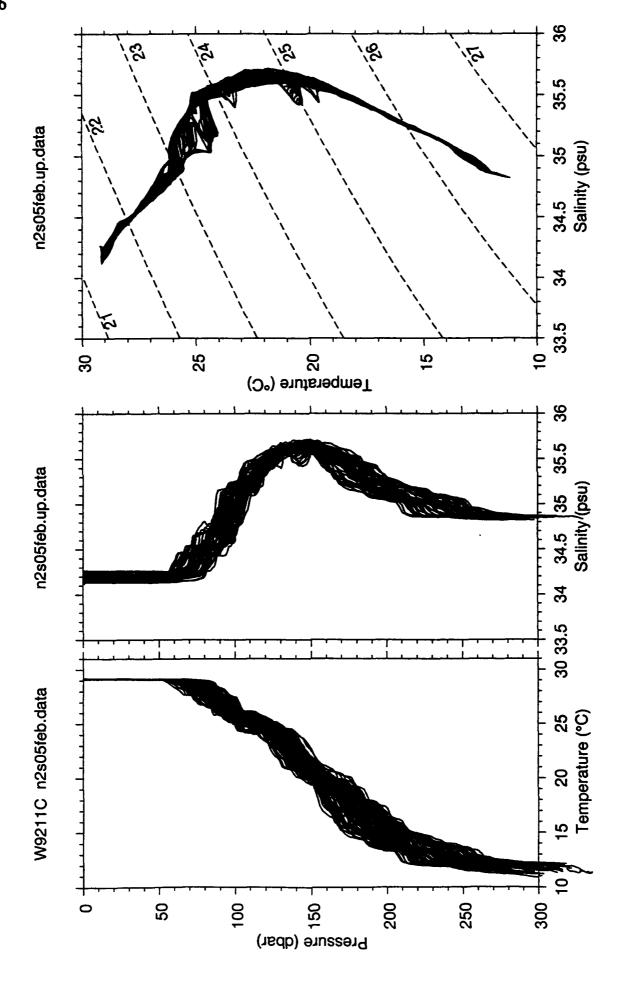


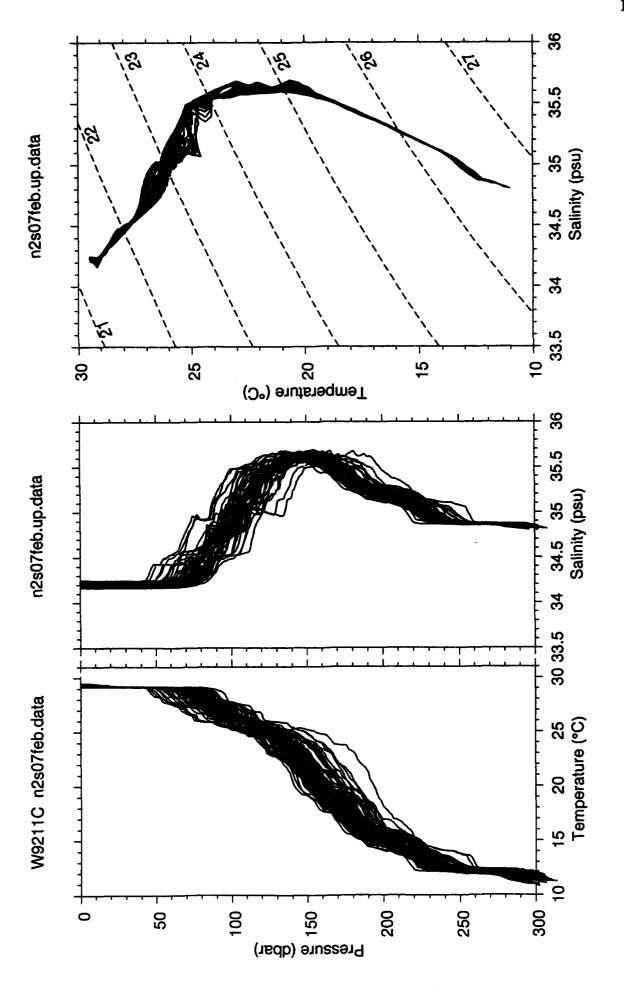


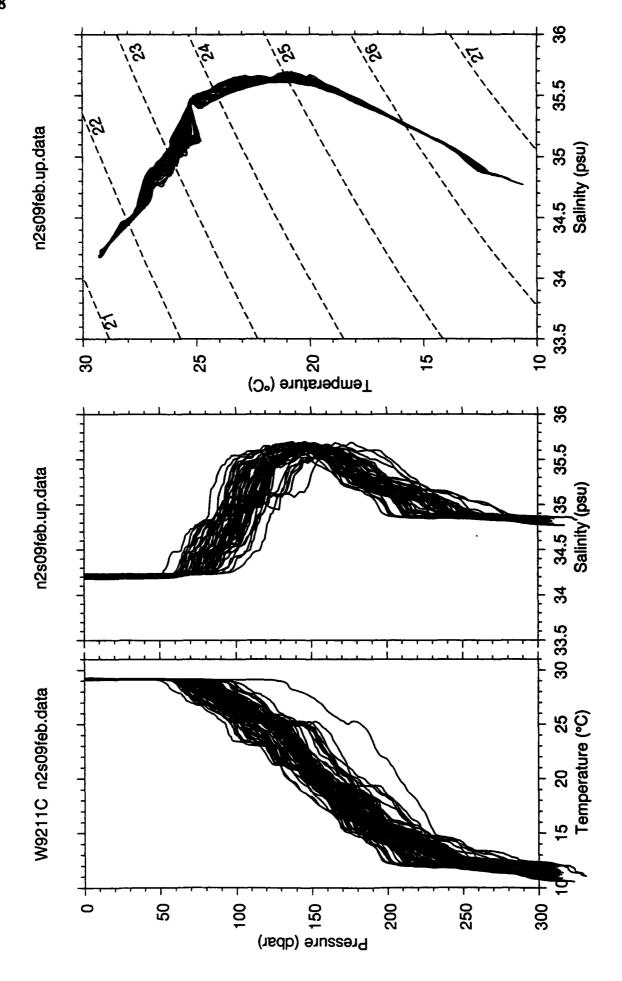


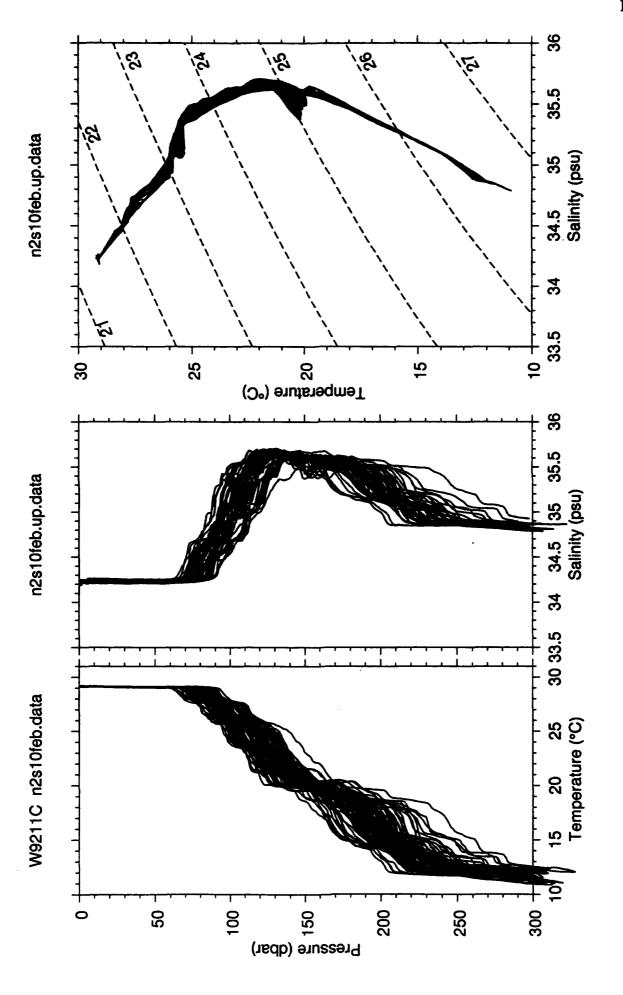


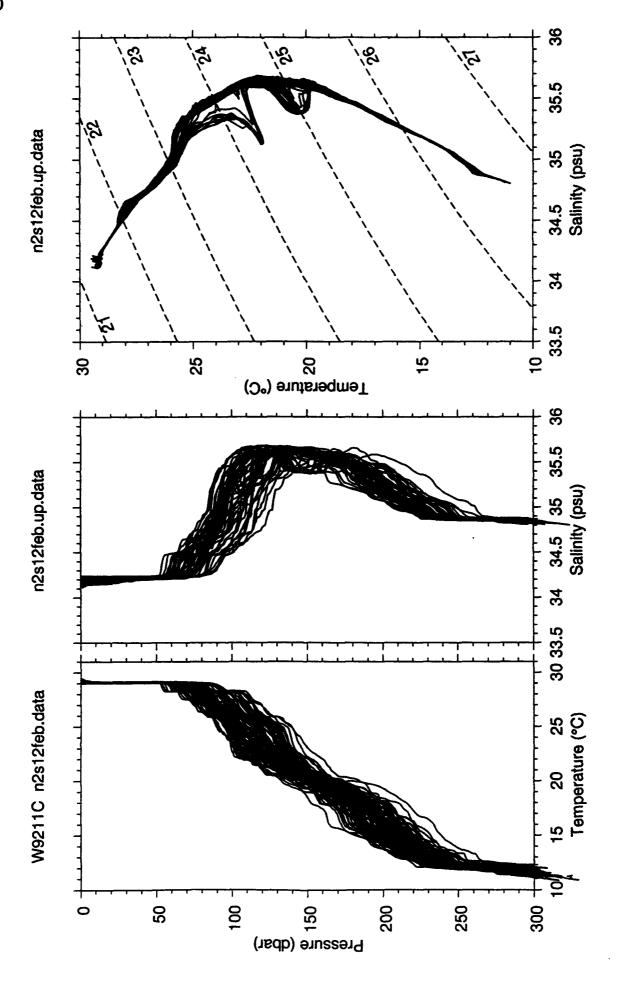


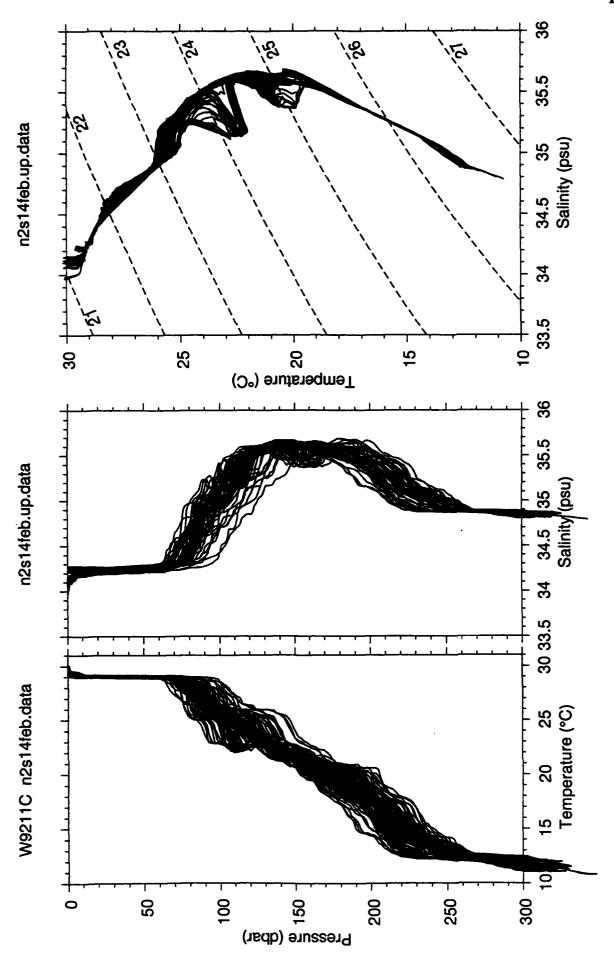


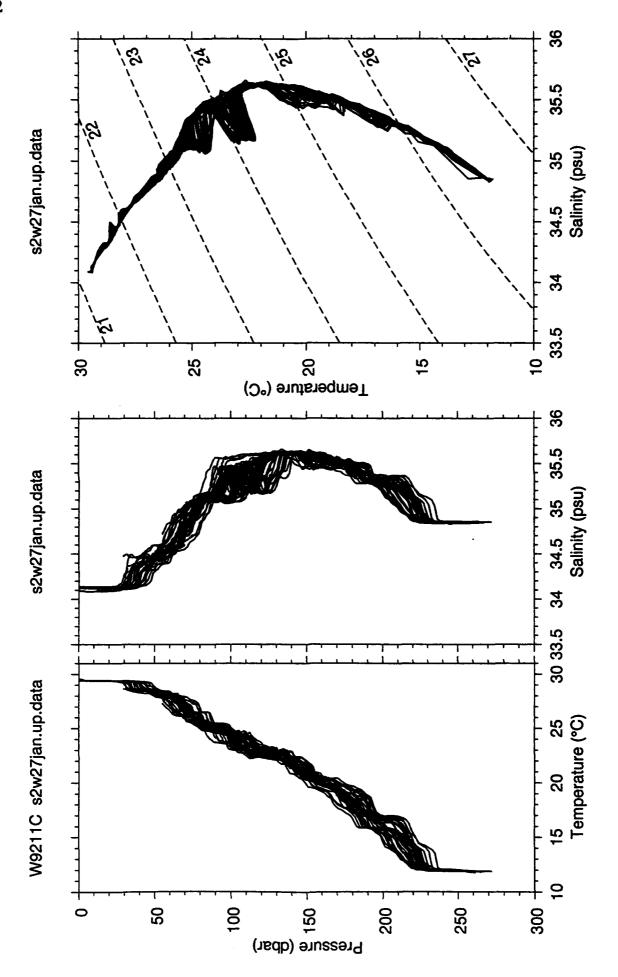


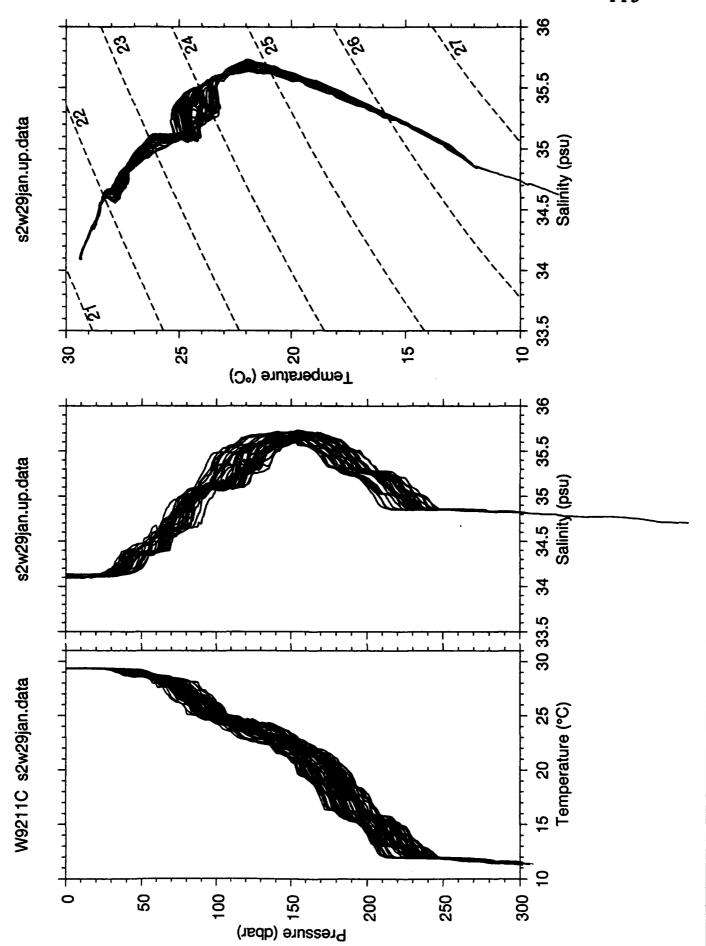


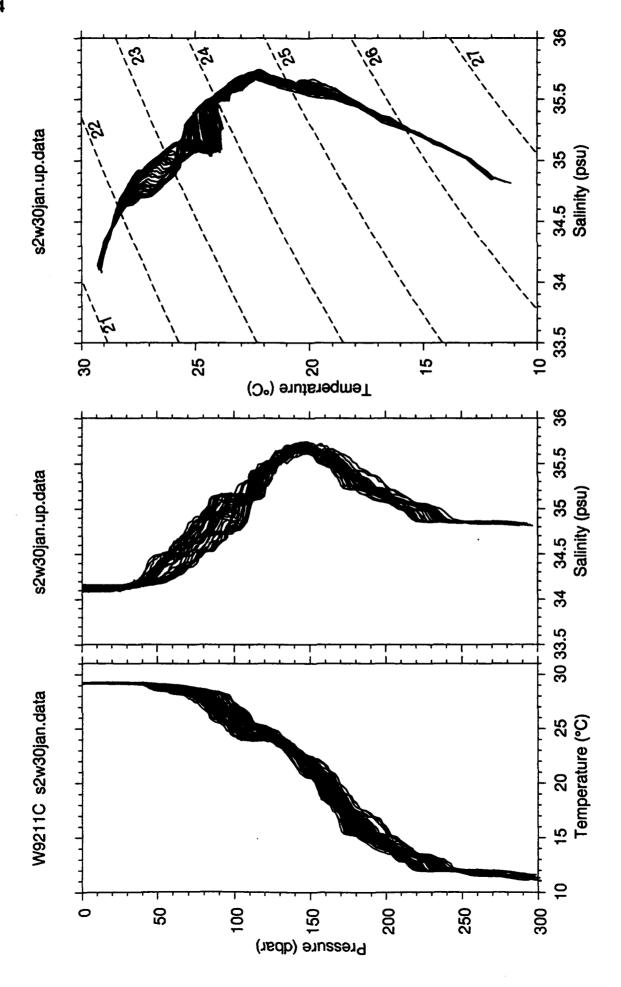


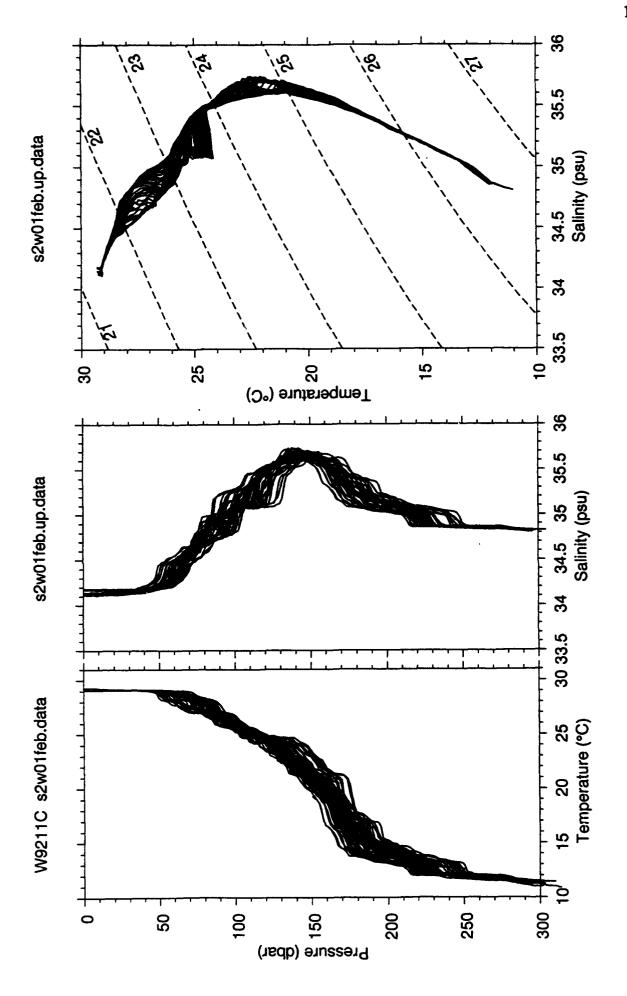


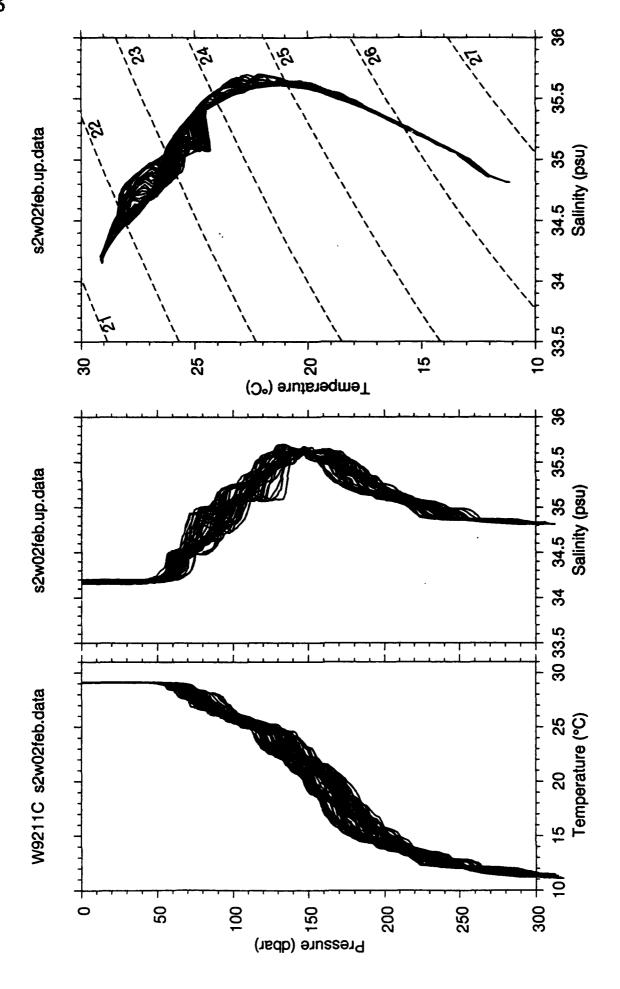


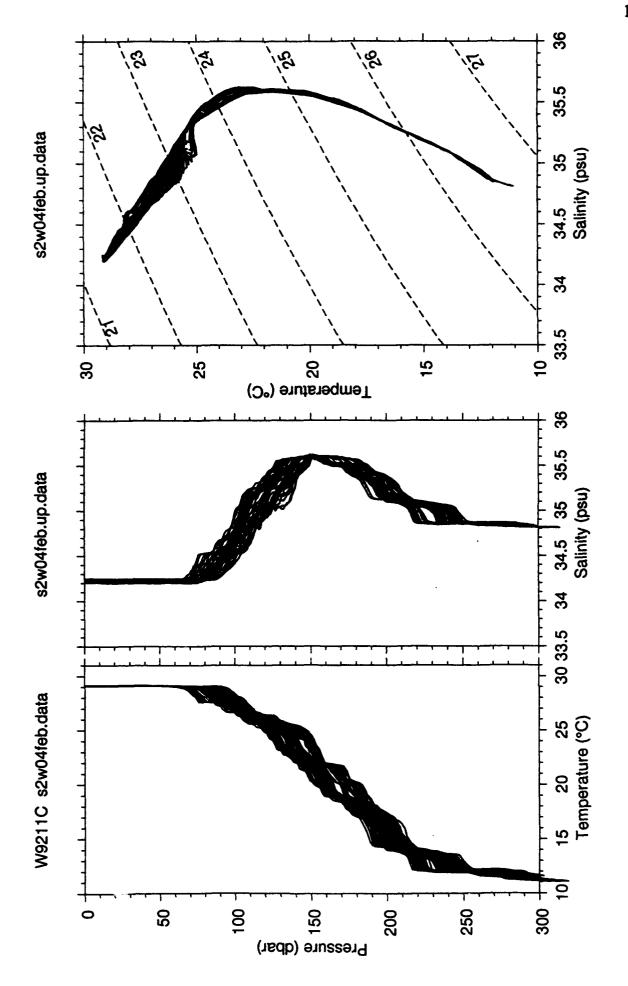


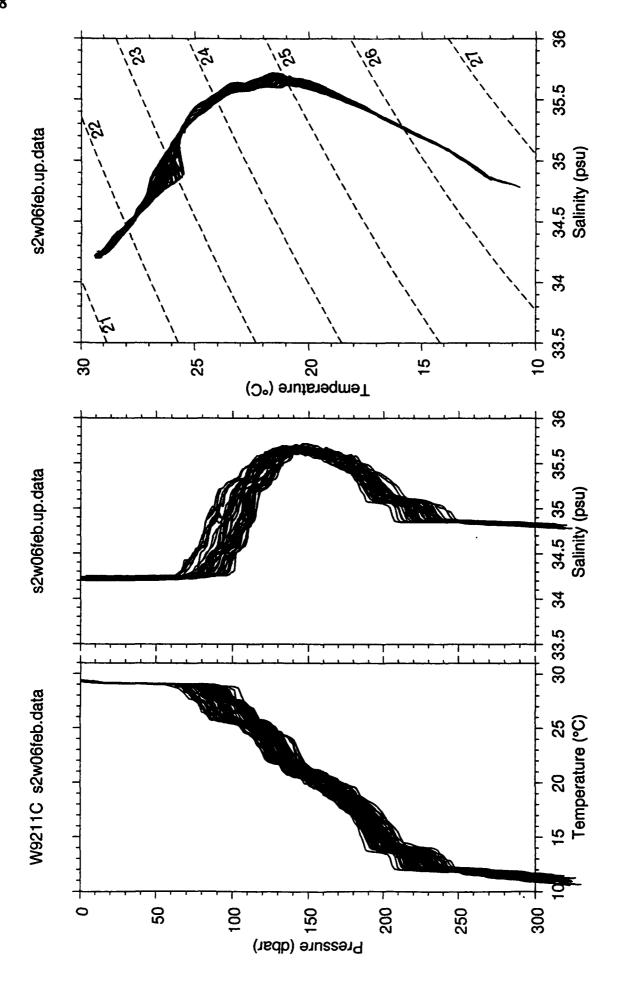


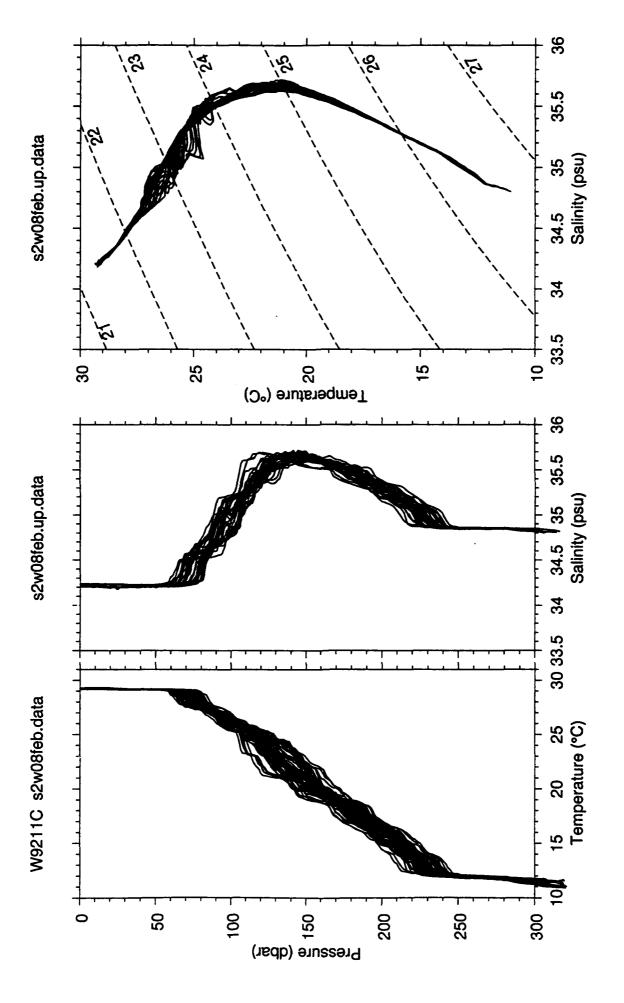


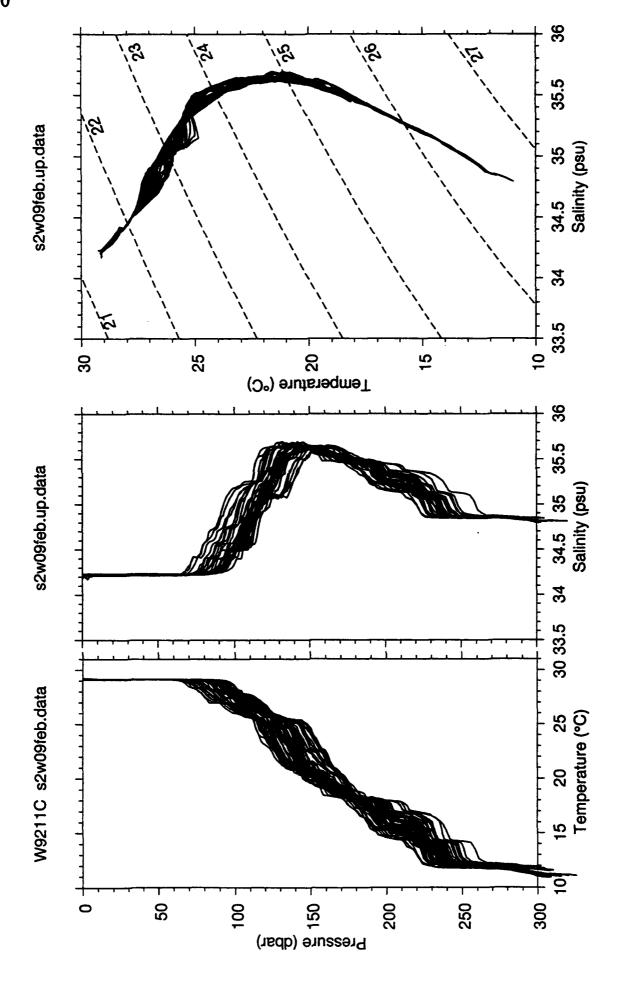


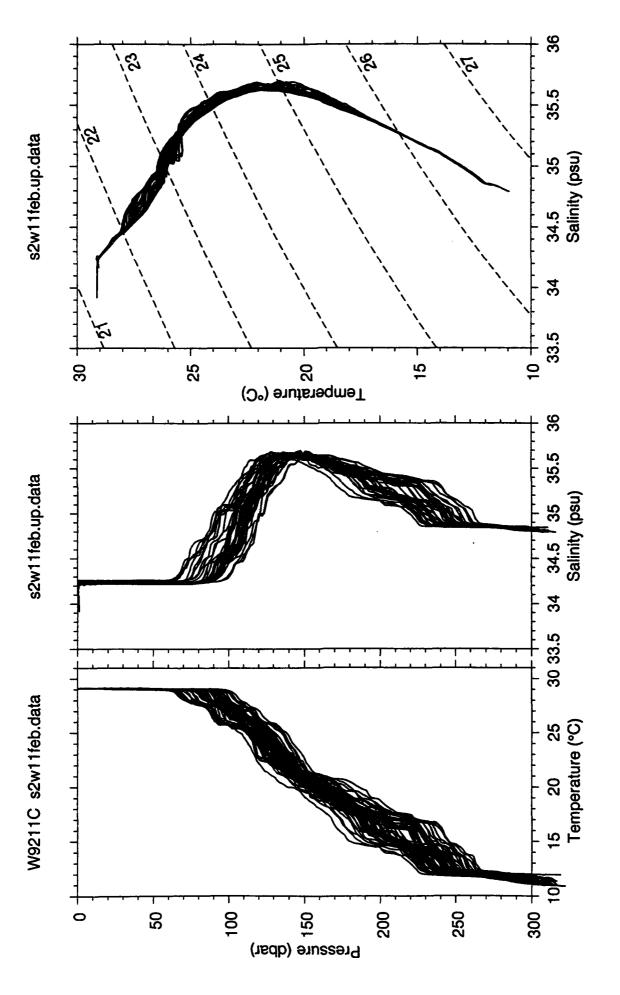


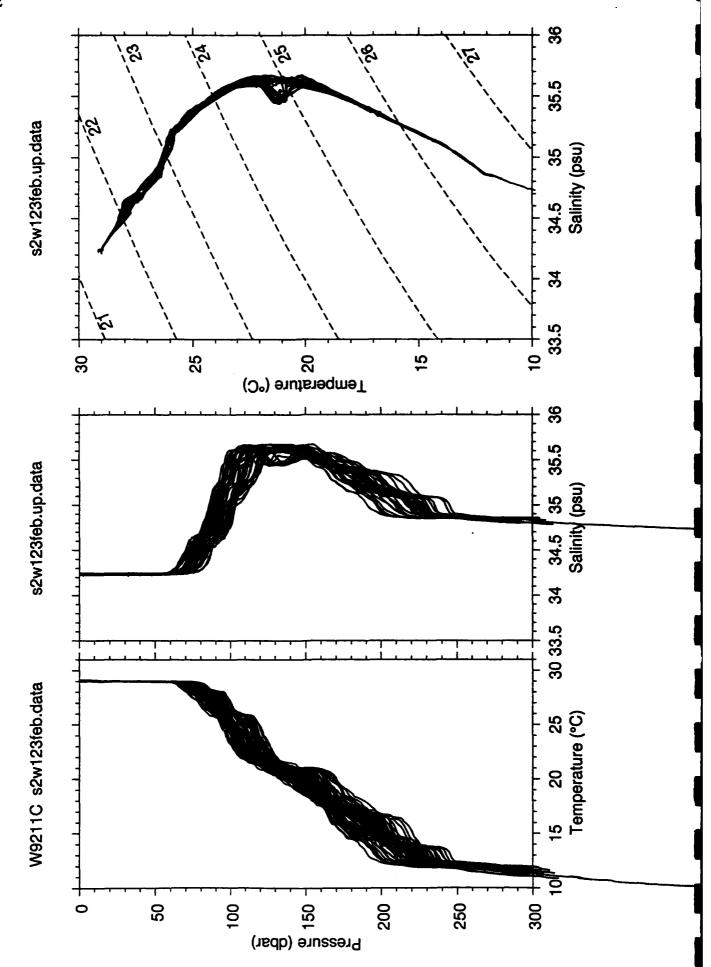


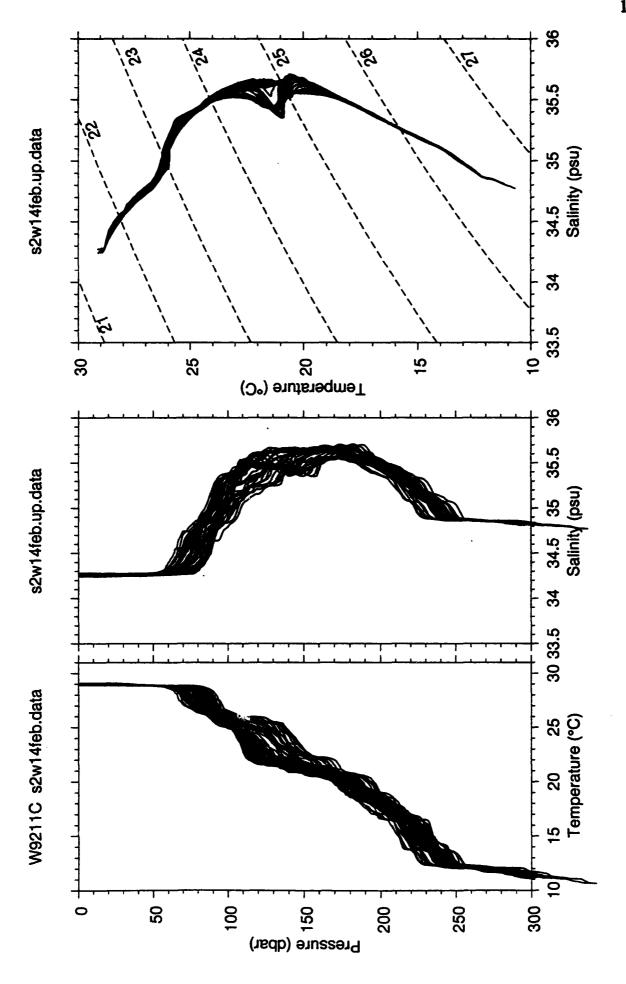


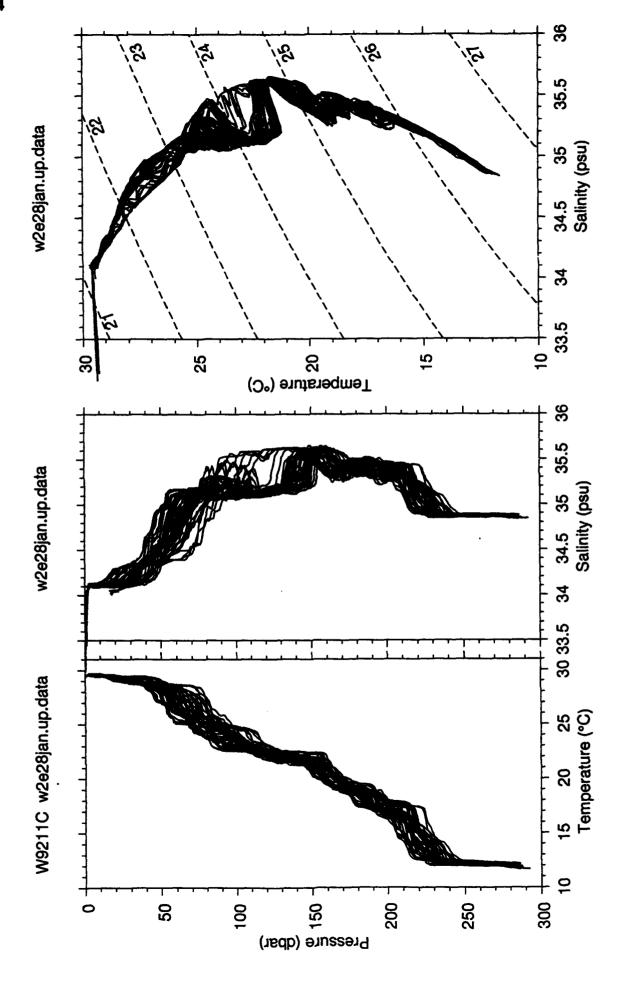


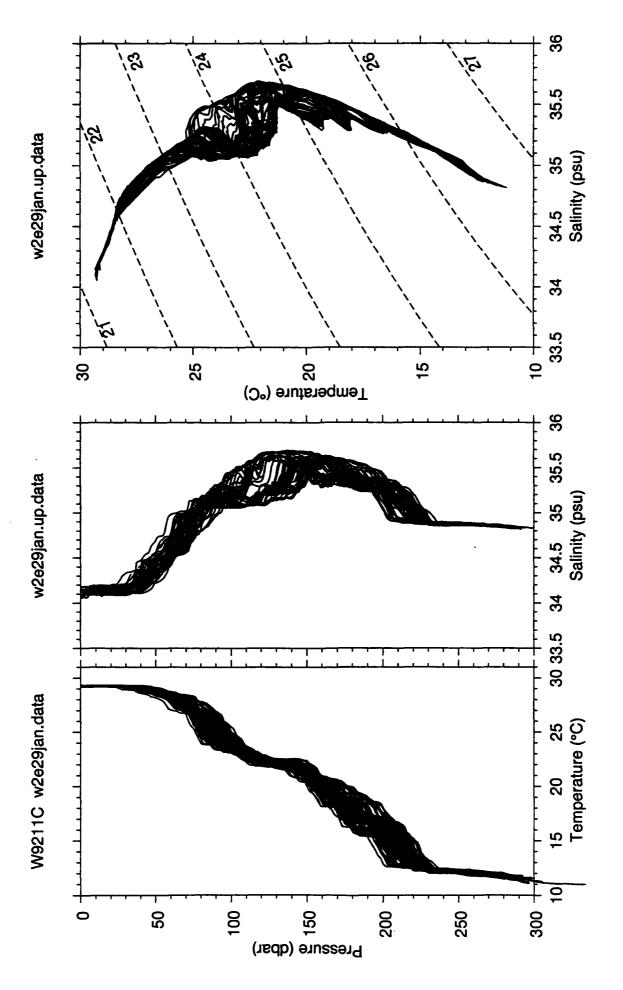


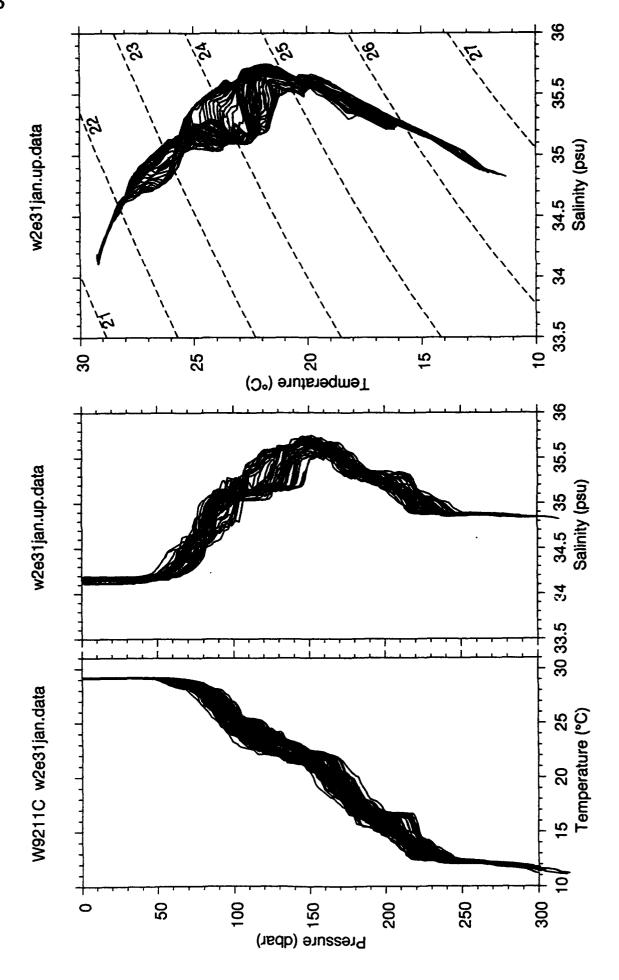


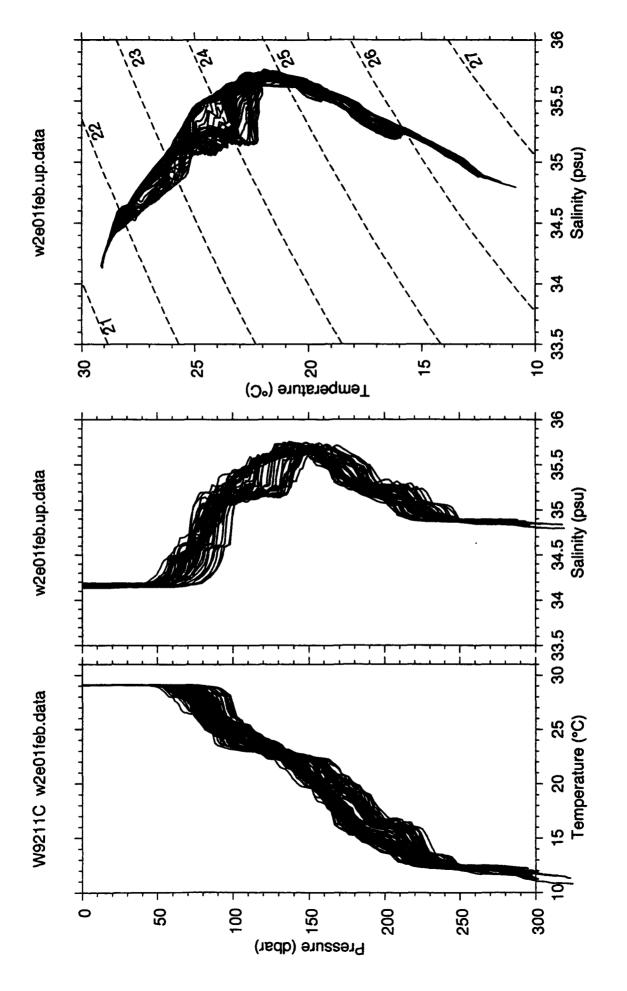


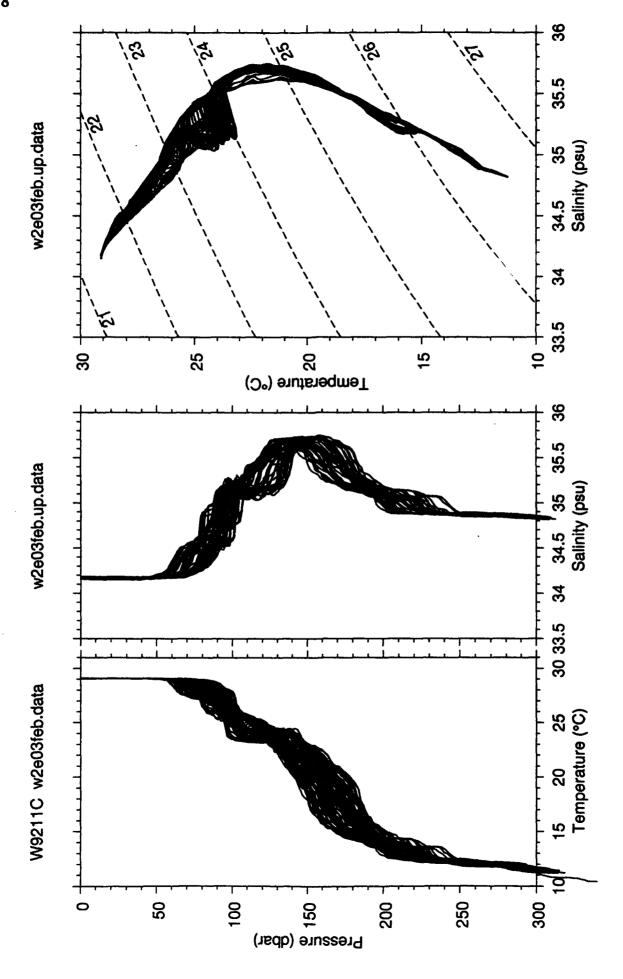


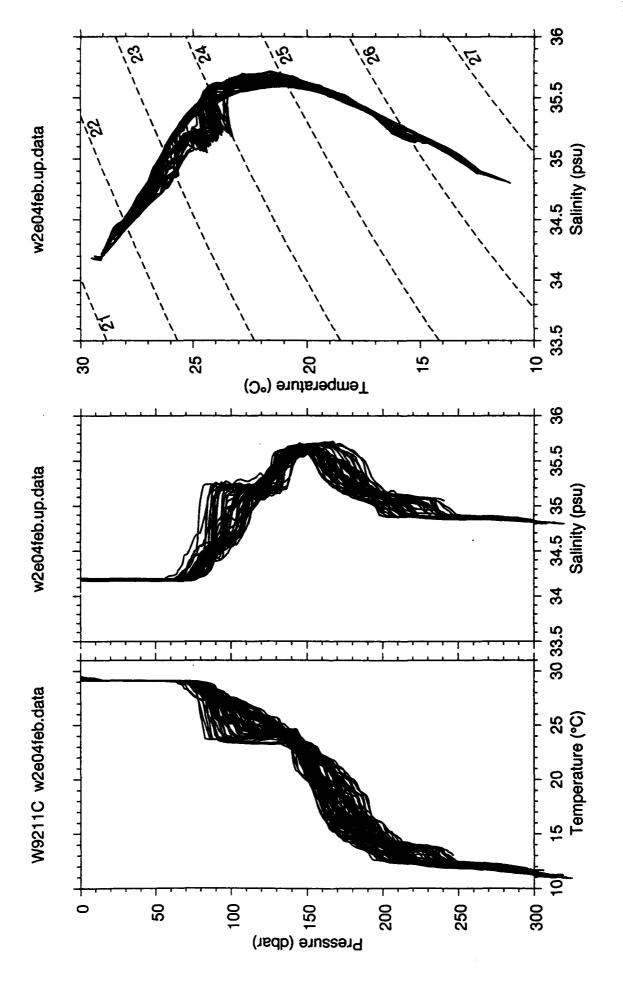


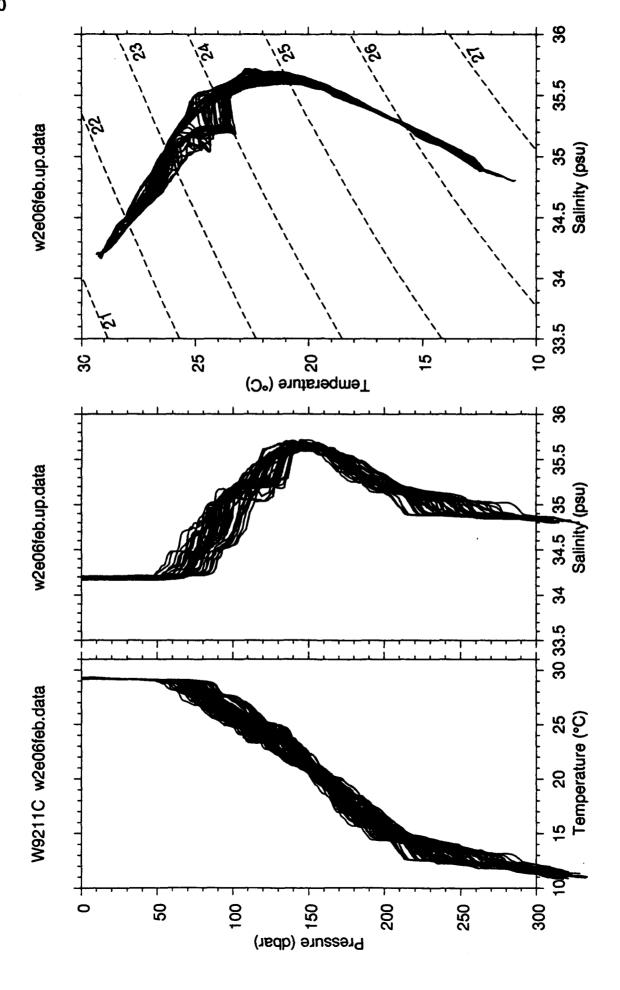


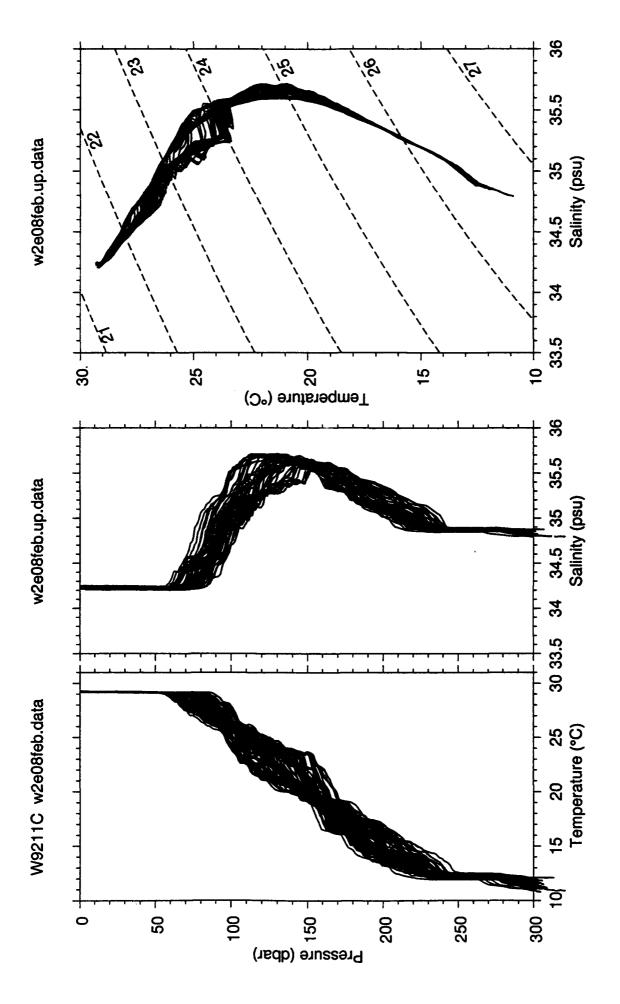


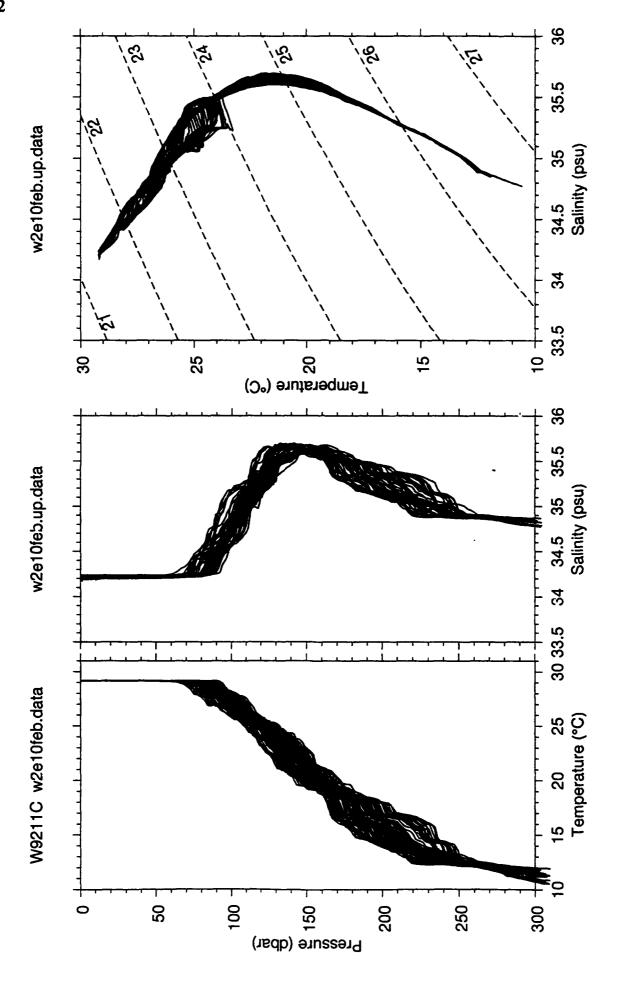


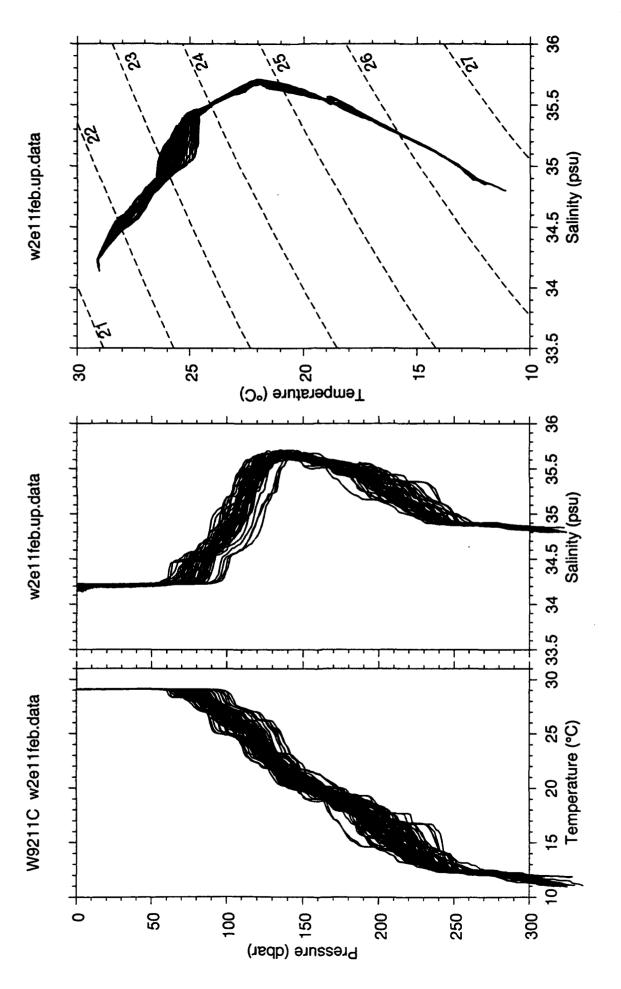


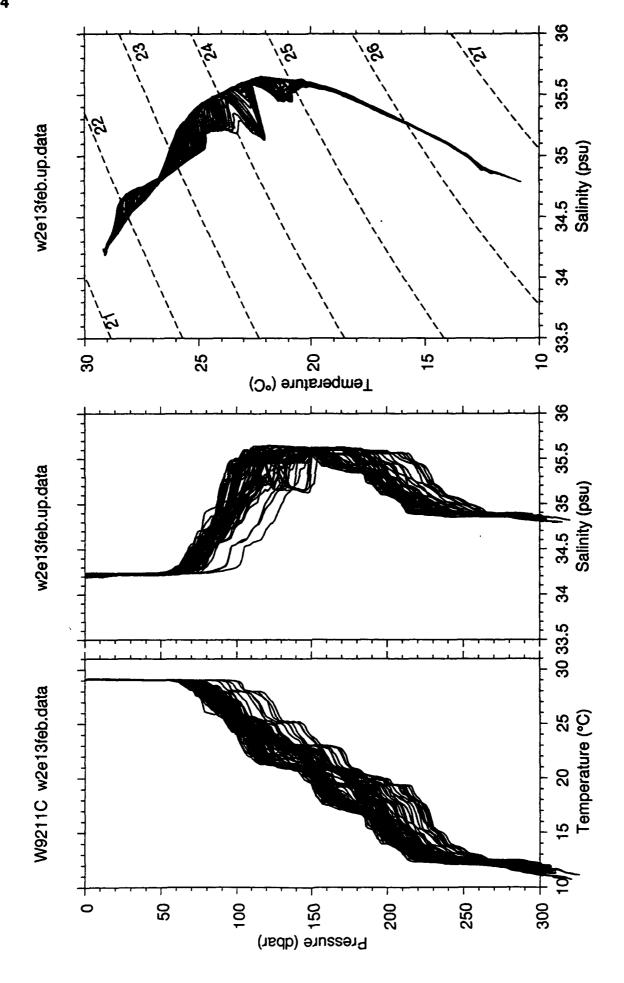


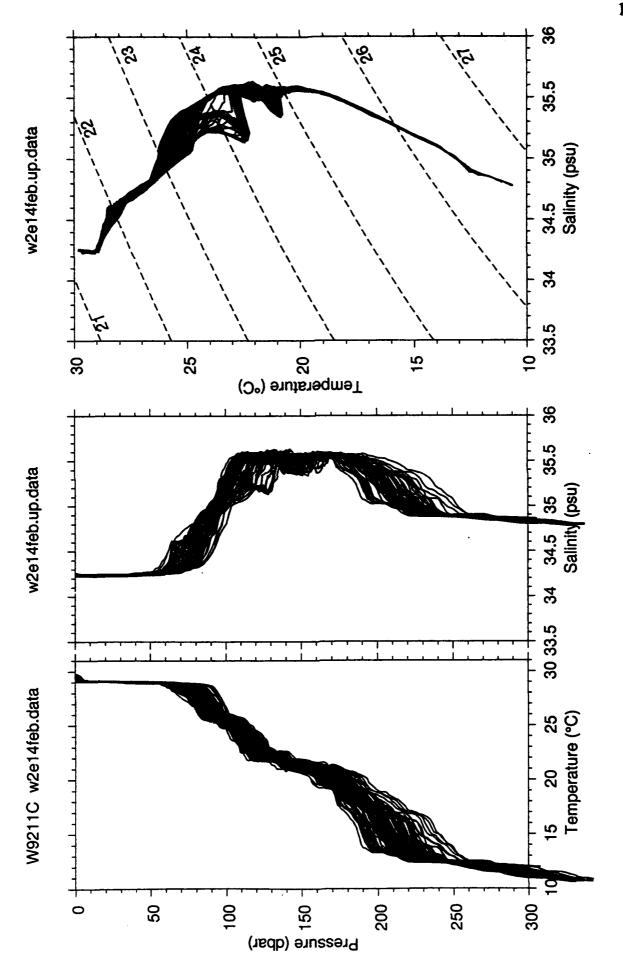


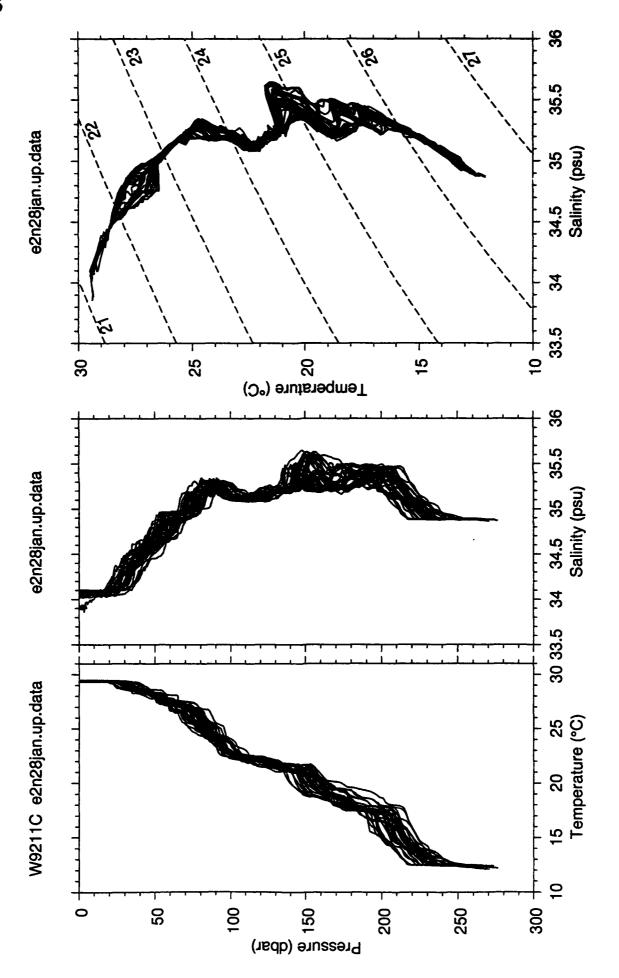


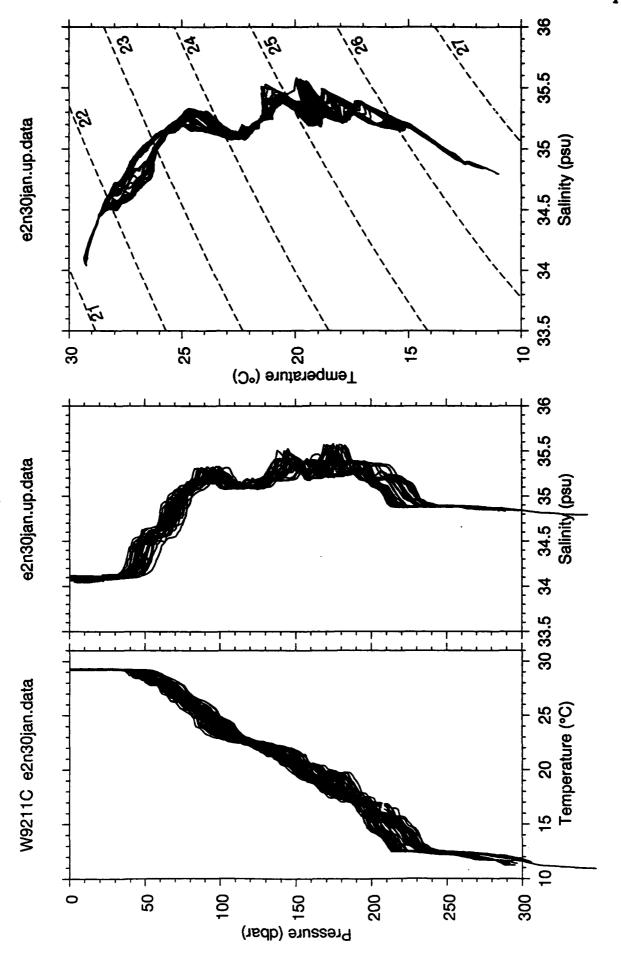


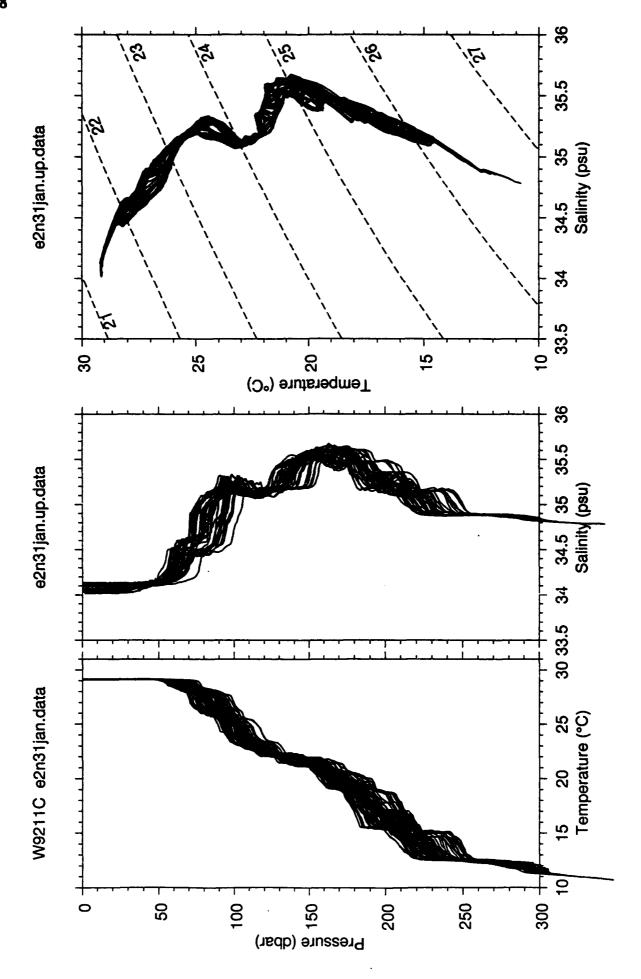


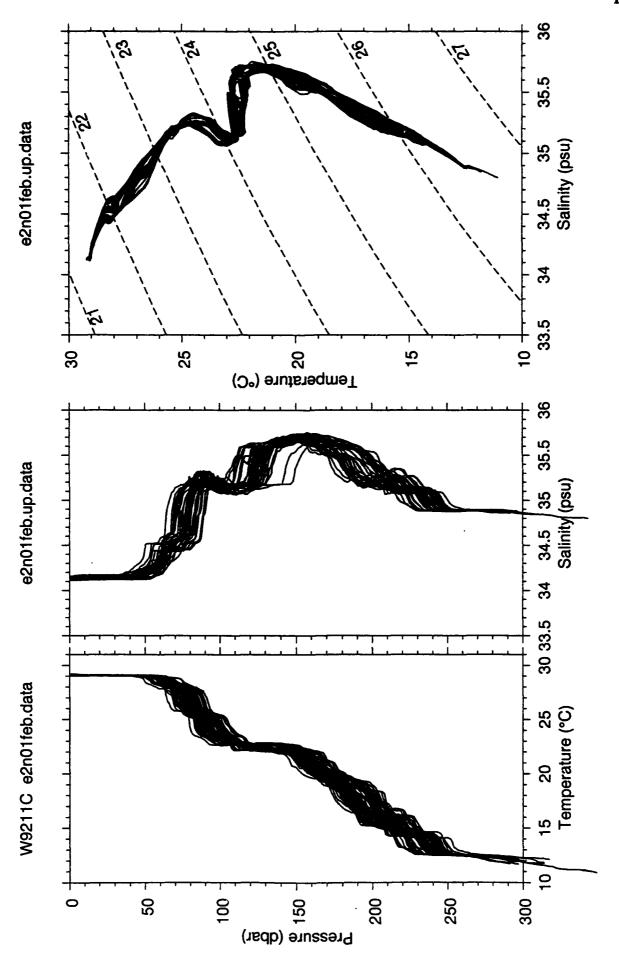


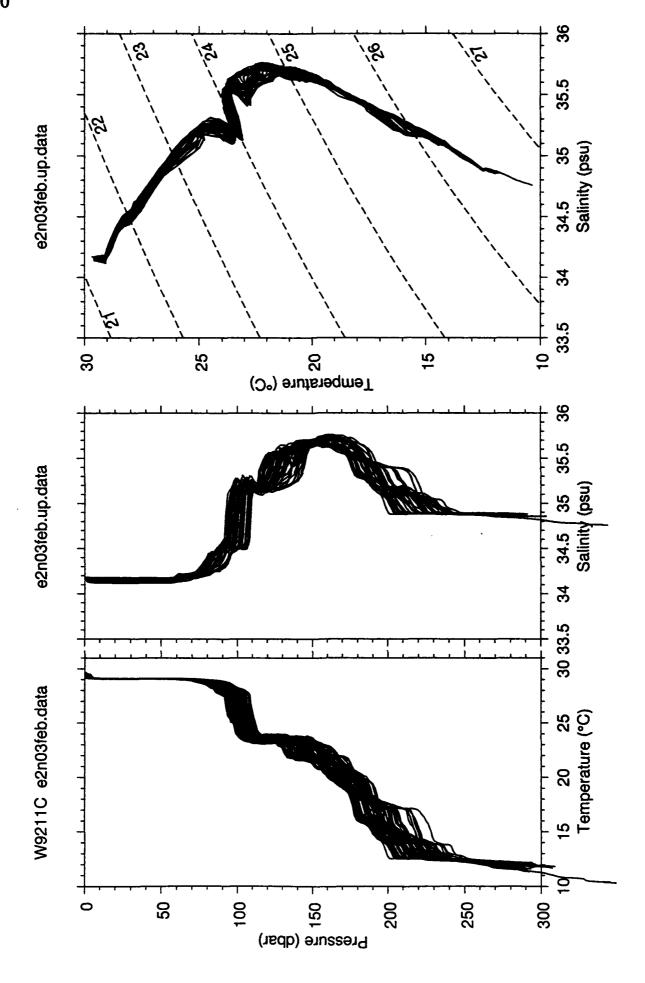


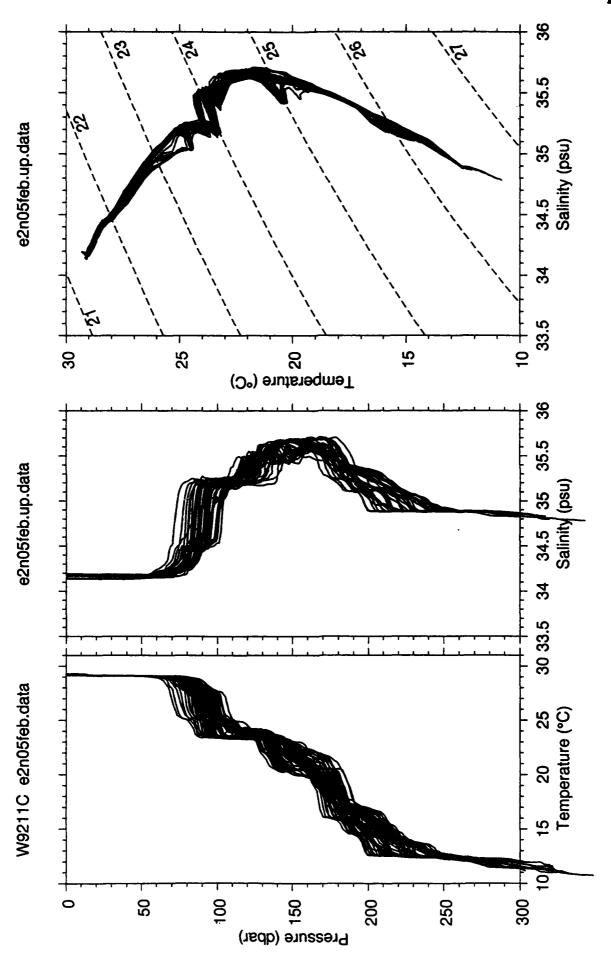


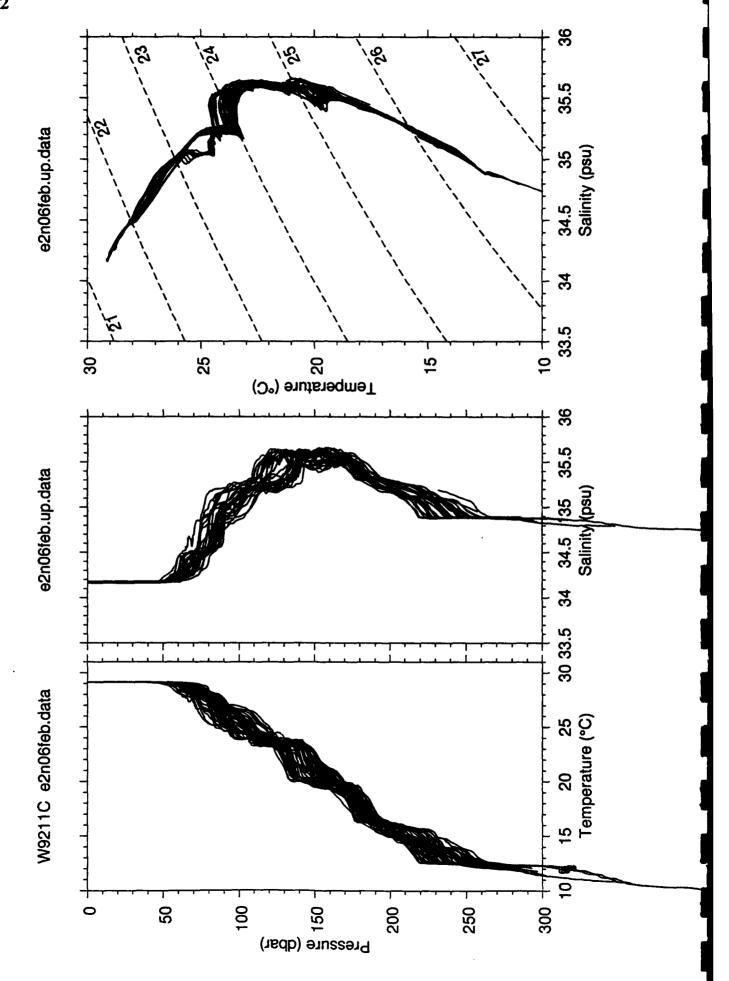


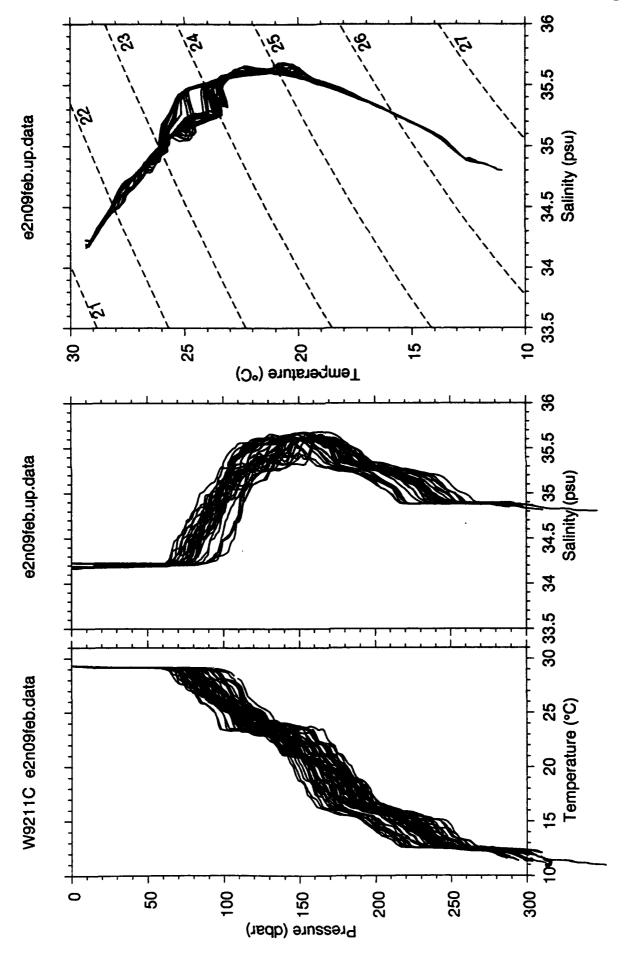


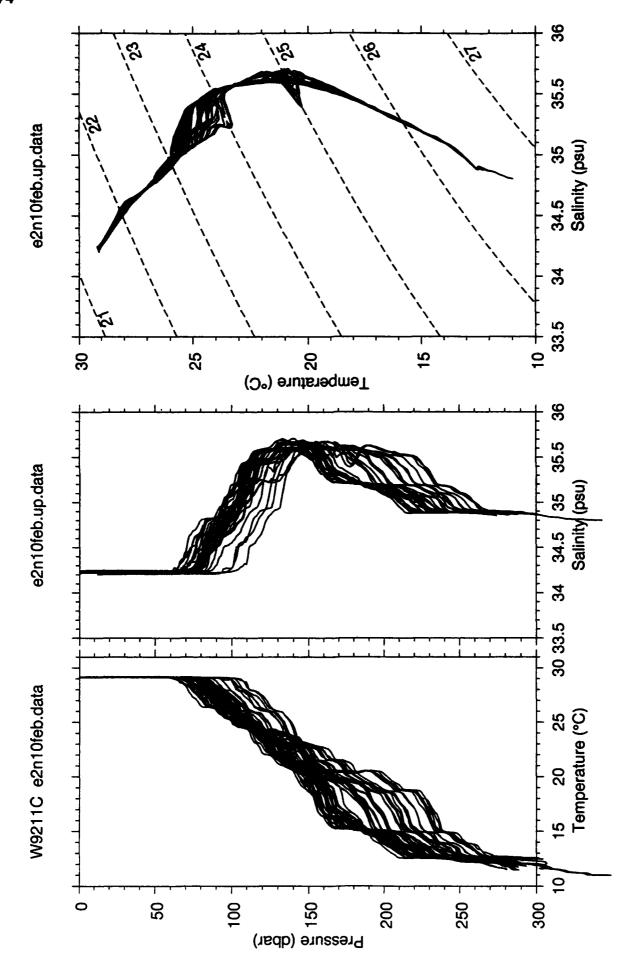


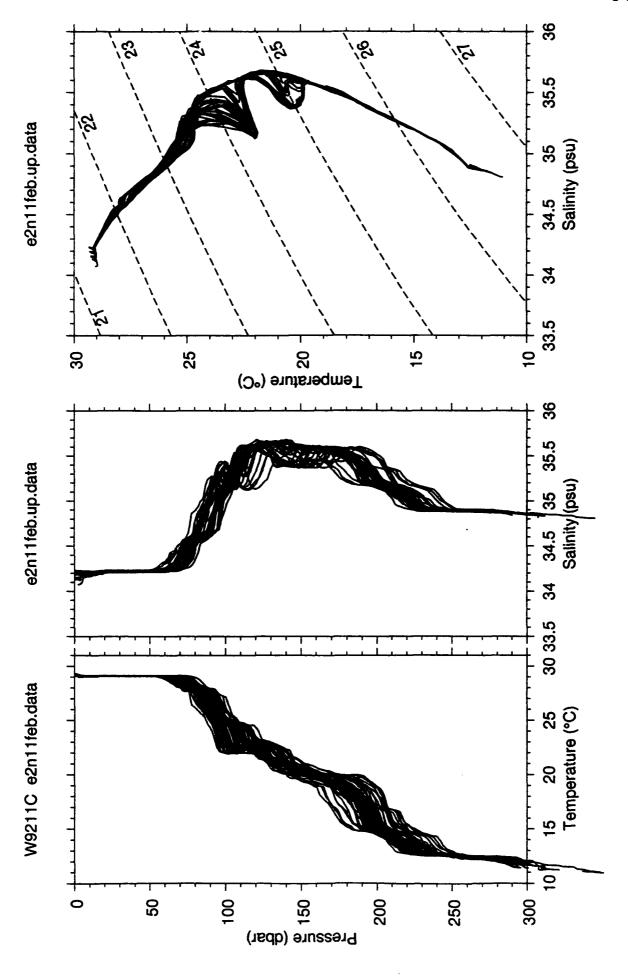


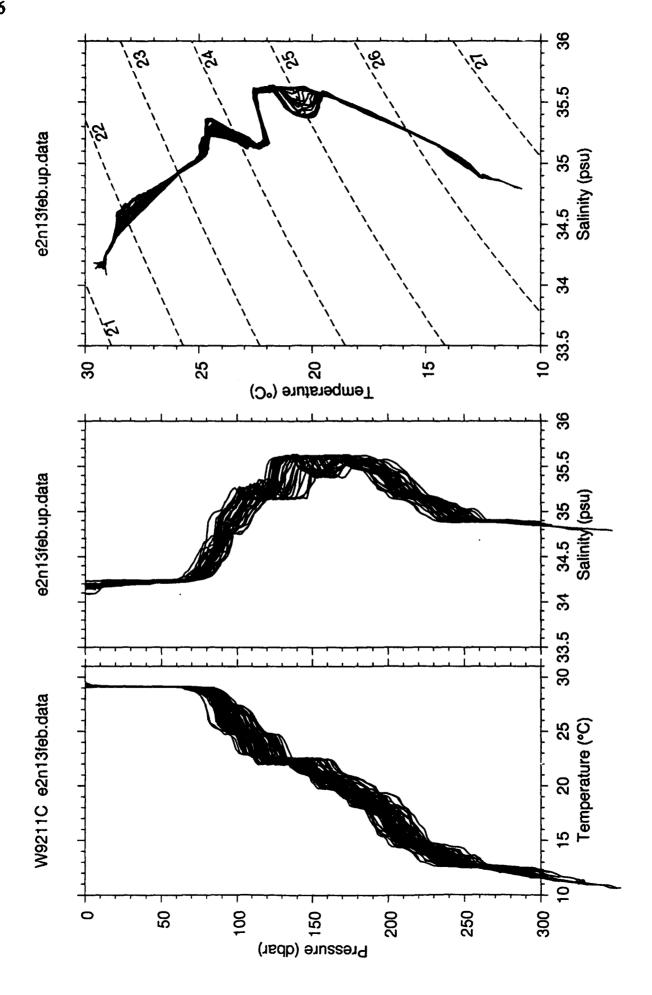


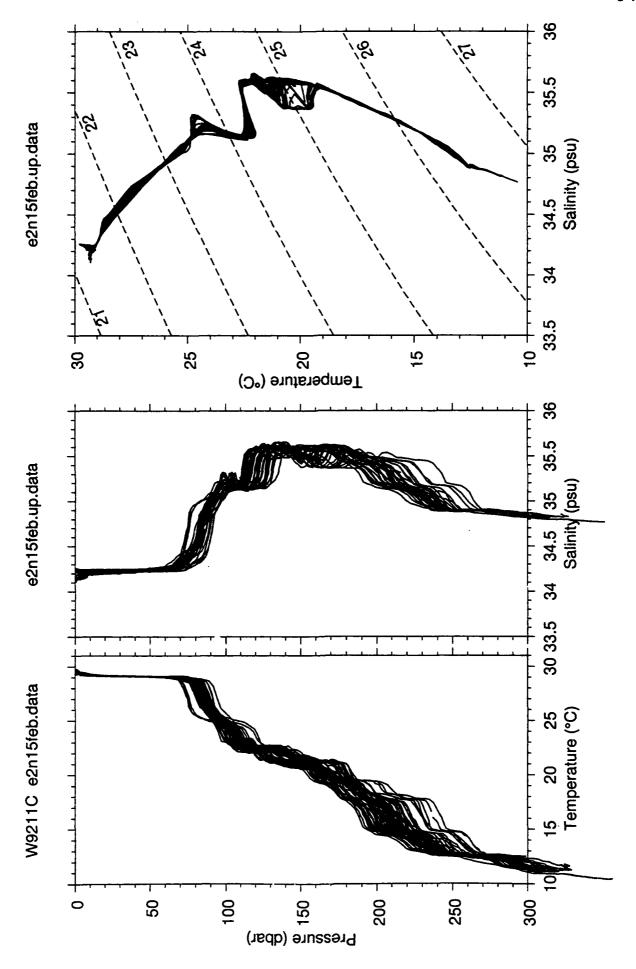


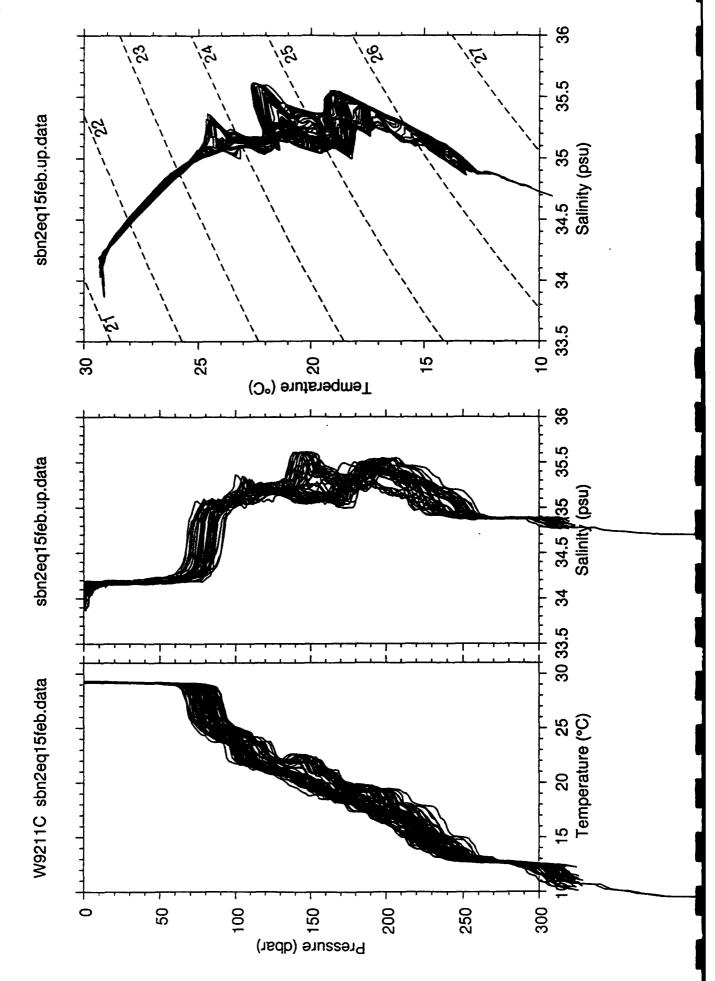








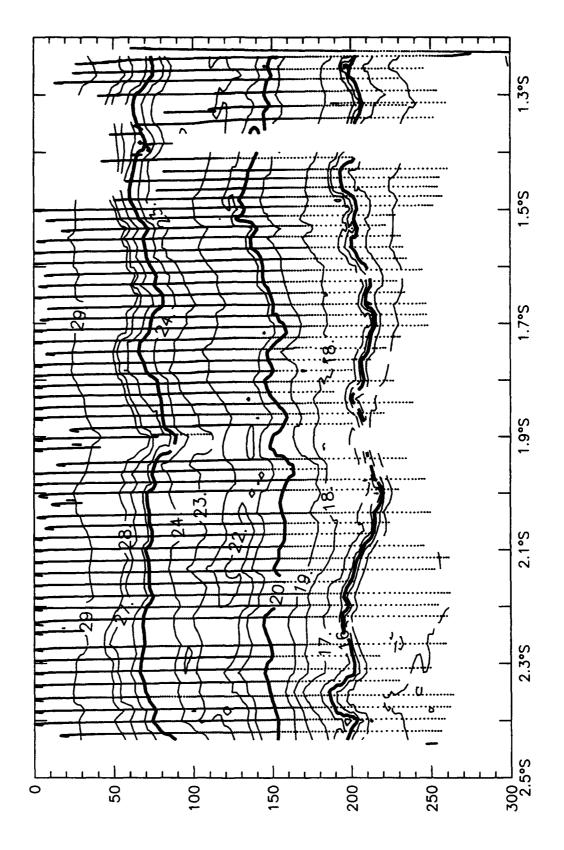




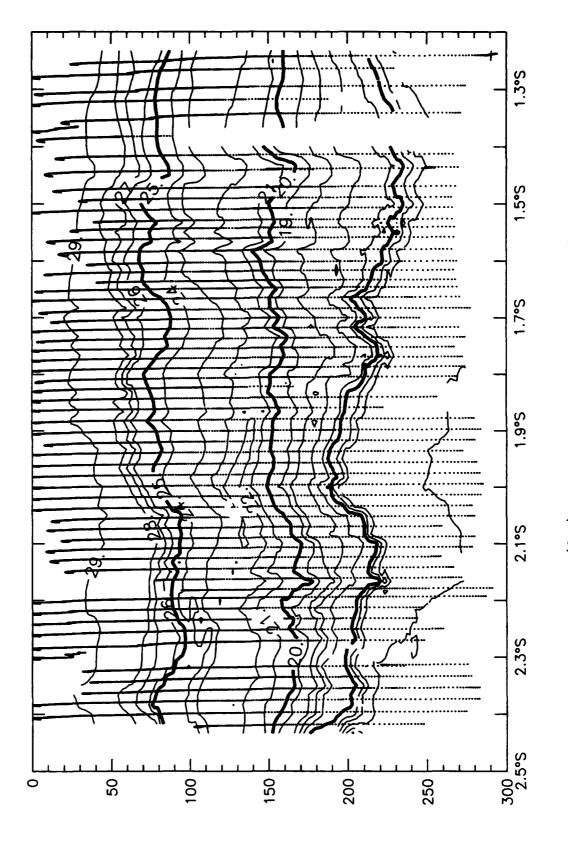
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OF

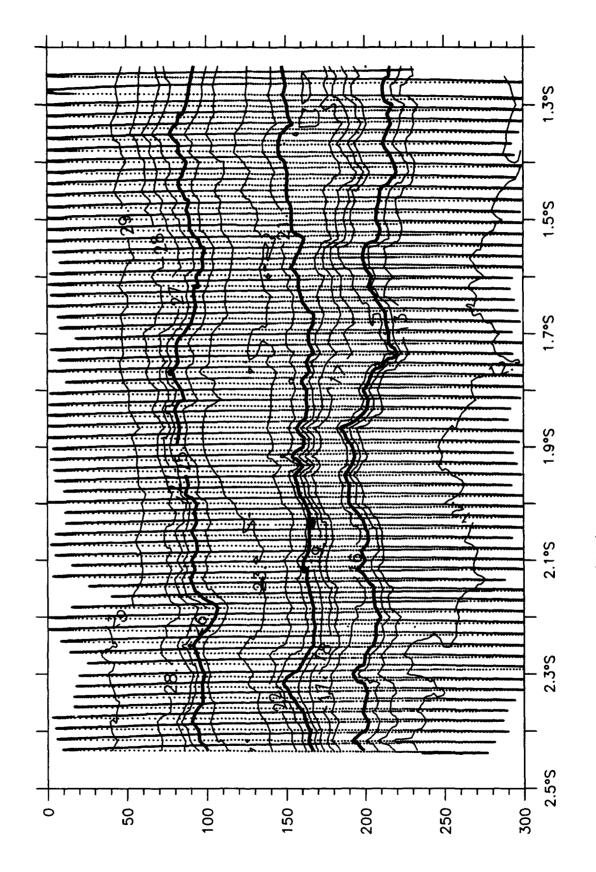
TEMPERATURE, SALINITY AND SIGMA-T



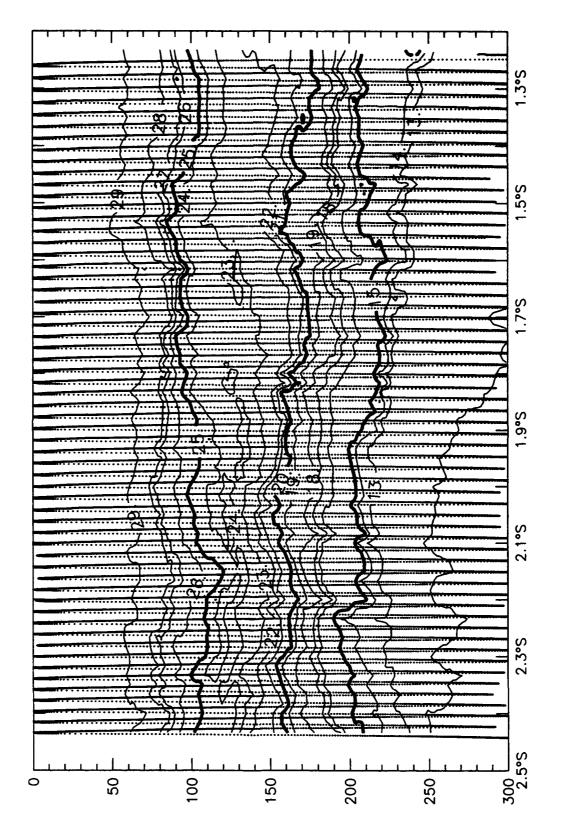
T(°C), N2S, 27 January 1993



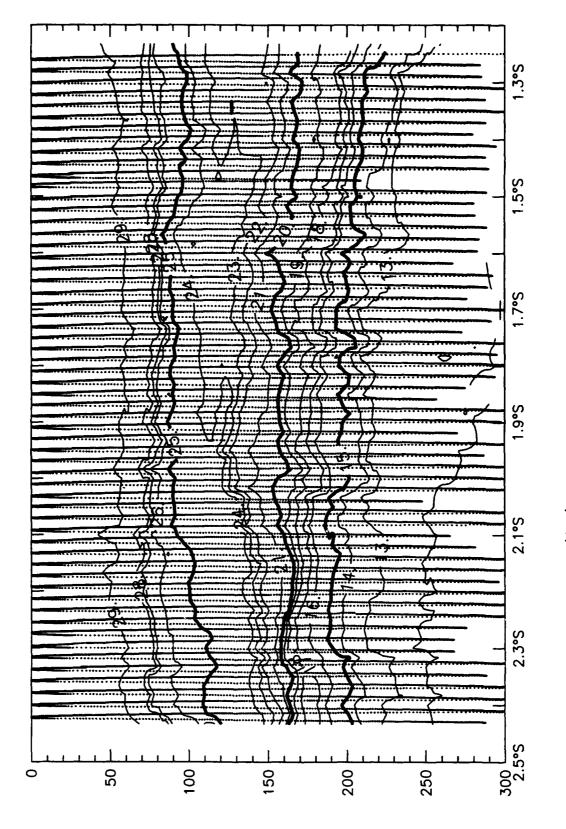
T(°C), N2S, 28 January 1993



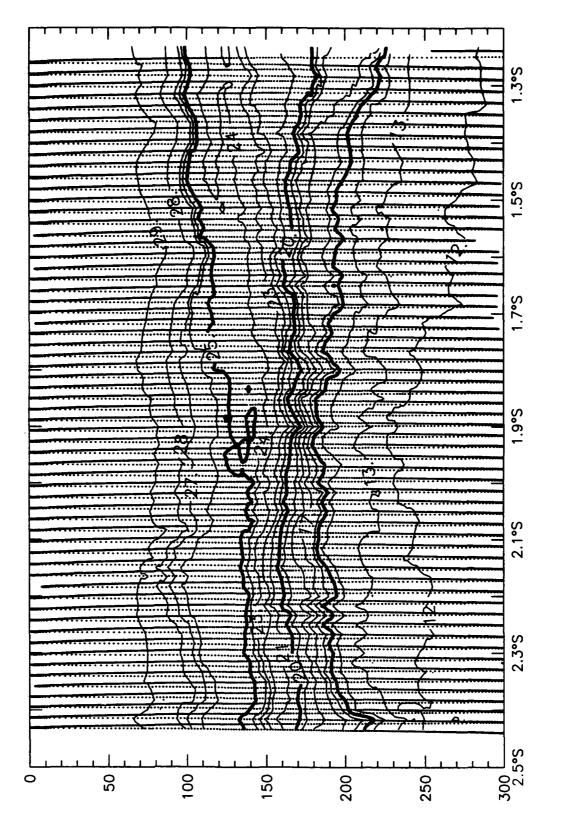
T(°C), N2S, 30 January 1993



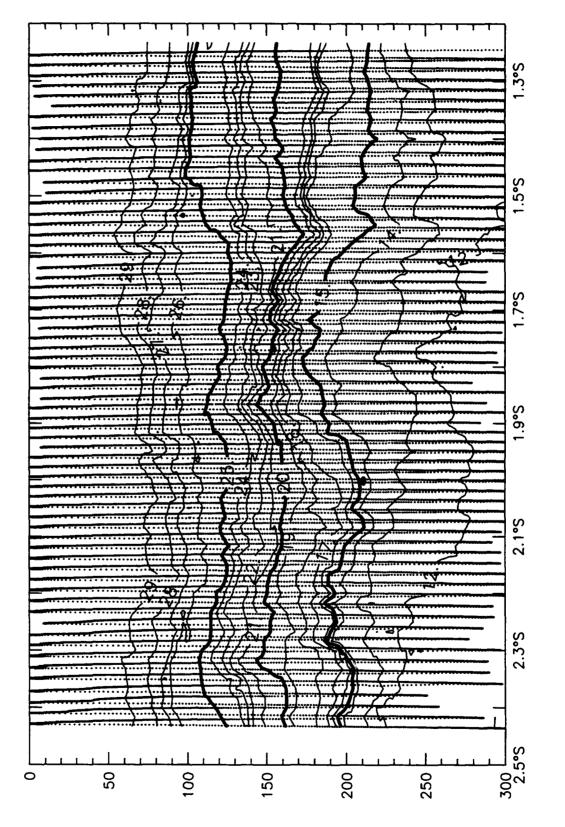
T(°C), N2S, 31 January 1993



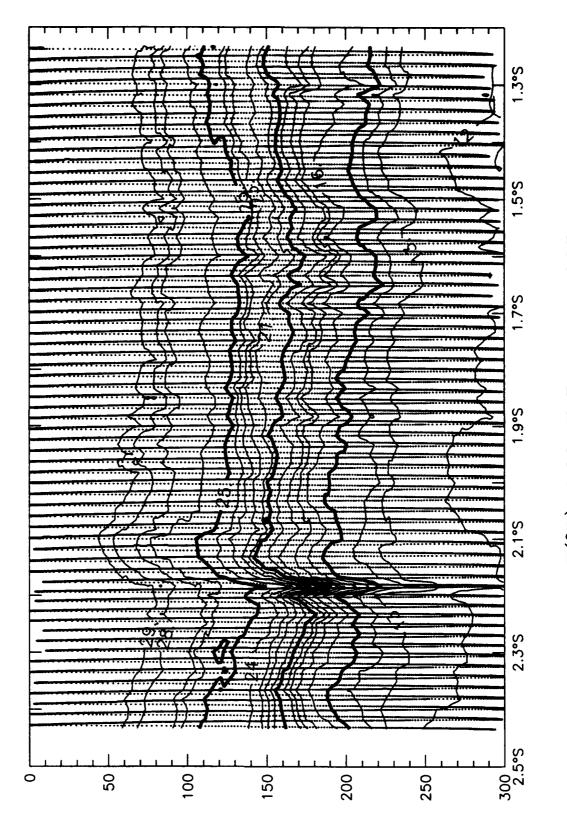
T(°C), N2S, 2 February 1993



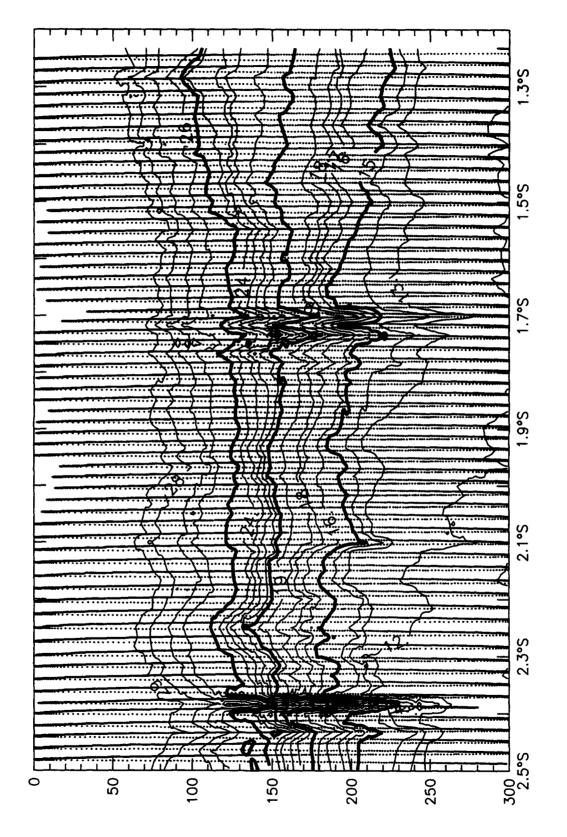
T(°C), N2S, 4 February 1993



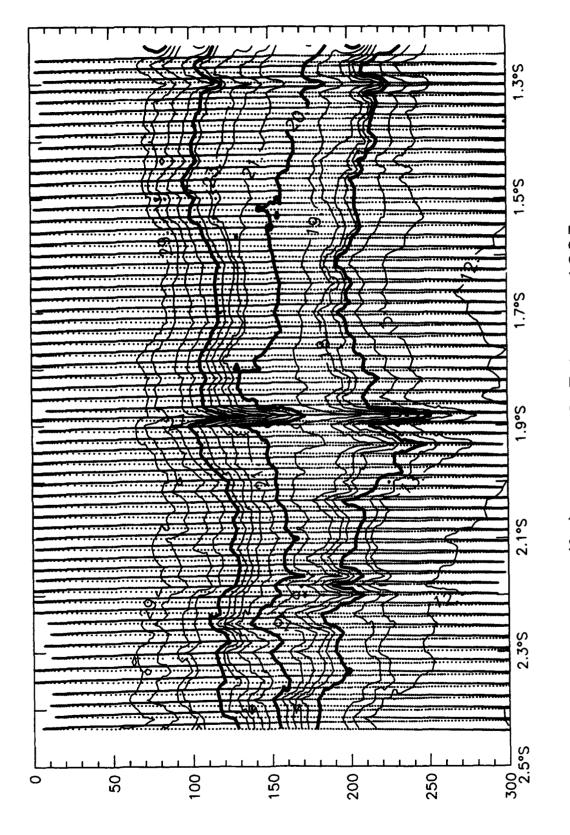
T(°C), N2S, 5 February 1993



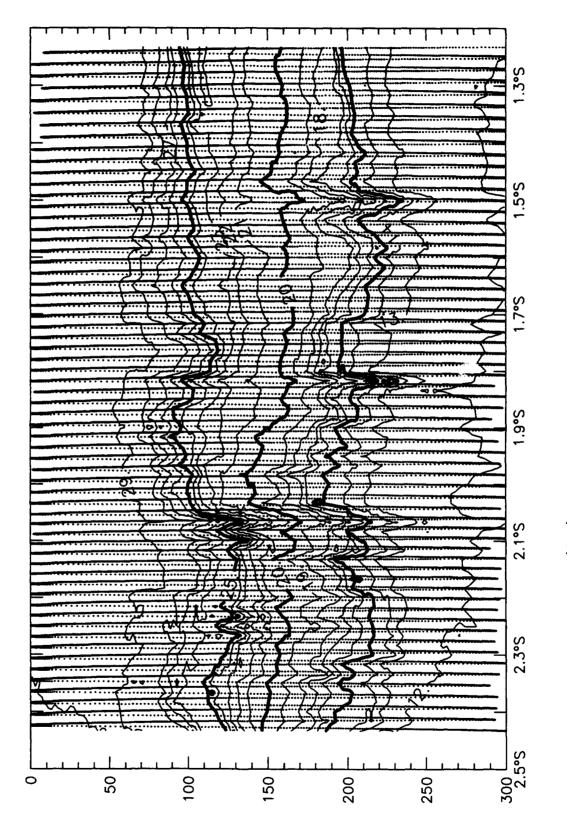
T(°C), N2S, 7 February 1993



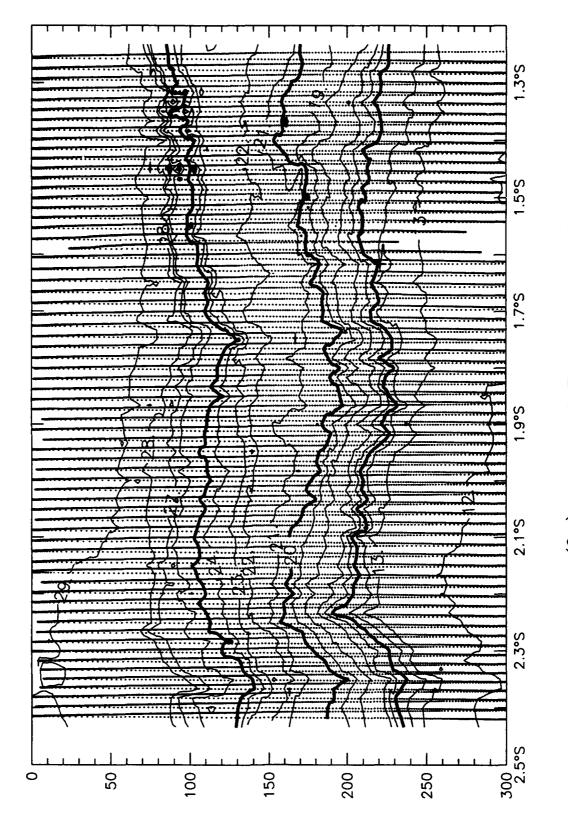
T(°C), N2S, 9 February 1993



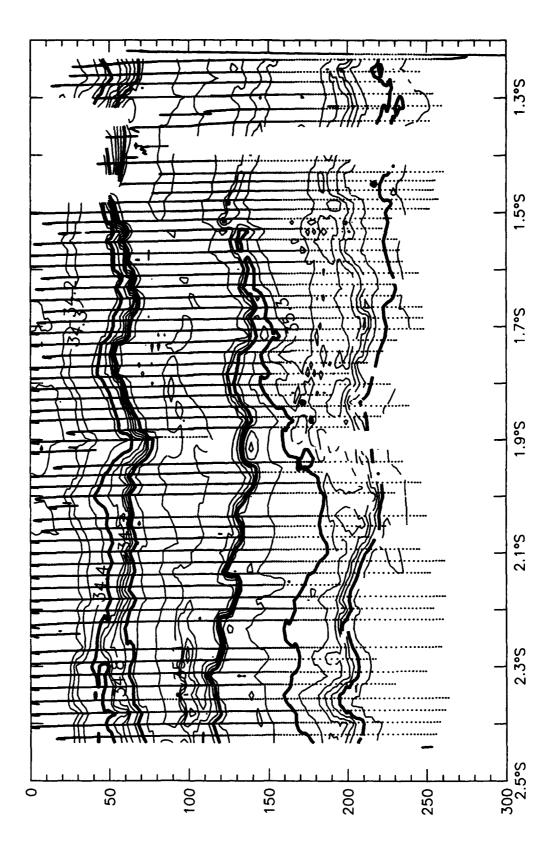
T(°C), N2S, 10 February 1993



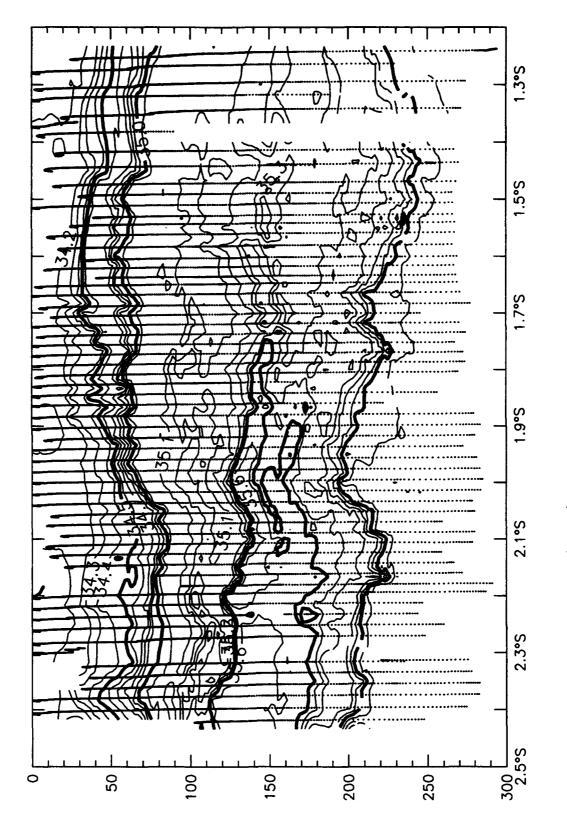
T(°C), N2S, 12 February 1993



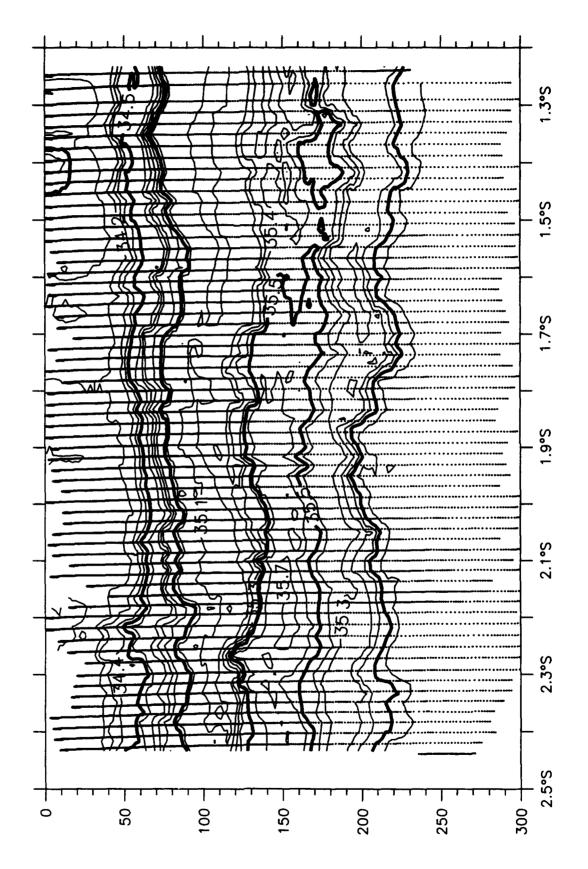
T(°C), N2S, 14 February 1993



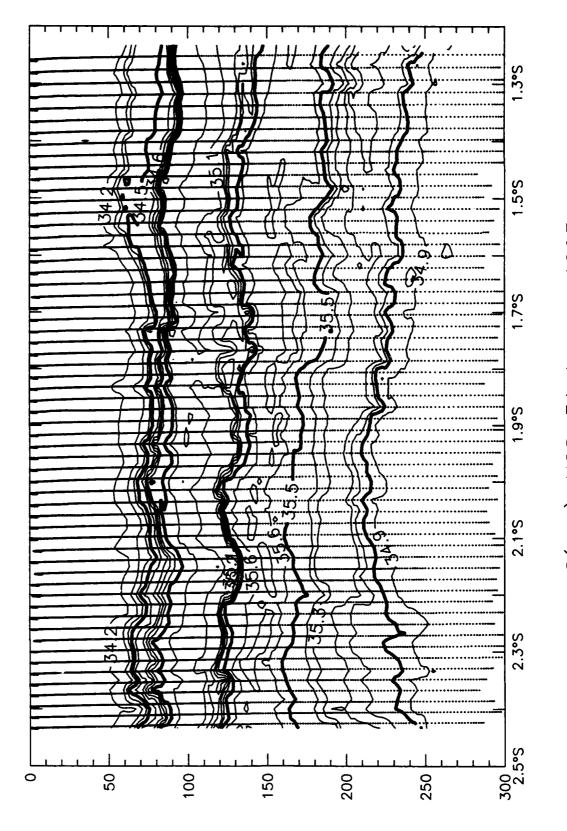
S(psu), N2S, 27 January 1993



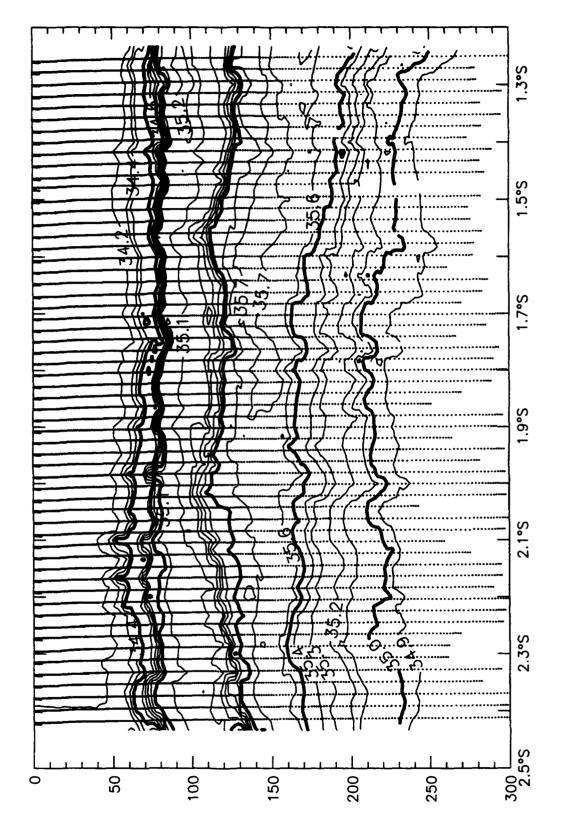
S(psu), N2S, 28 January 1993



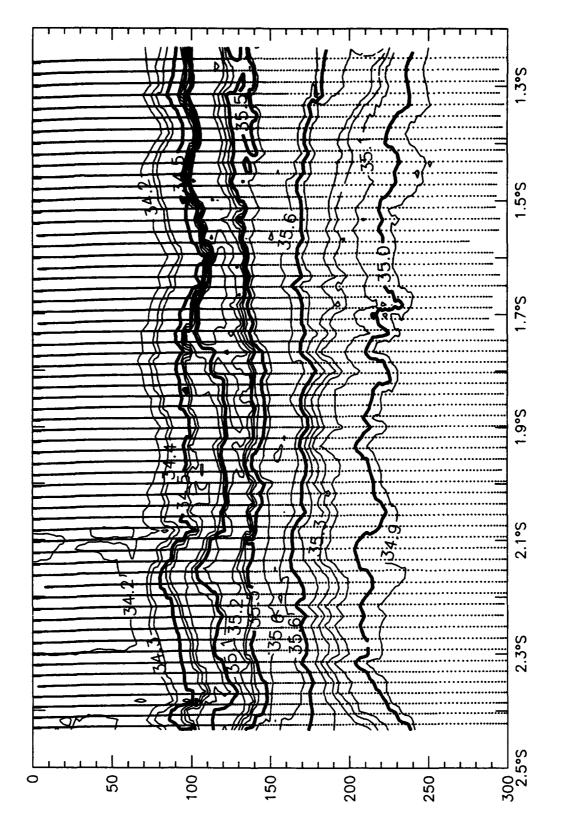
S(psu), N2S, 30 January 1993



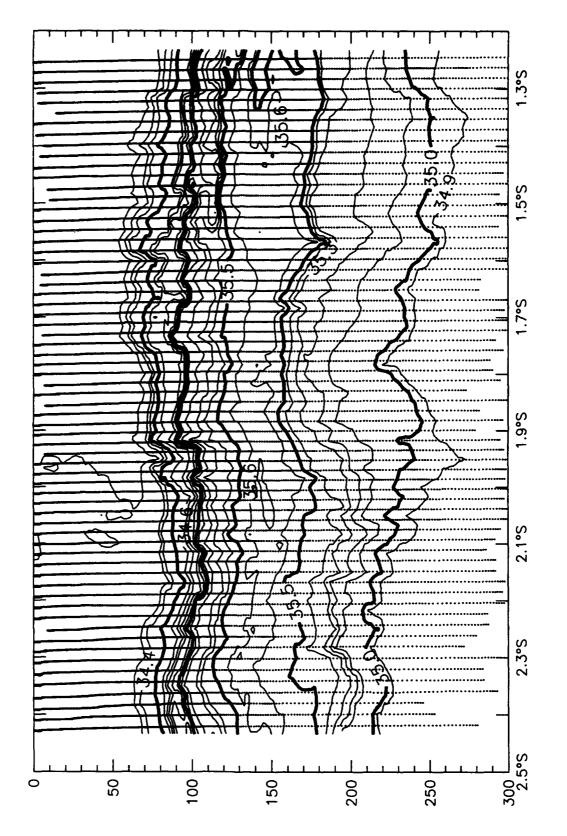
S(psu), N2S, 31 January 1993



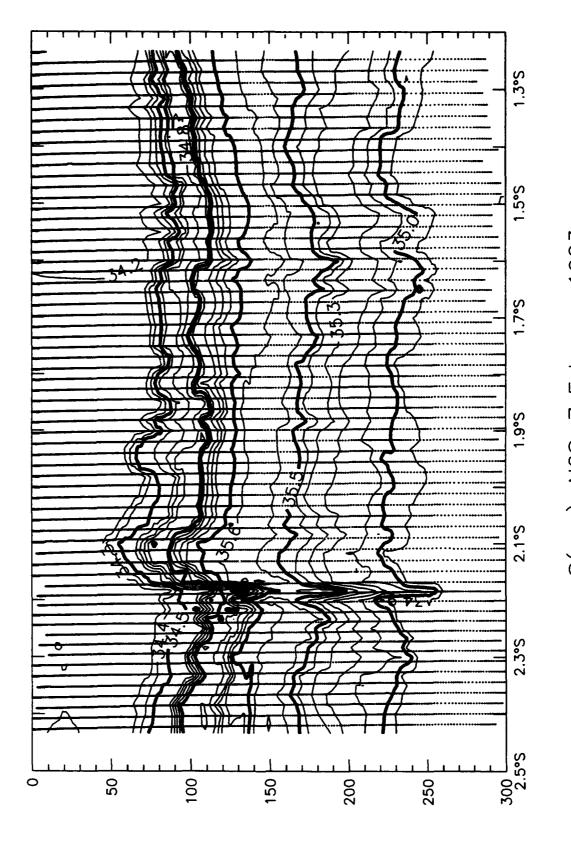
S(psu), N2S, 2 February 1993



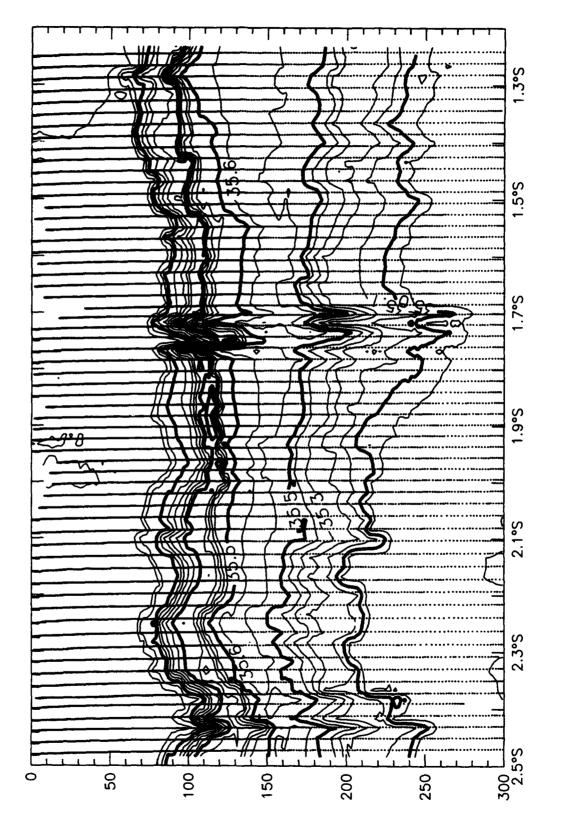
S(psu), N2S, 4 February 1993



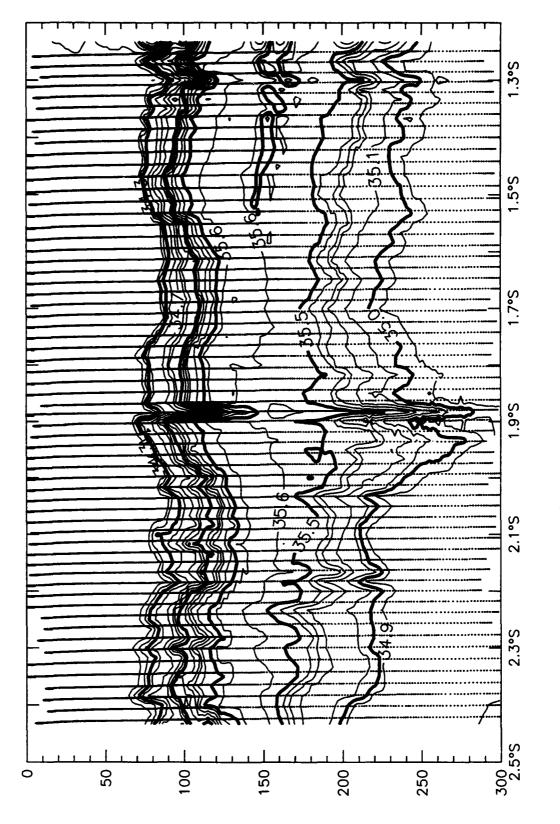
S(psu), N2S, 5 February 1993



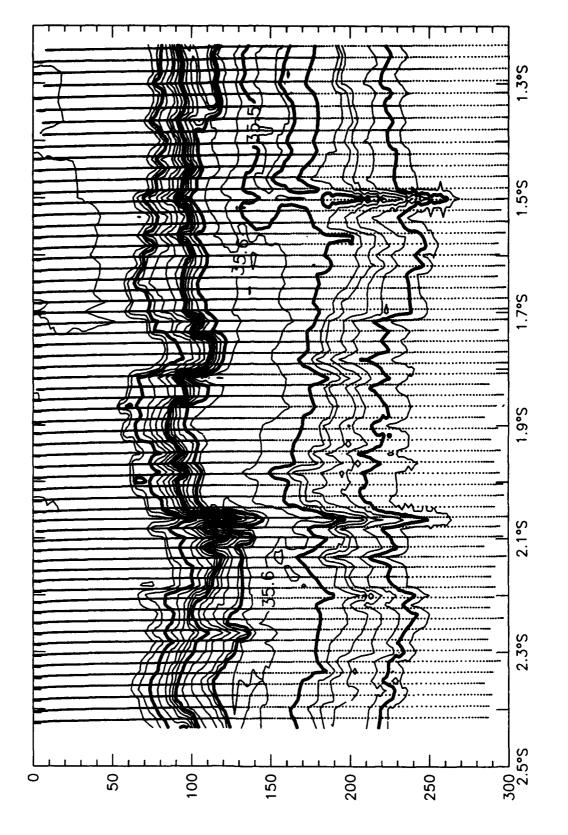
S(psu), N2S, 7 February 1993



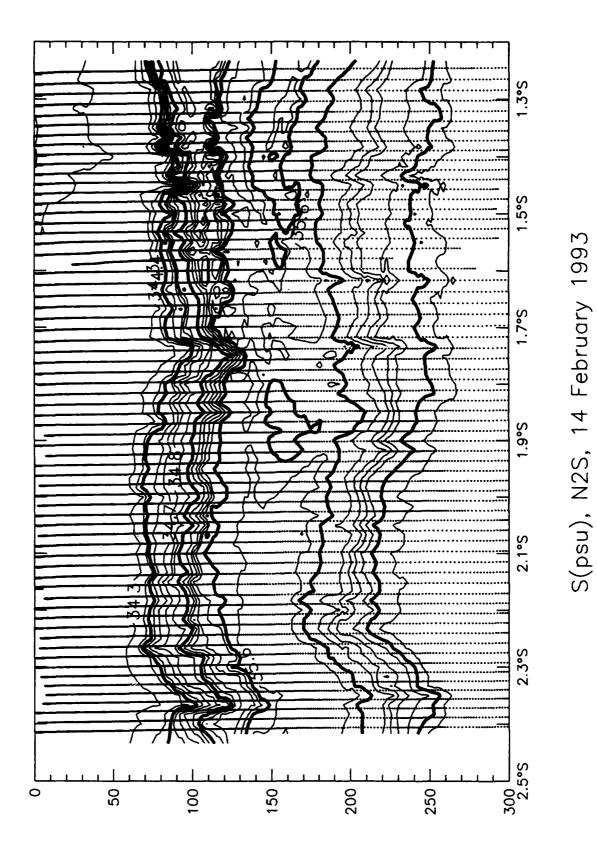
S(psu), N2S, 9 February 1993

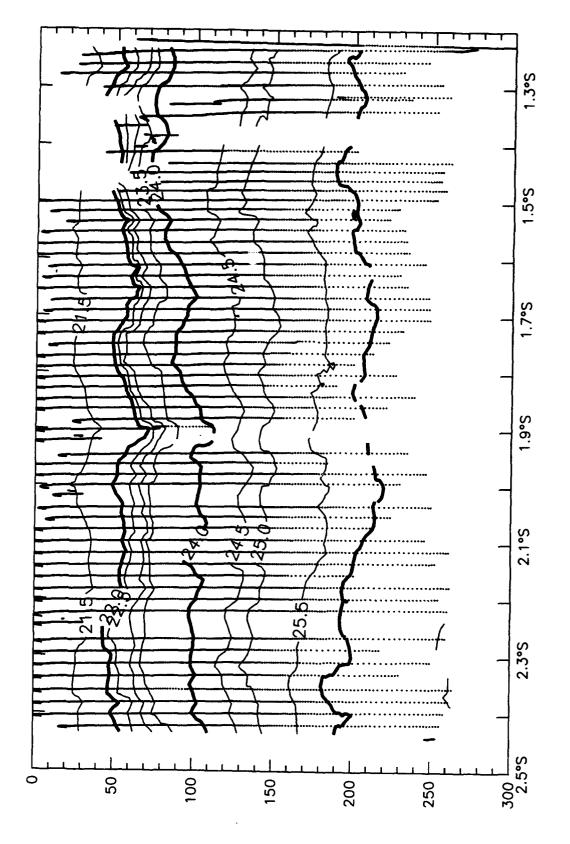


S(psu), N2S, 10 February 1993

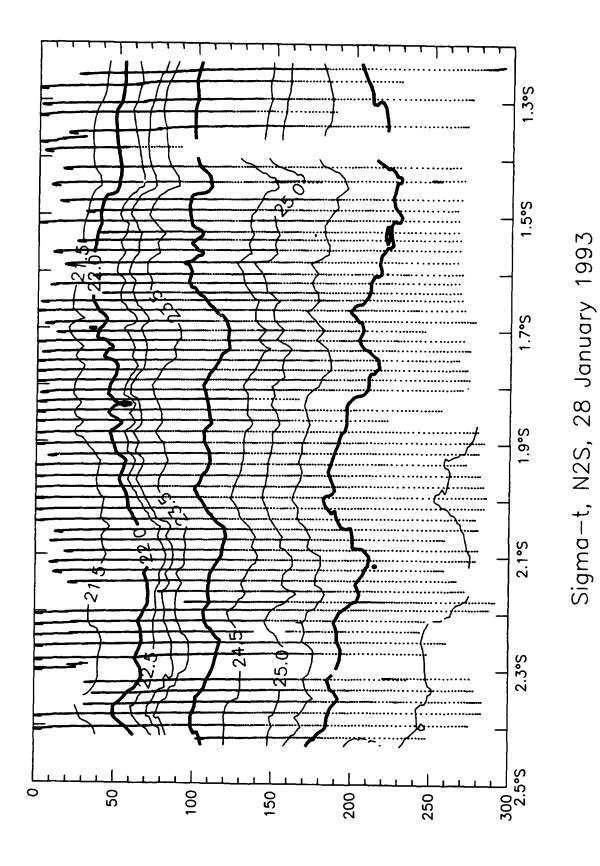


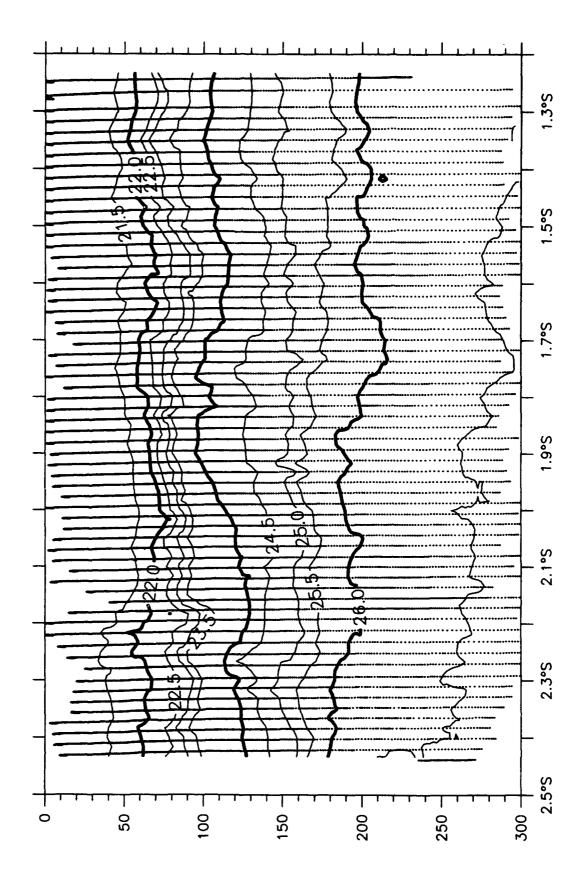
S(psu), N2S, 12 February 1993



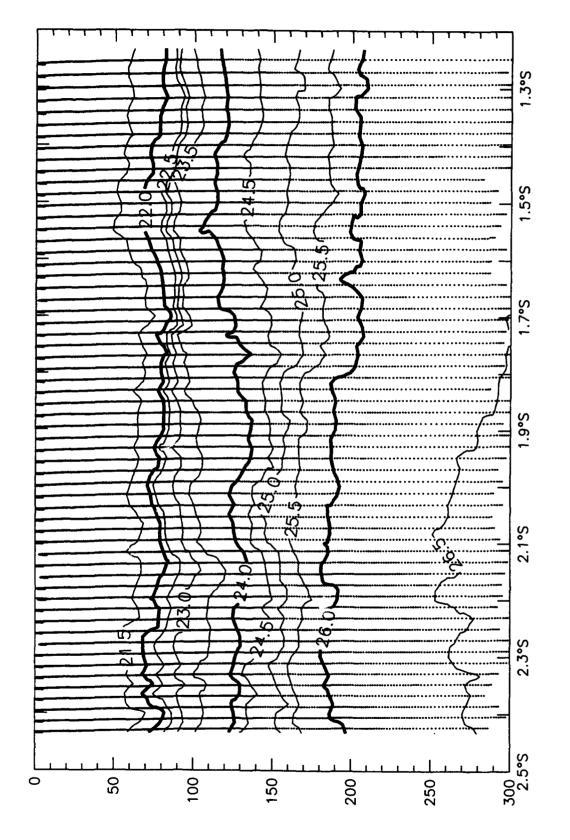


Sigma—t, N2S, 27 January 1993

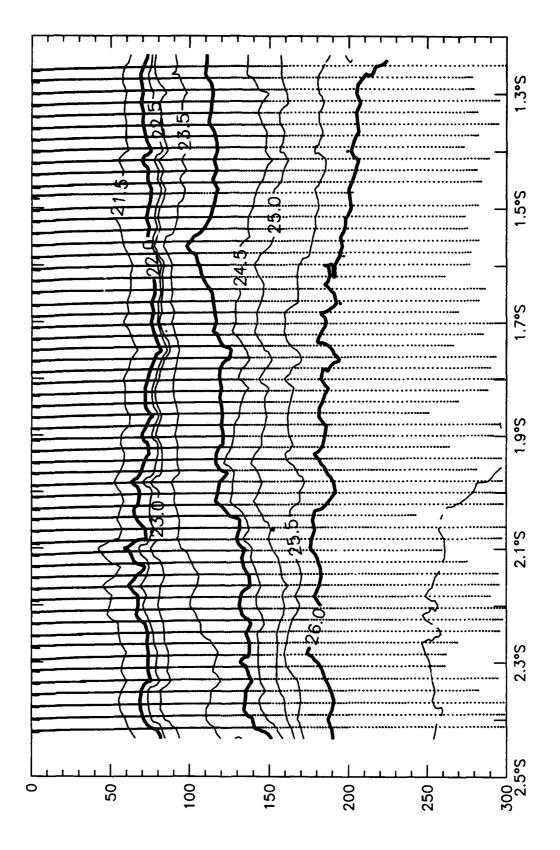




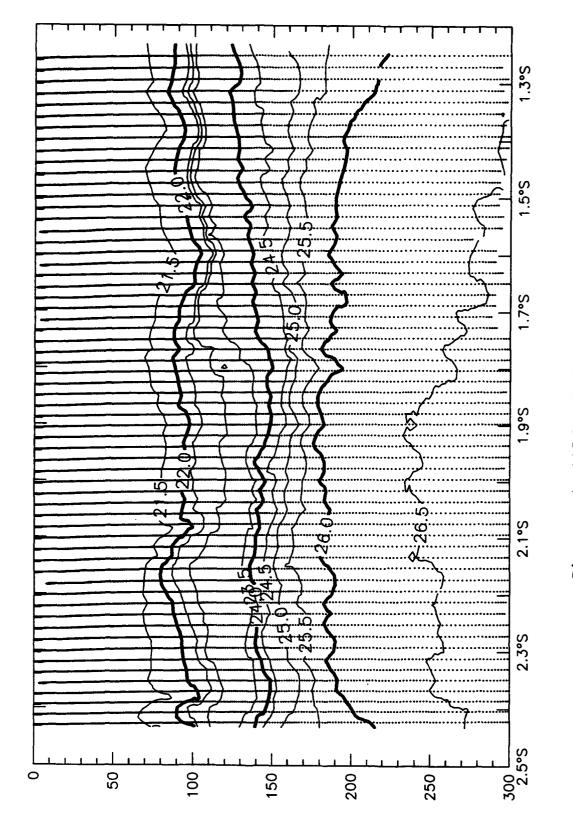
Sigma-t, N2S, 30 January 1993



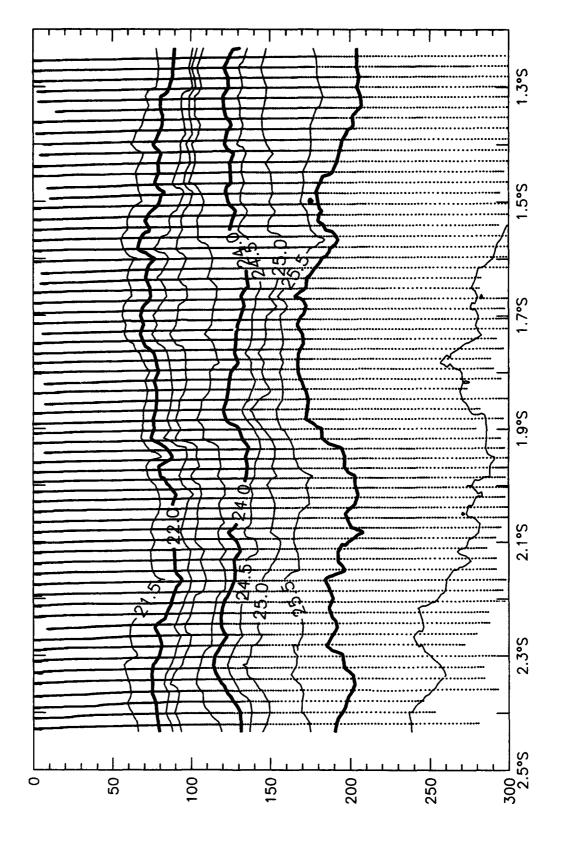
Sigma—t, N2S, 31 January 1993



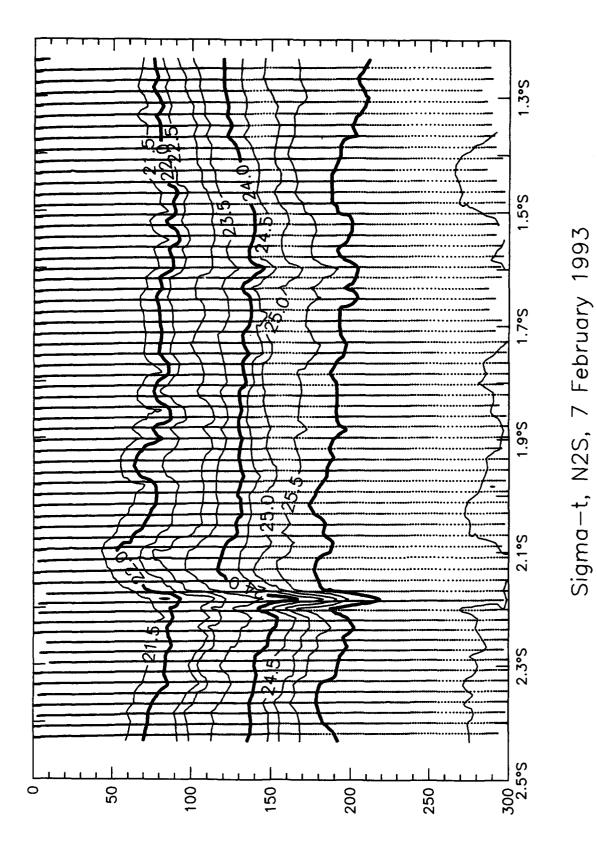
Sigma-t, N2S, 2 February 1993

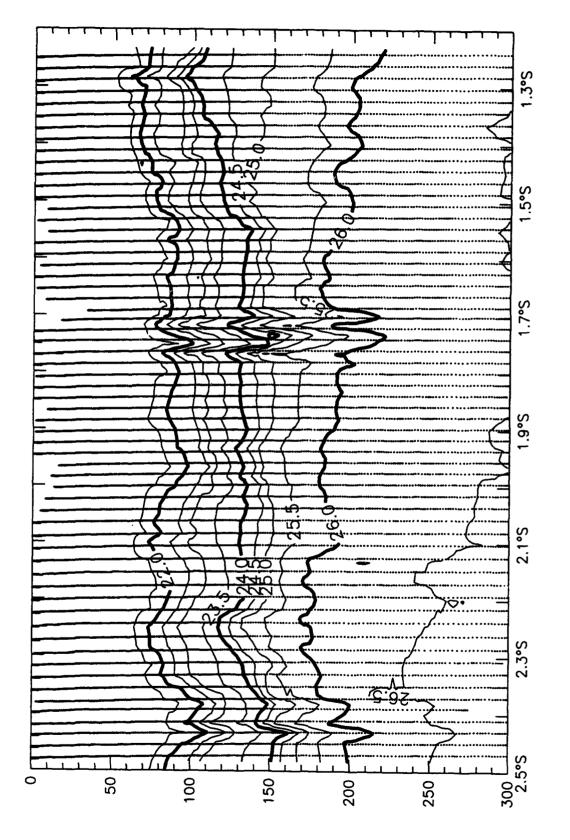


Sigma—t, N2S, 4 February 1993

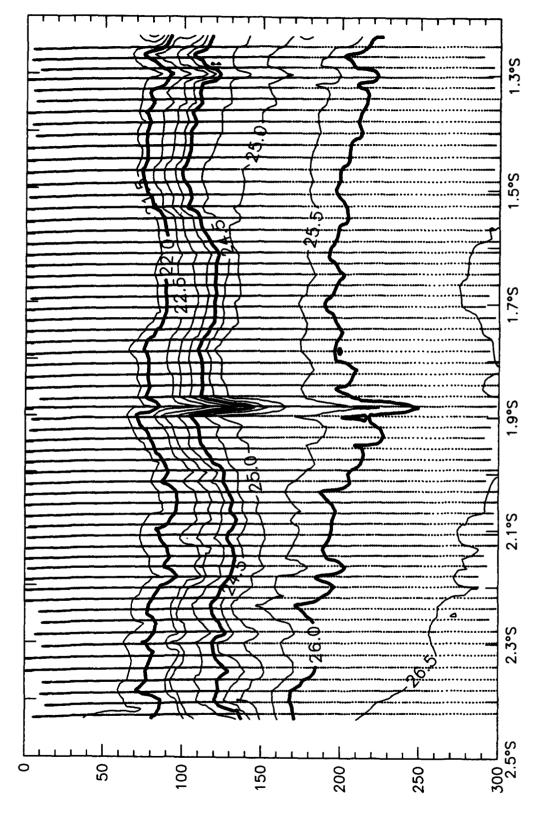


Sigma-t, N2S, 5 February 1993

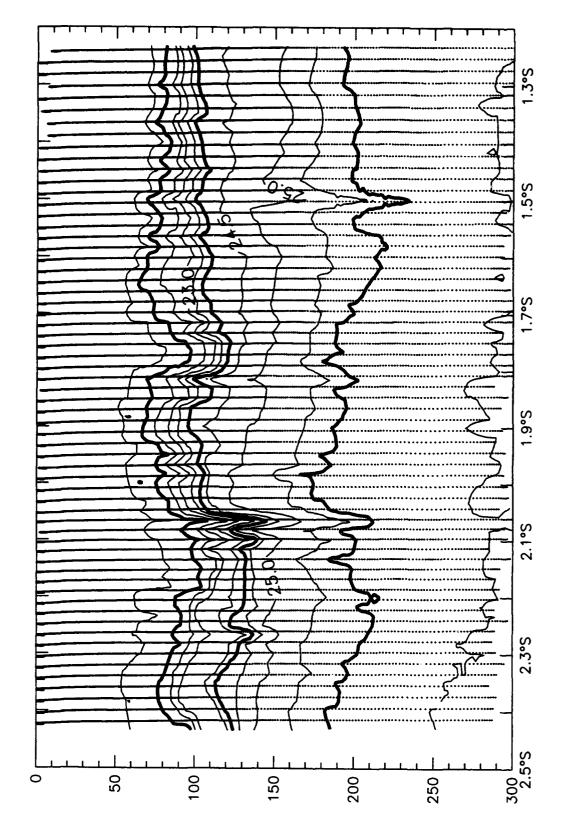




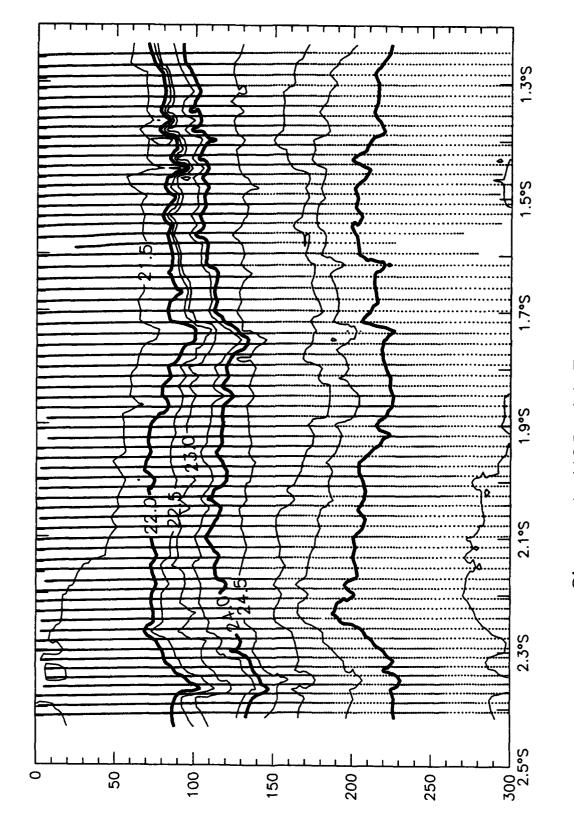
Sigma-t, N2S, 9 February 1993



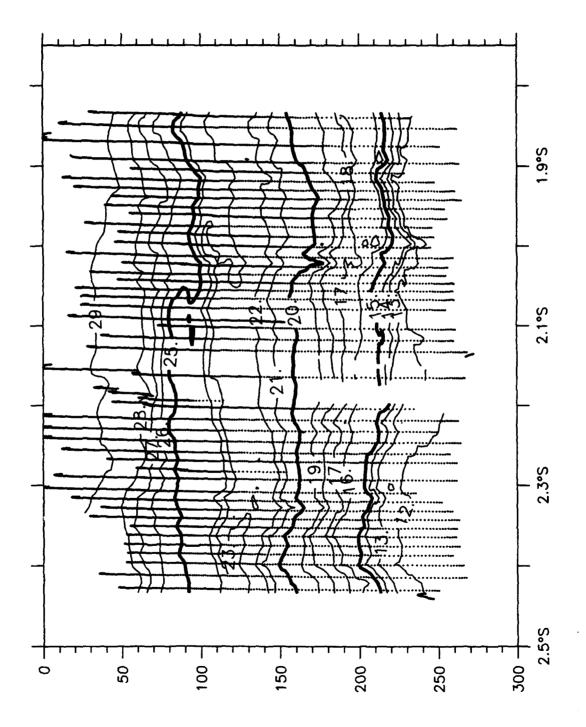
Sigma—t, N2S, 10 February 1993



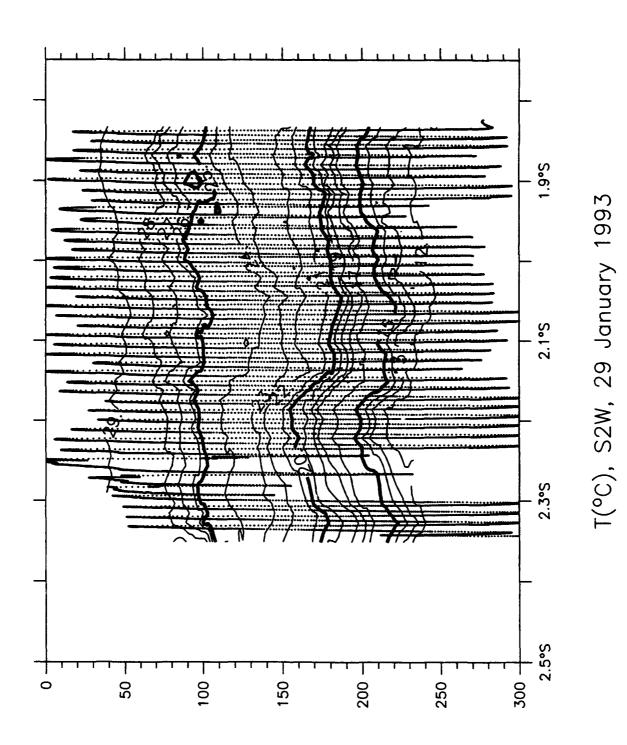
Sigma-t, N2S, 12 February 1993

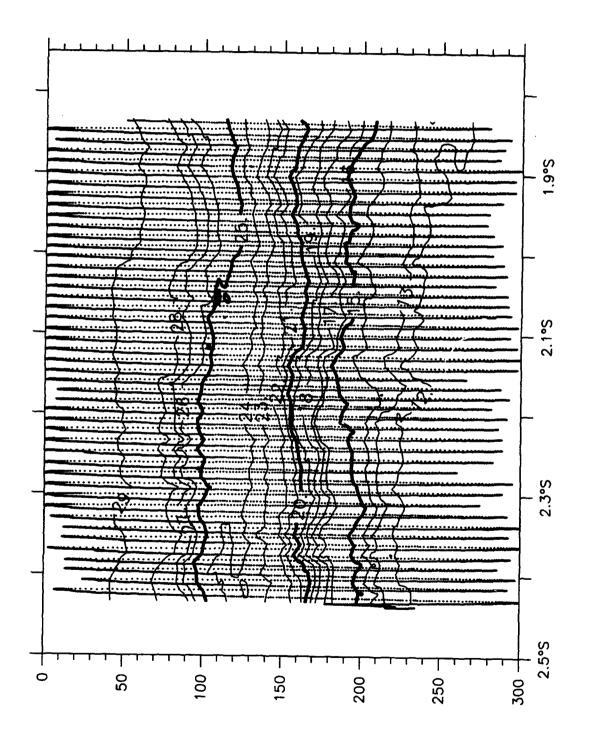


Sigma-t, N2S, 14 February 1993

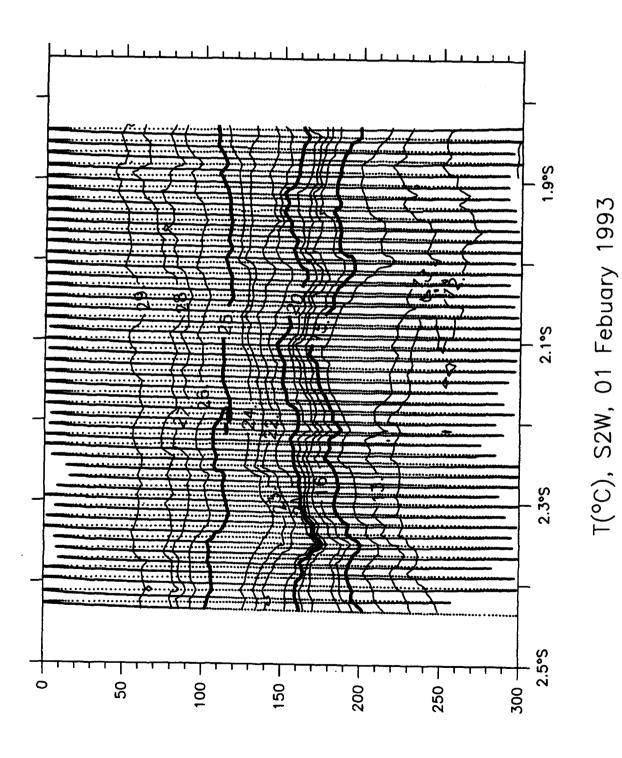


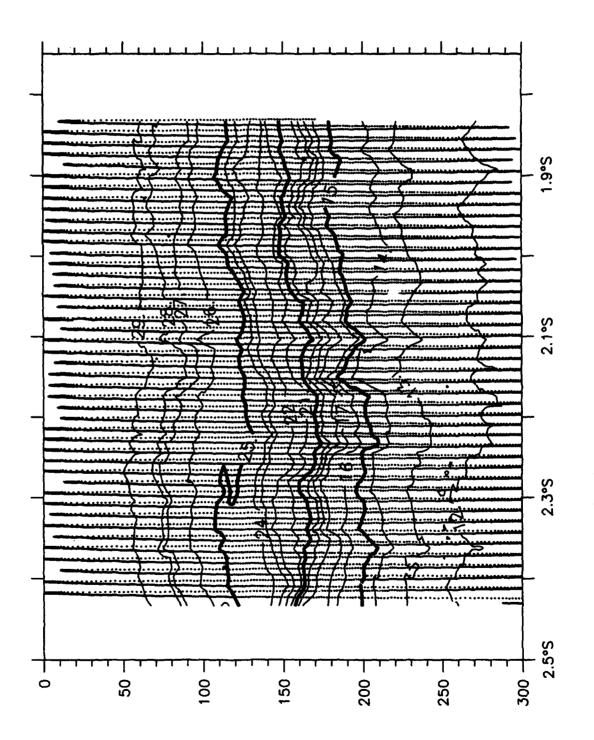
T(°C), S2W, 27 January 1993



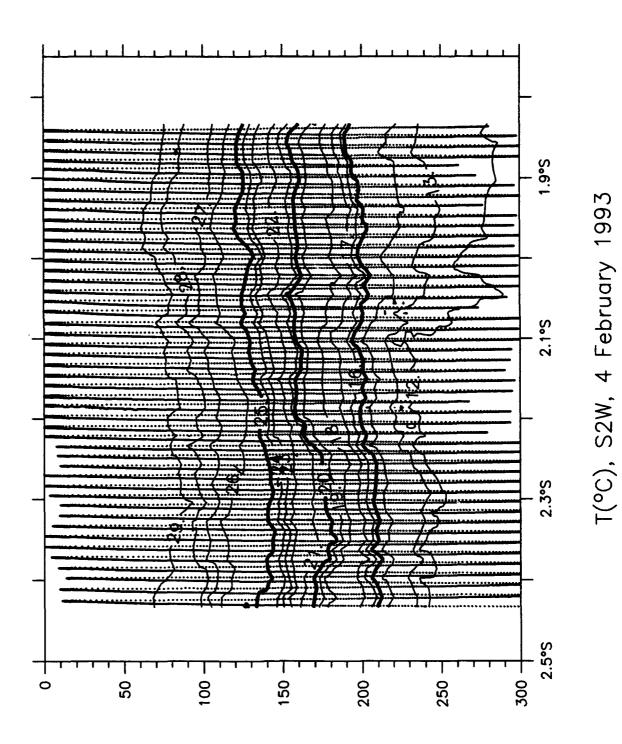


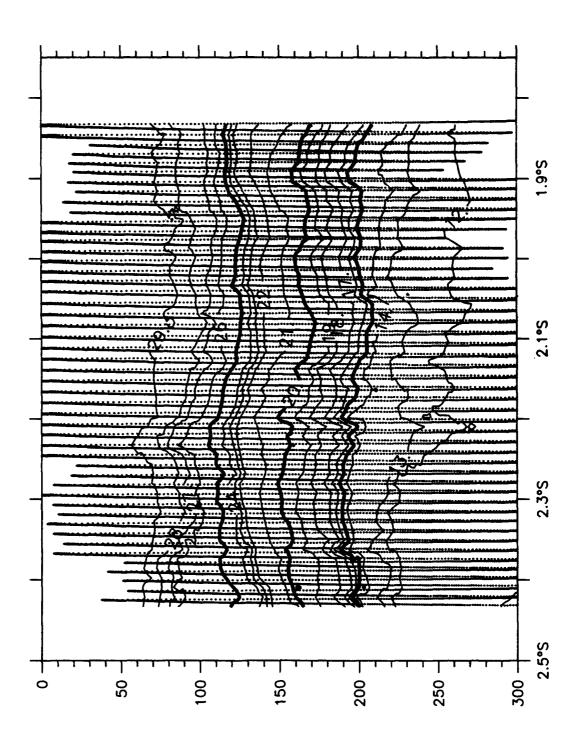
T(°C), S2W, 30 January 1993



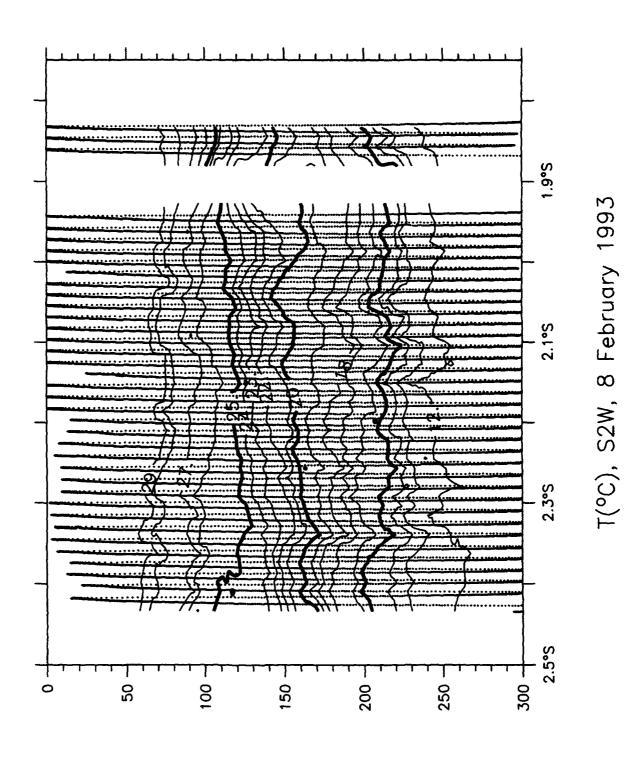


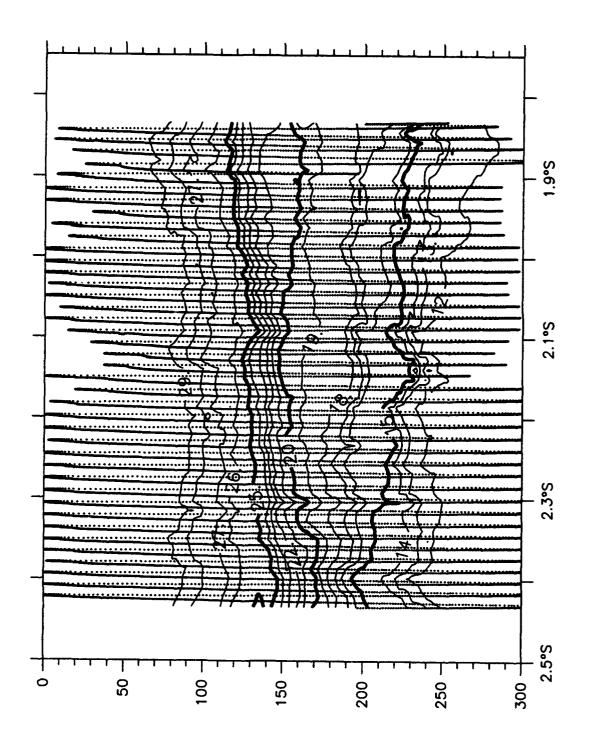
T(°C), S2W, 2 February 1993



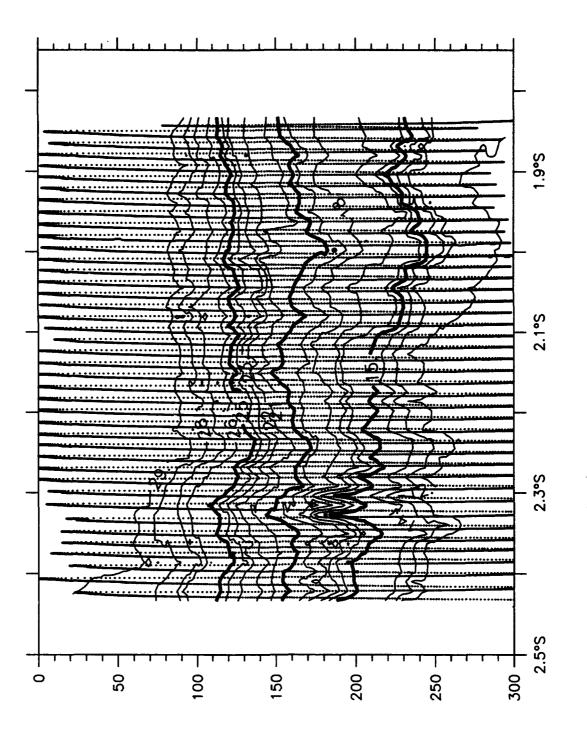


T(°C), S2W, 6 February 1993

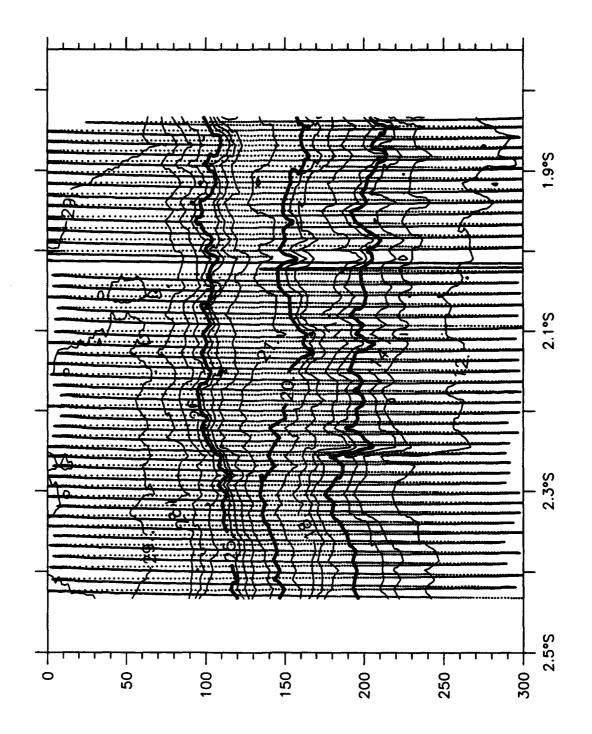




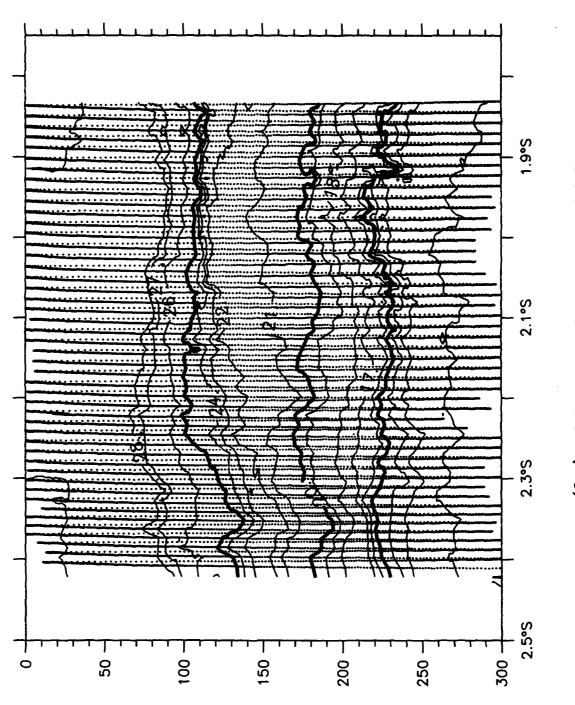
T(°C), S2W, 9 February 1993



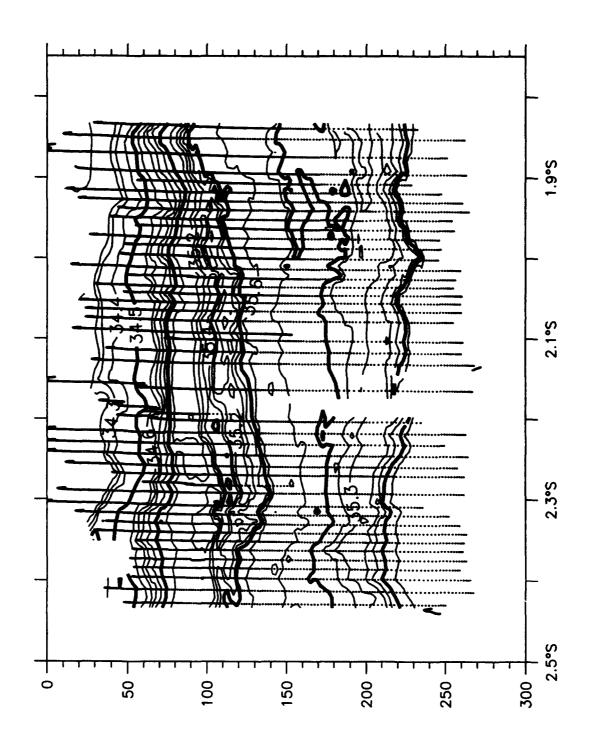
T(°C), S2W, 11 February 1993



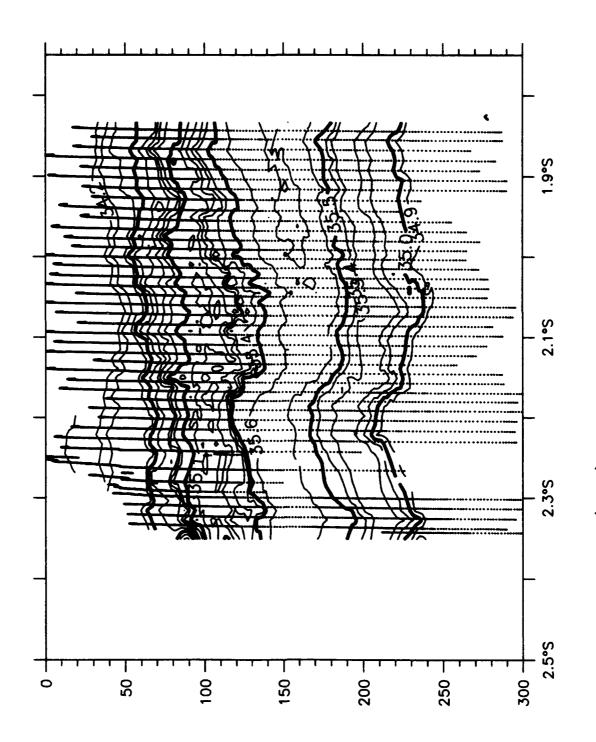
T(°C), S2W, 12—13 February 1993



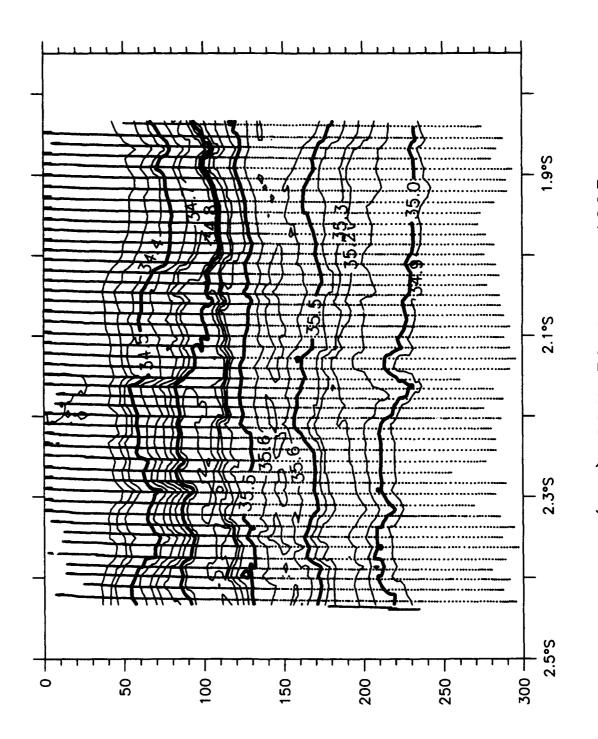
T(°C), S2W, 14 February 1993



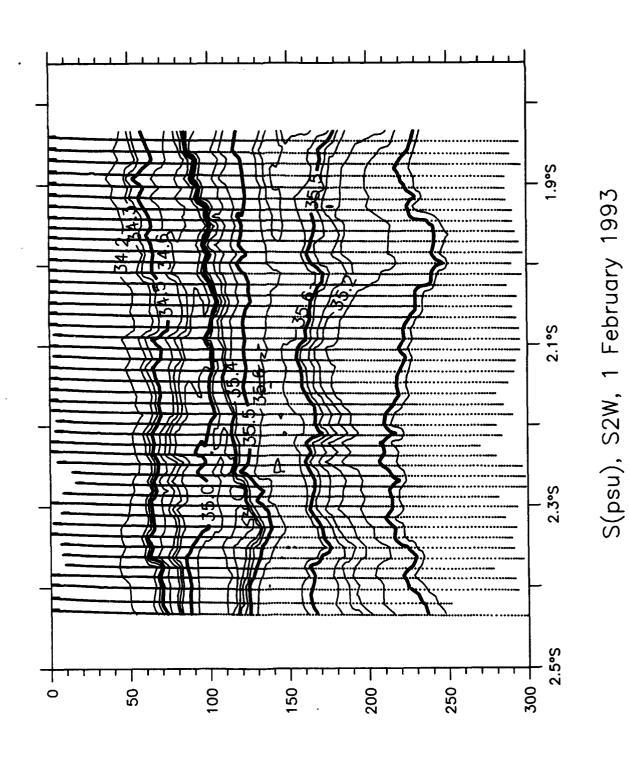
S(psu), S2W, 27 January 1993

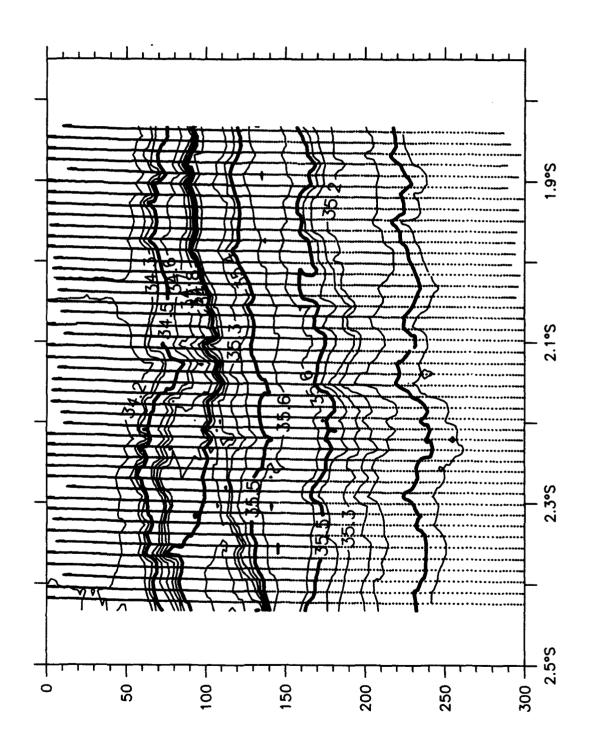


S(psu), S2W, 29 January 1993

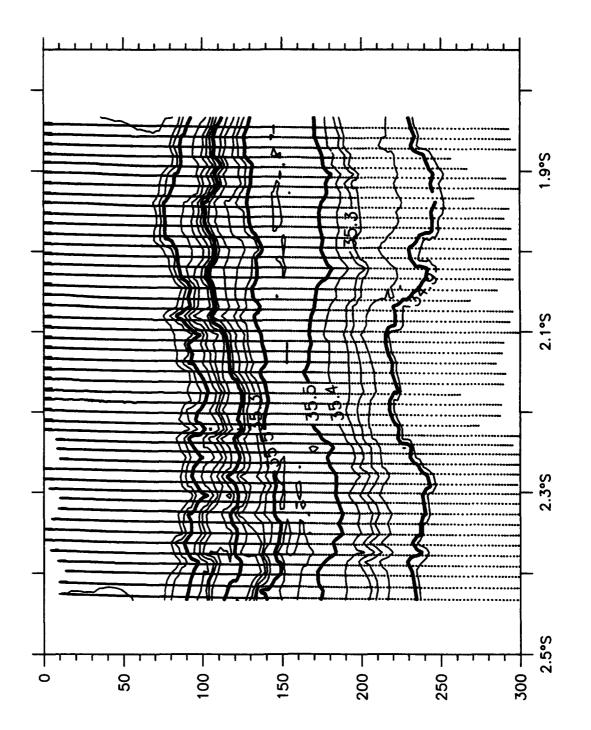


S(psu), S2W, 30 January 1993

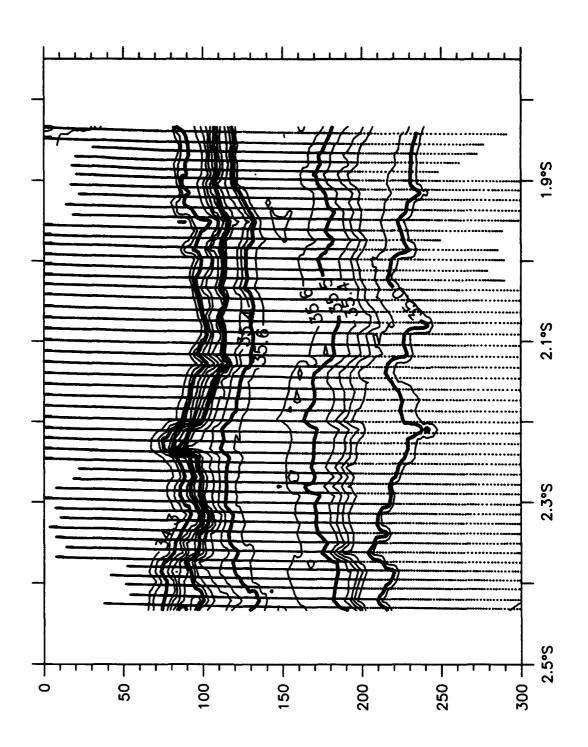




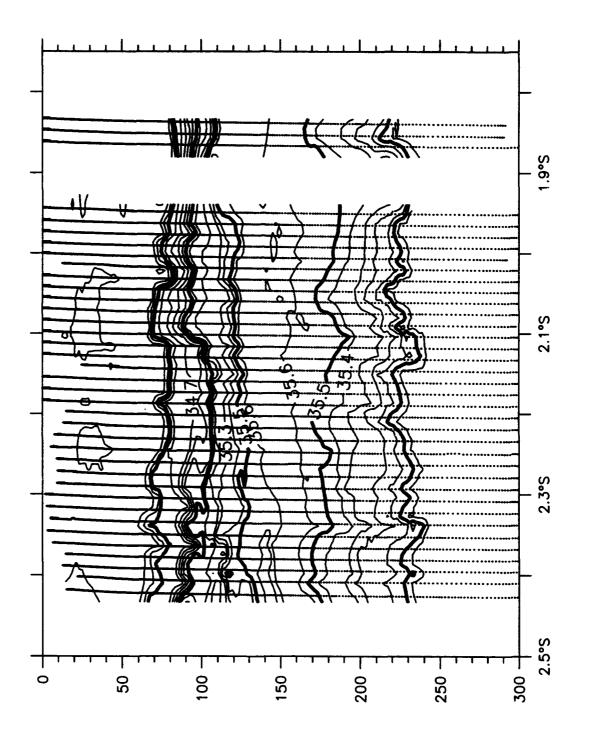
S(psu), S2W, 2 February 1993



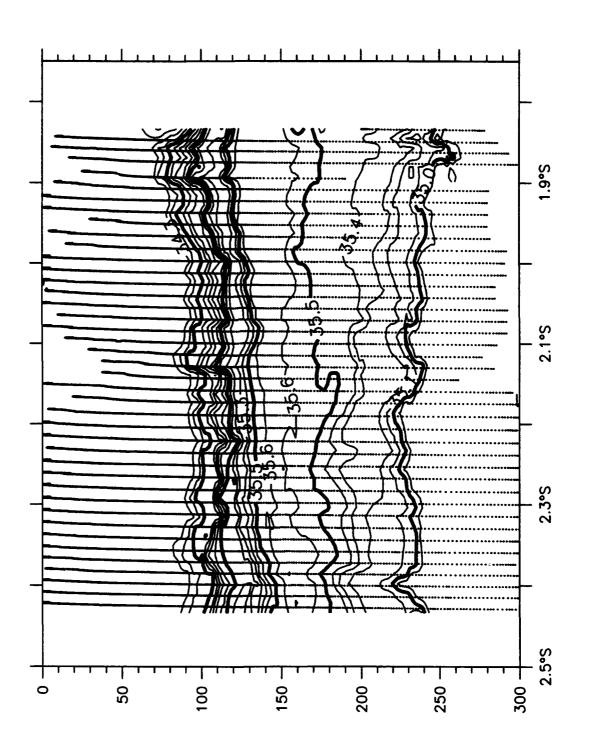
S(psu), S2W, 4 February 1993



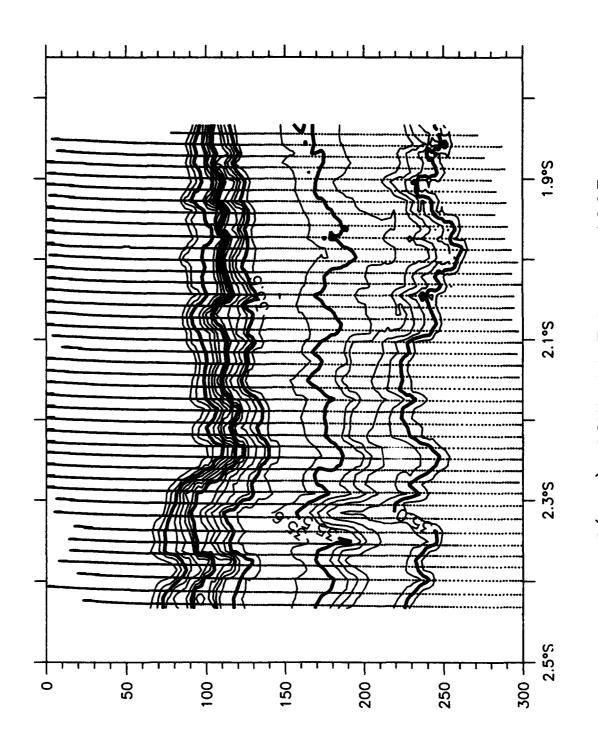
S(psu), S2W, 6 February 1993



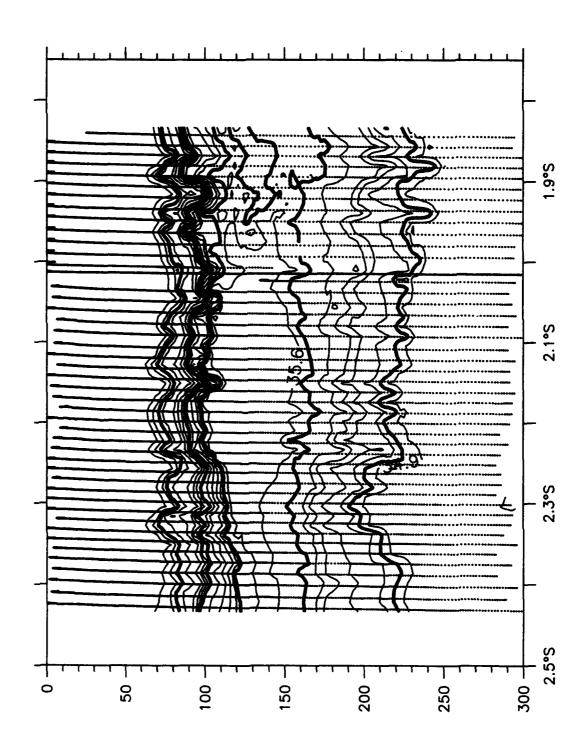
S(psu), S2W, 8 February 1993



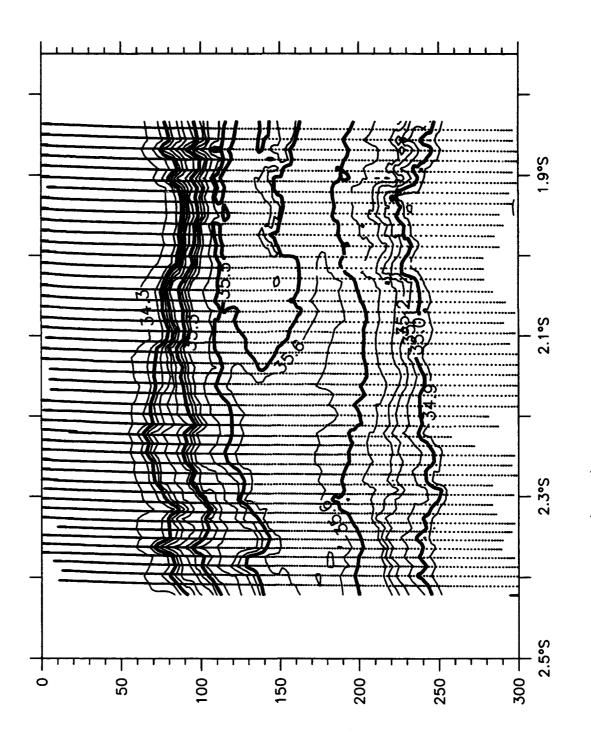
S(psu), S2W, 9 February 1993



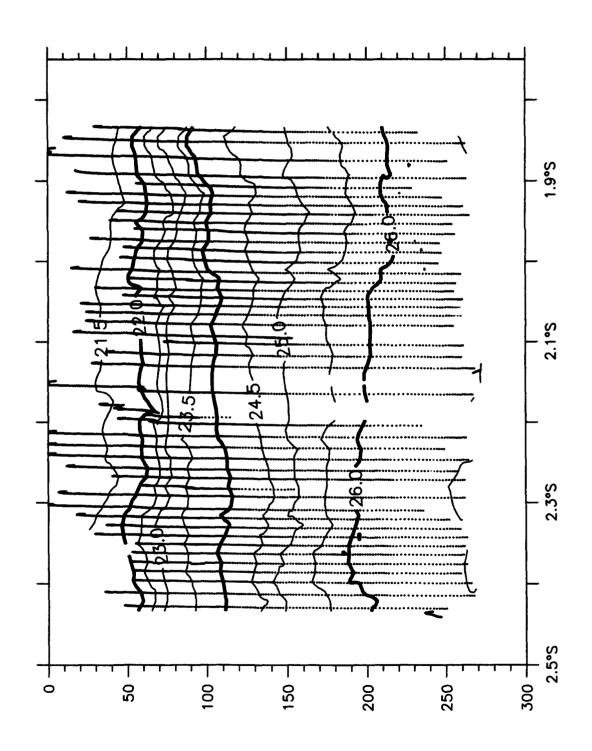
S(psu), S2W, 11 February 1993



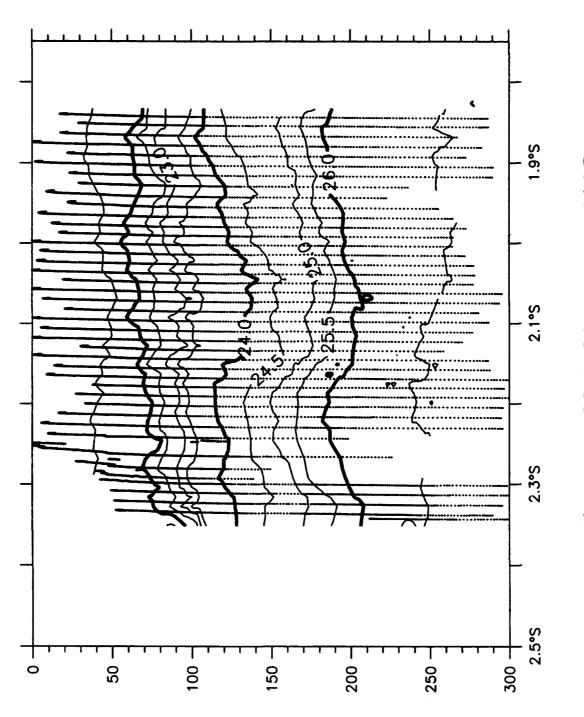
S(psu), S2W, 12-13 February 1993



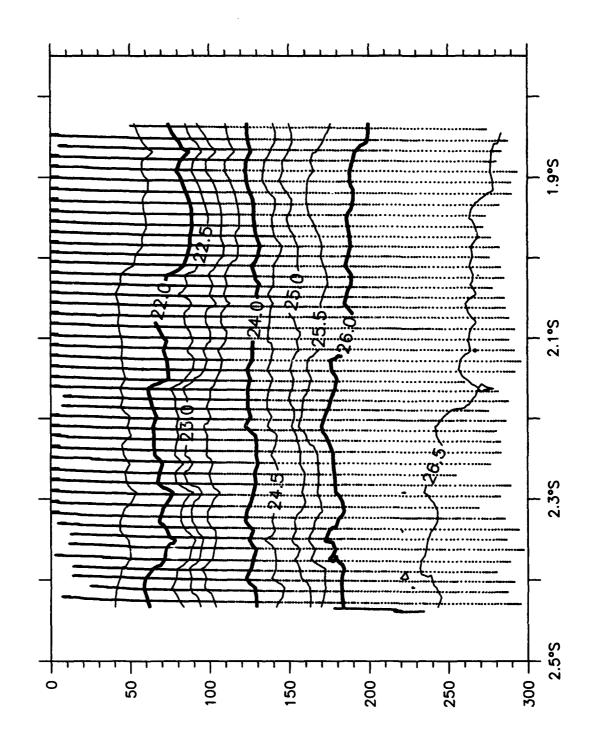
S(psu), S2W, 14 February 1993



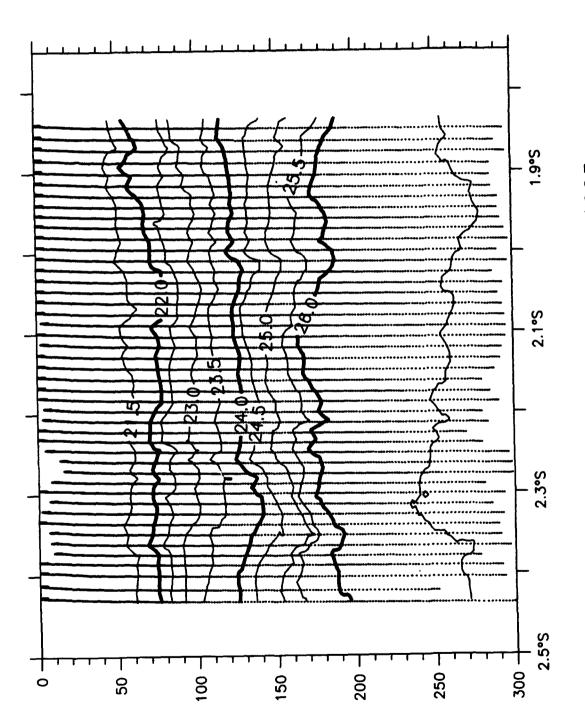
Sigma—t, S2W, 27 January 1993



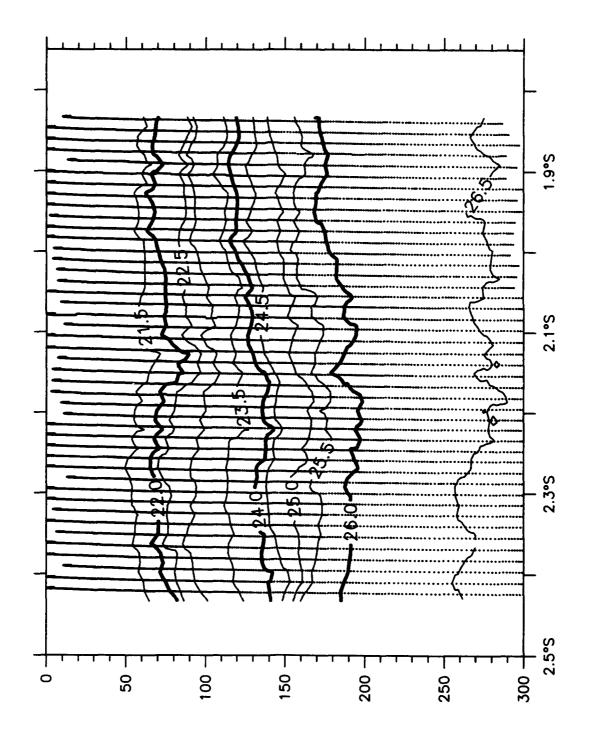
Sigma—t, S2W, 29 January 1993



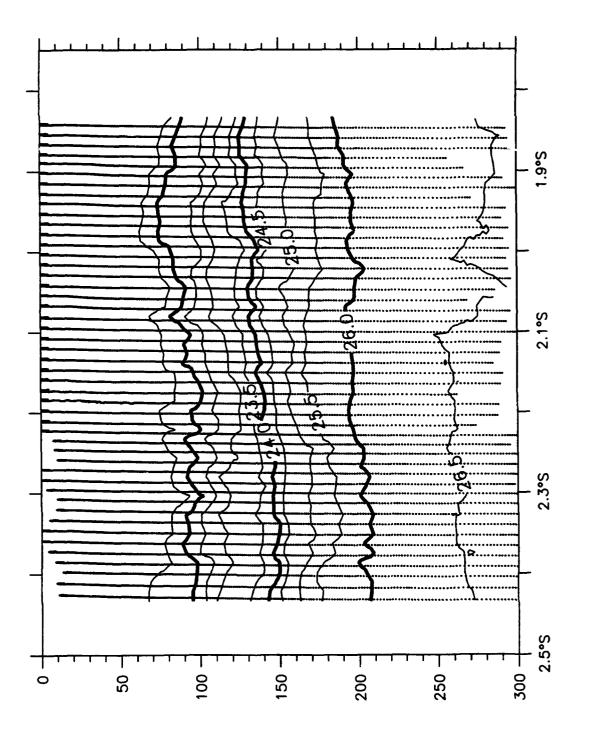
Sigma-t, S2W, 30 January 1993



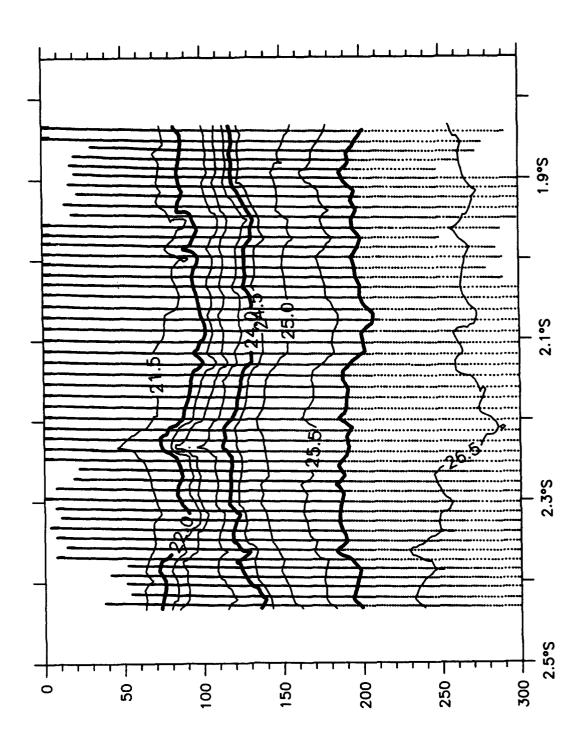
Sigma-t, S2W, 1 February 1993



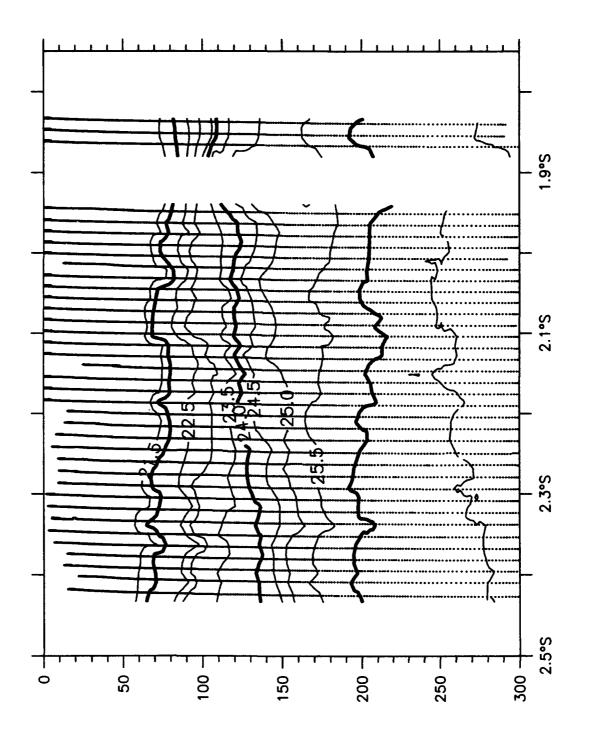
Sigma-t, S2W, 2 February 1993



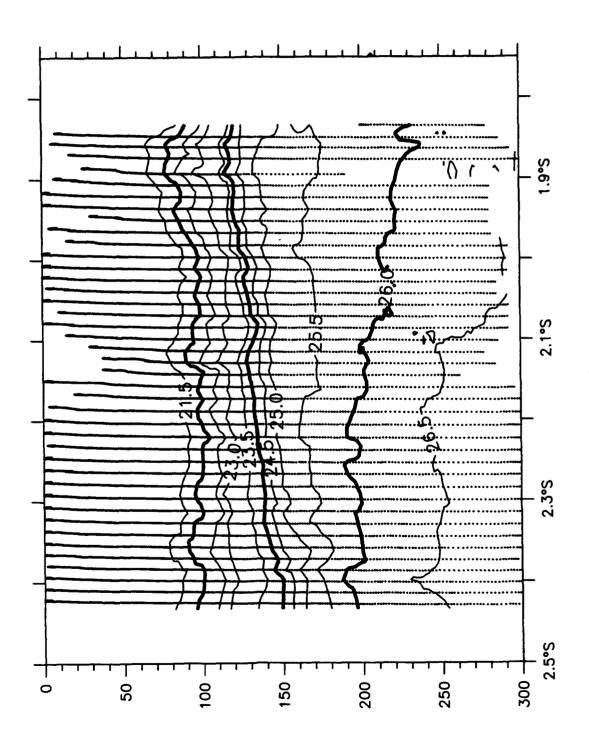
Sigma—t, S2W, 4 February 1993



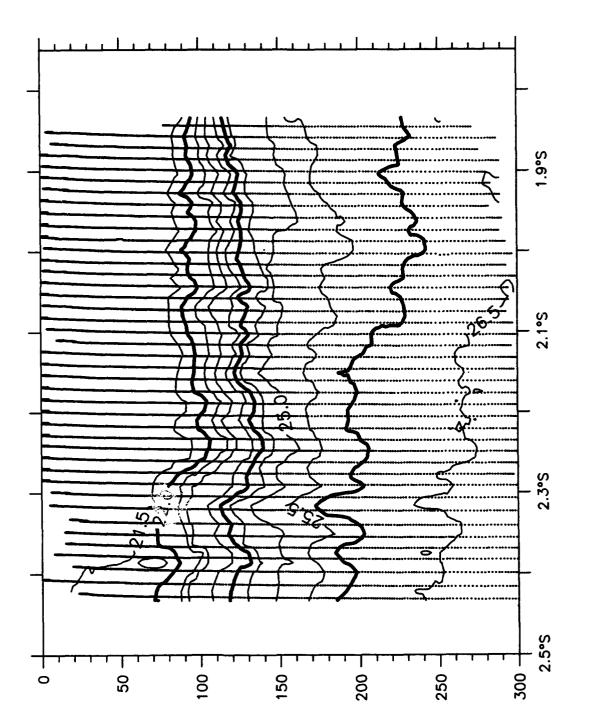
Sigma-t, S2W, 6 February 1993



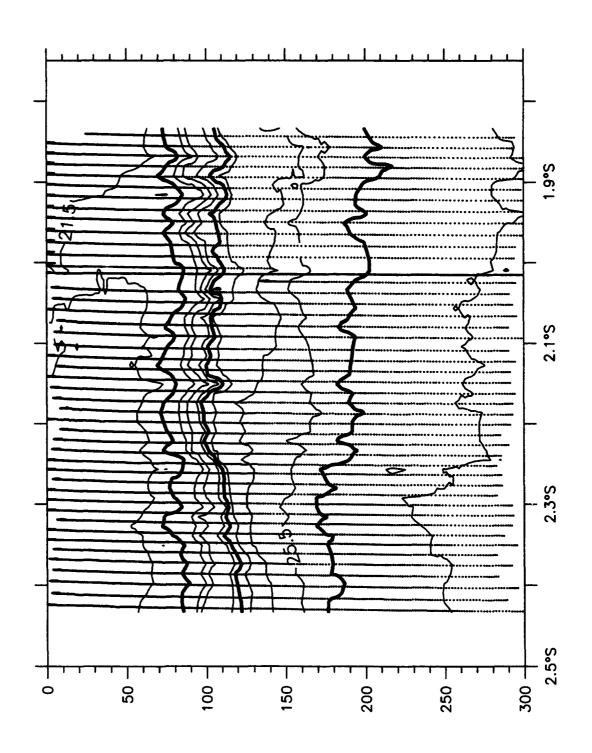
Sigma-t, S2W, 8 February 1993



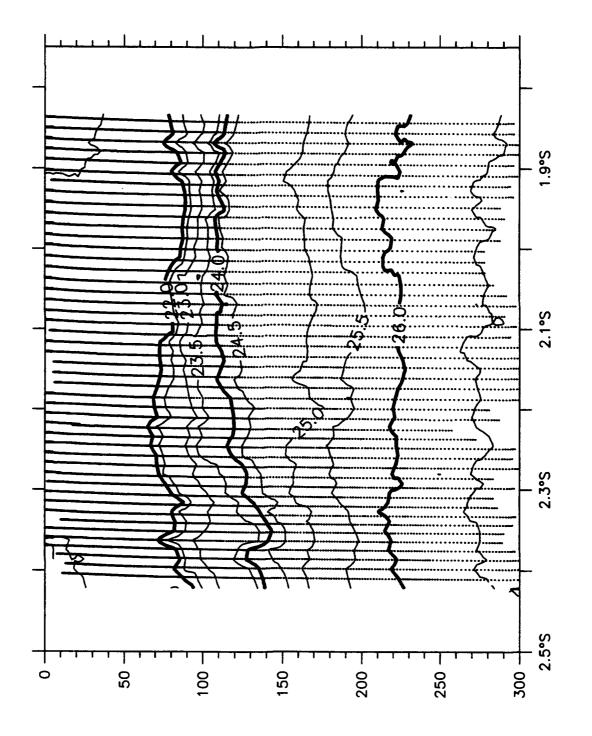
Sigma—t, S2W, 9 February 1993



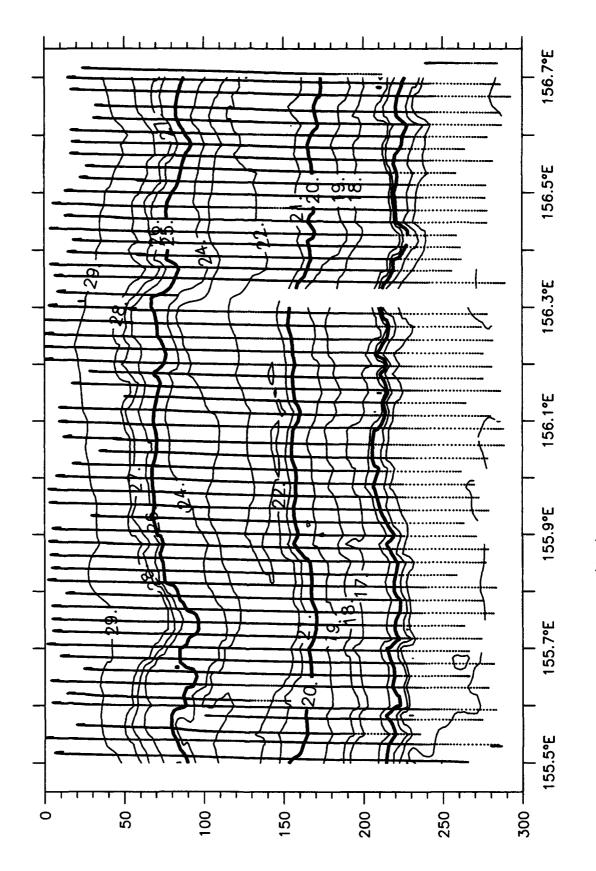
Sigma-t, S2W, 11 February 1993



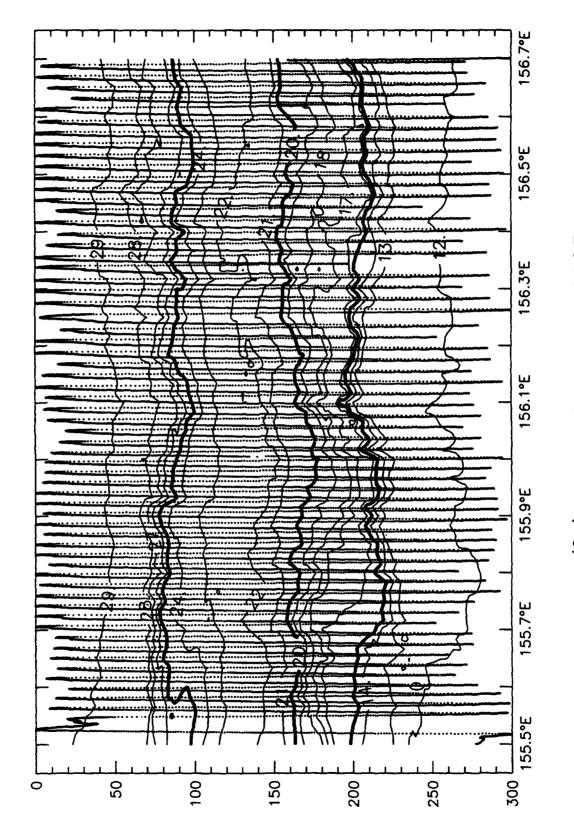
Sigma-t, S2W, 12-13 February 1993



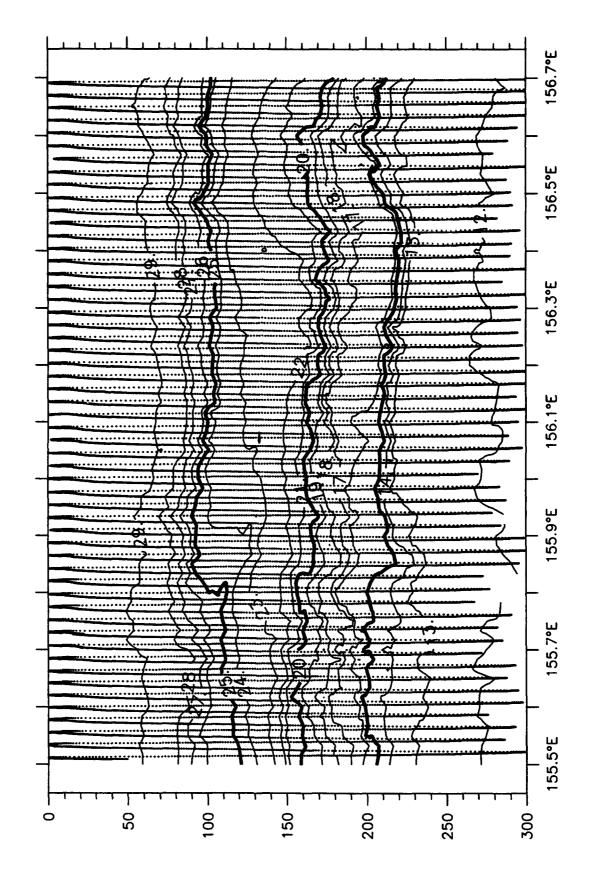
Sigma—t, S2W, 14 February 1993



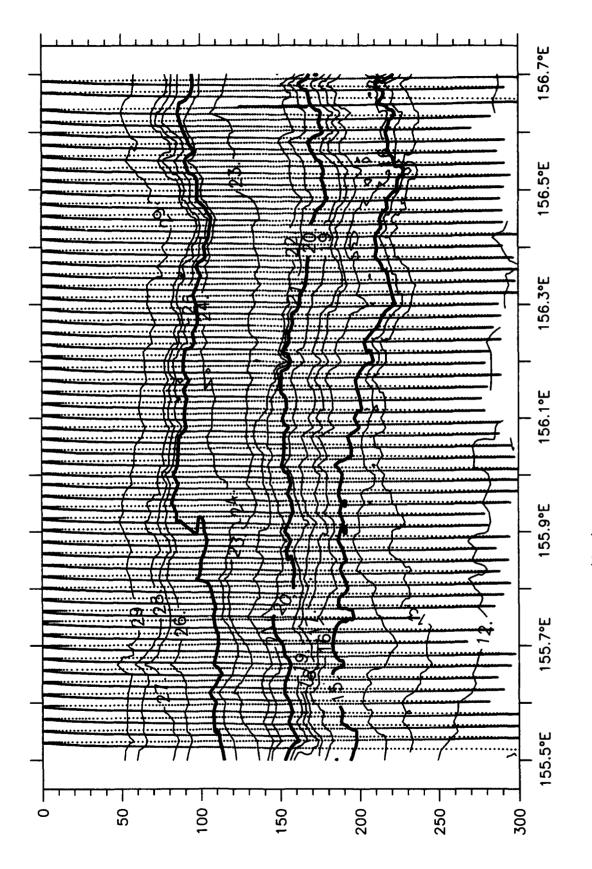
T(°C), W2E, 28 January 1993



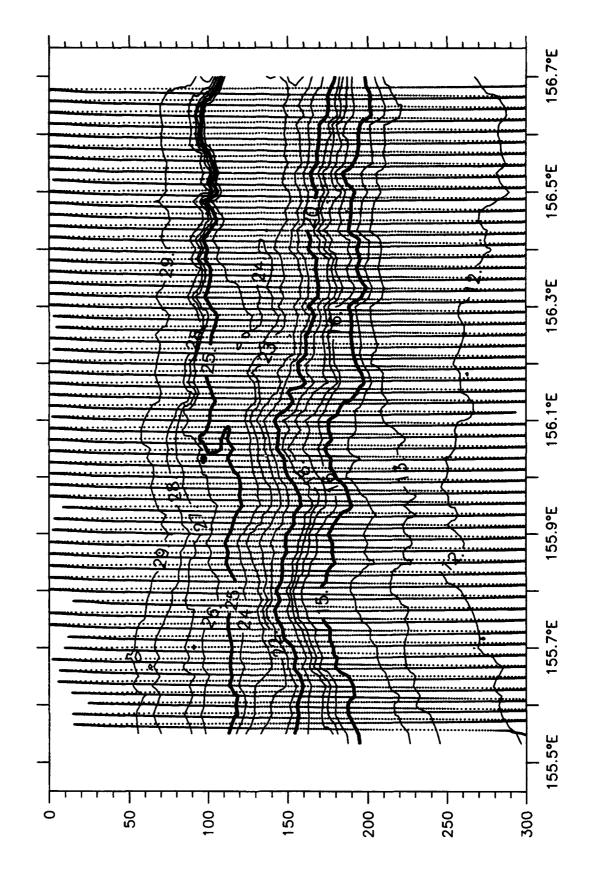
T(°C), W2E, 29 January 1993



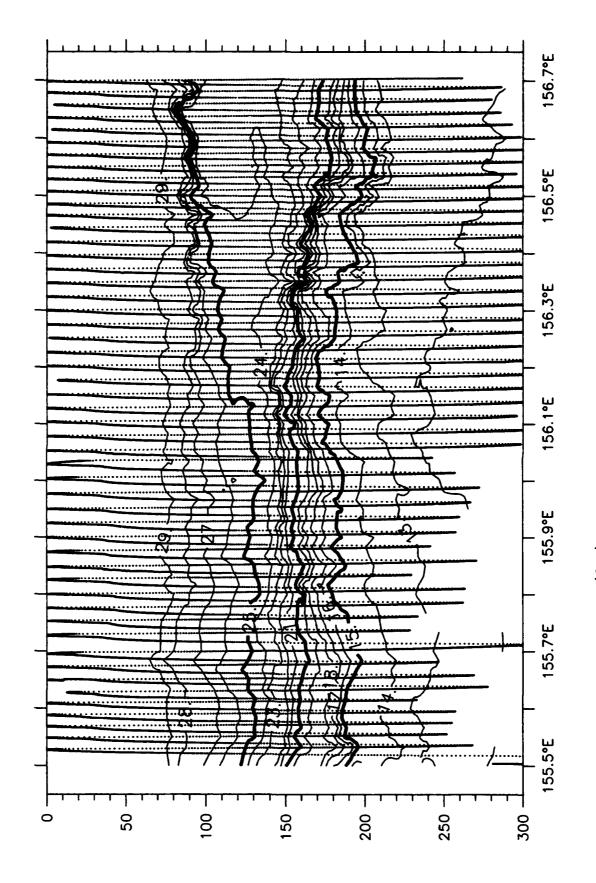
T(°C), W2E, 31 January 1993



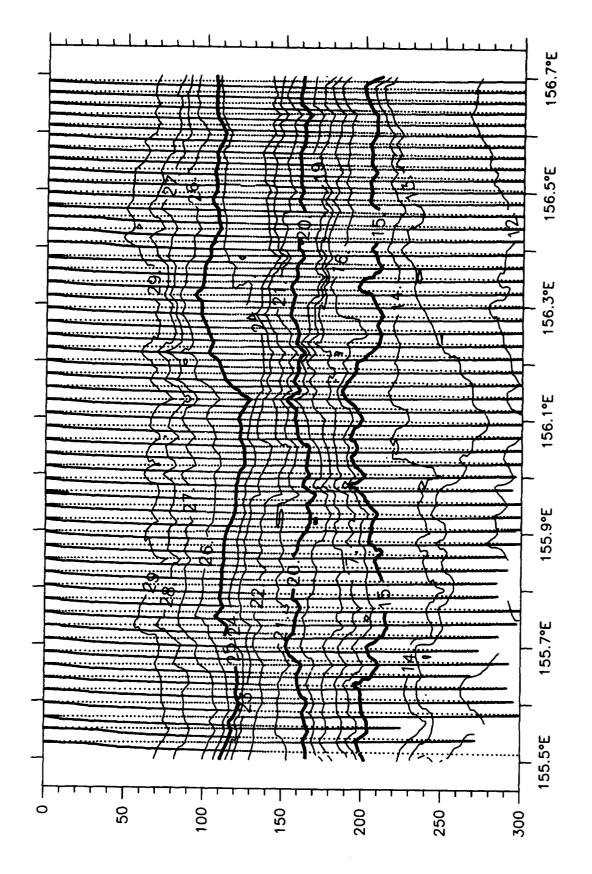
T(°C), W2E, 1 February 1993



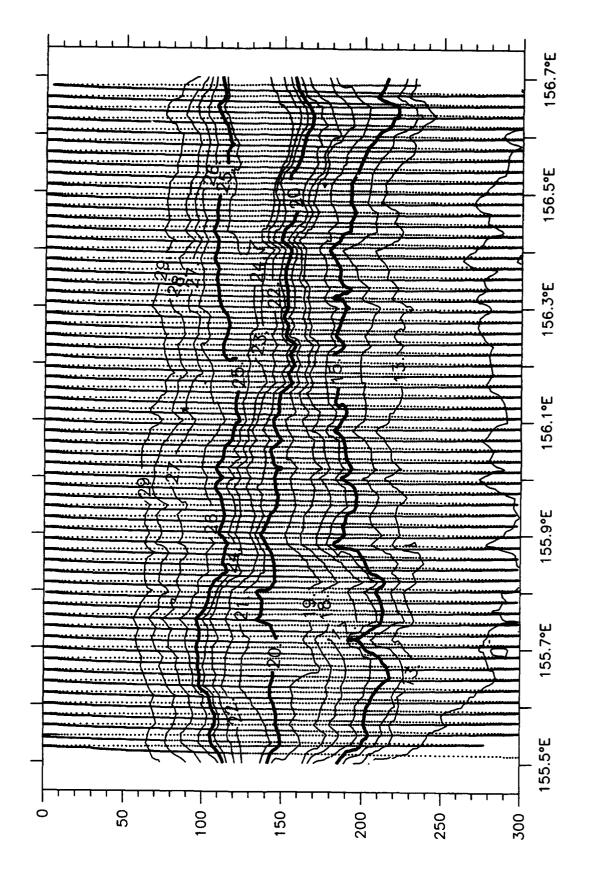
T(°C), W2E, 3 February 1993



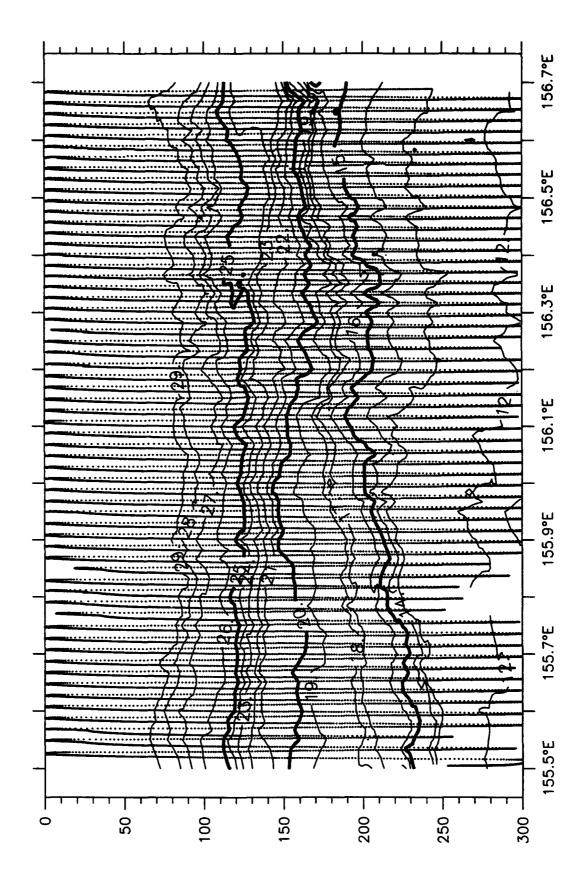
T(°C), W2E, 04 February 1993



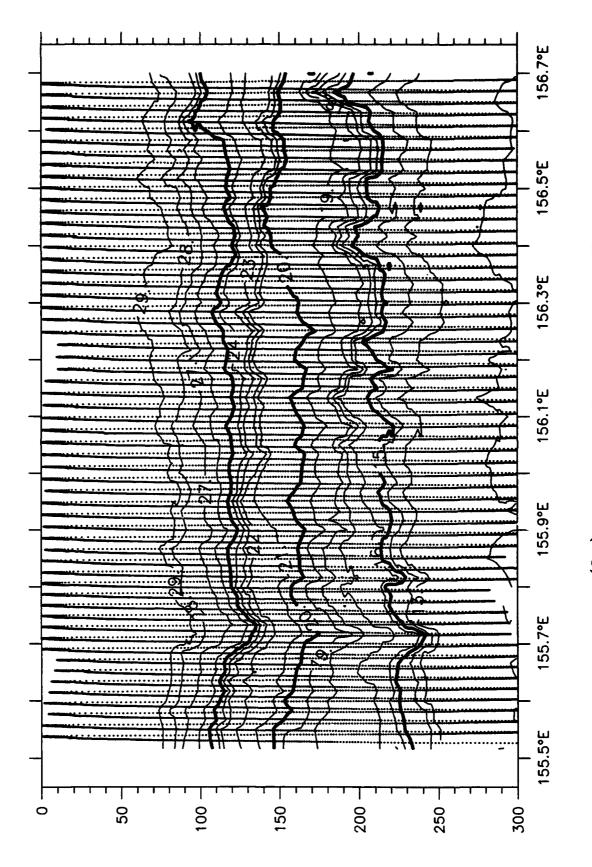
T(°C), W2E, 06 February 1993



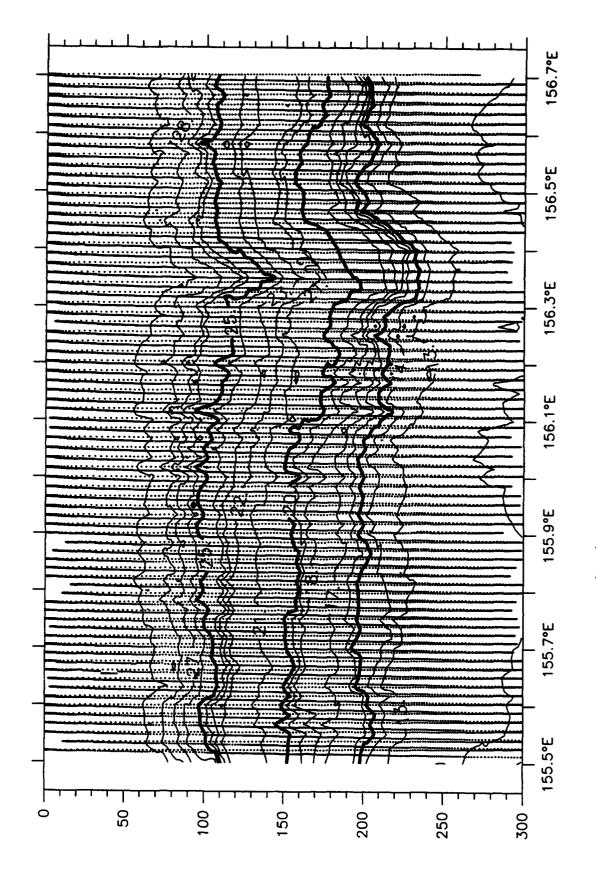
T(°C), W2E, 08 February 1993



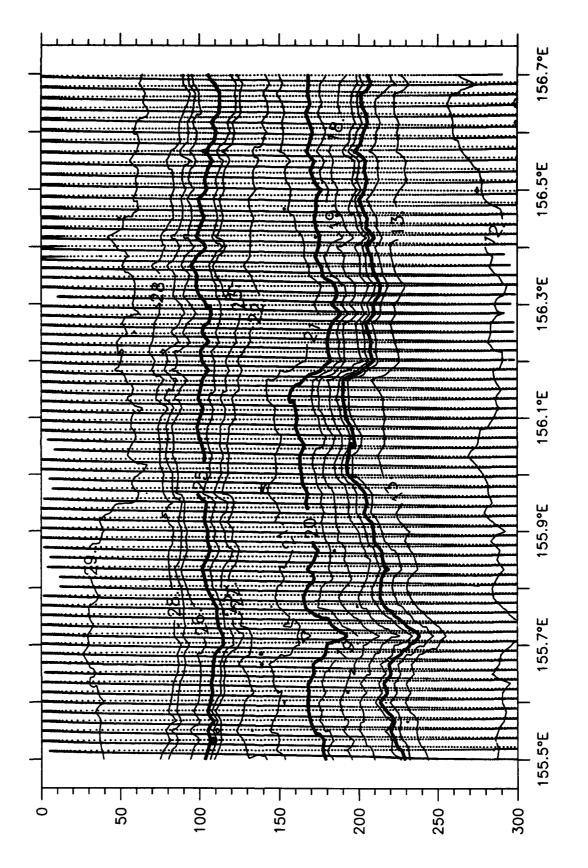
T(°C), W2E, 10 February 1993



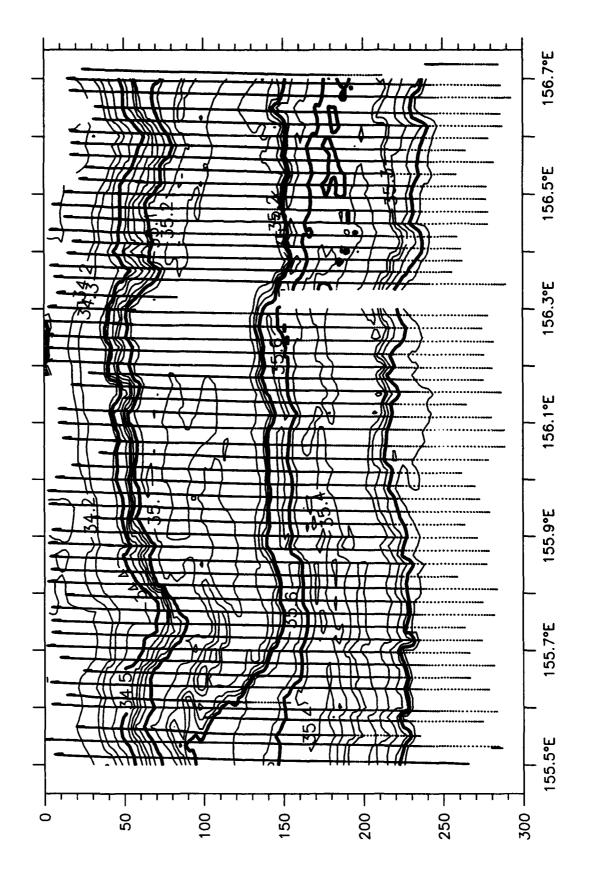
T(°C), W2E, 11 February 1993



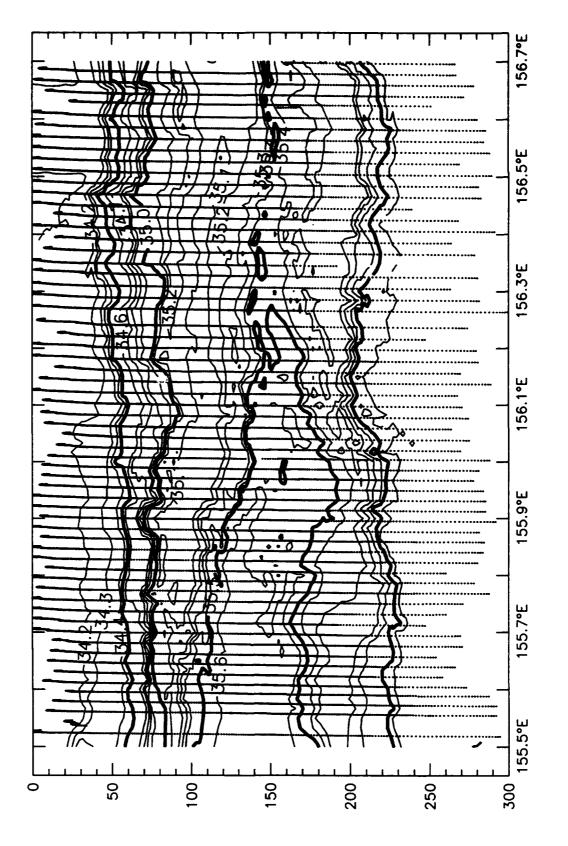
T(°C), W2E, 13 February 1993



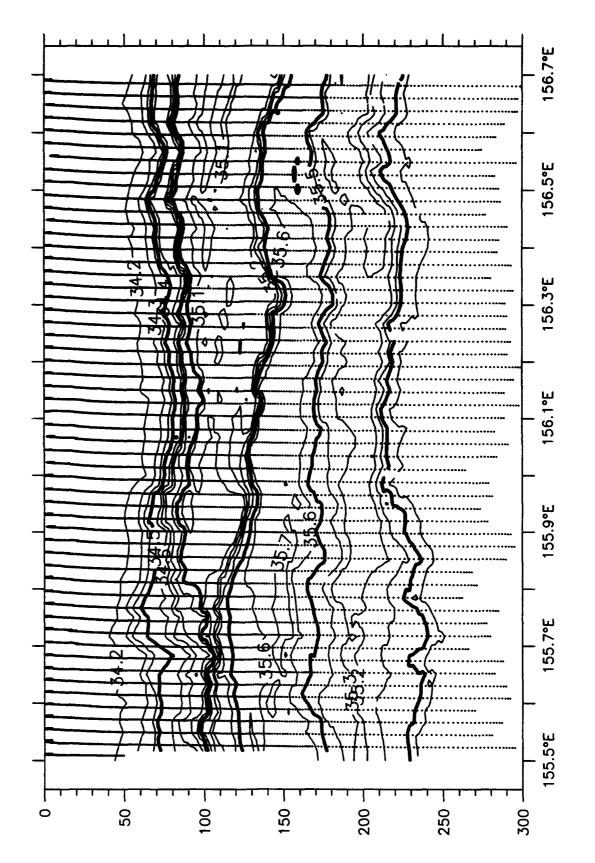
T(°C), W2E, 14 February 1993



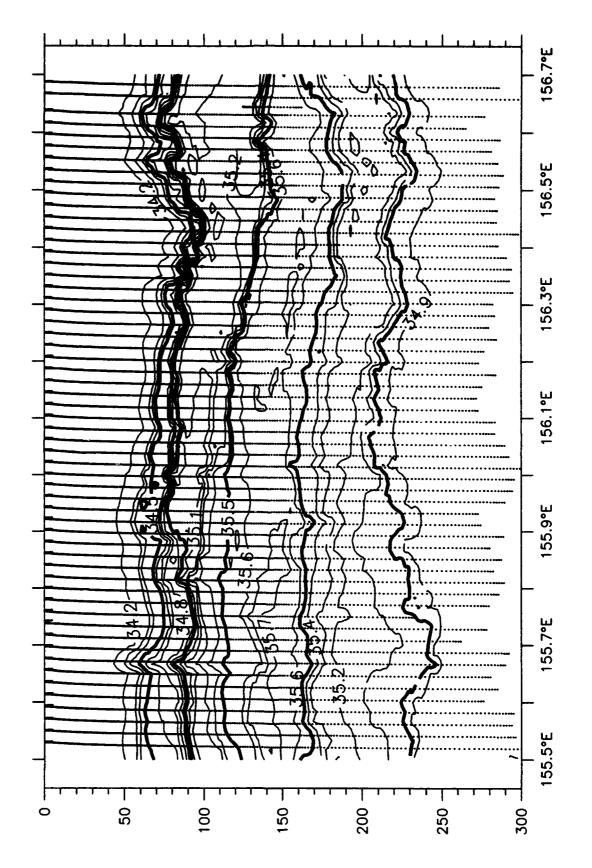
S(psu), W2E, 28 January 1993



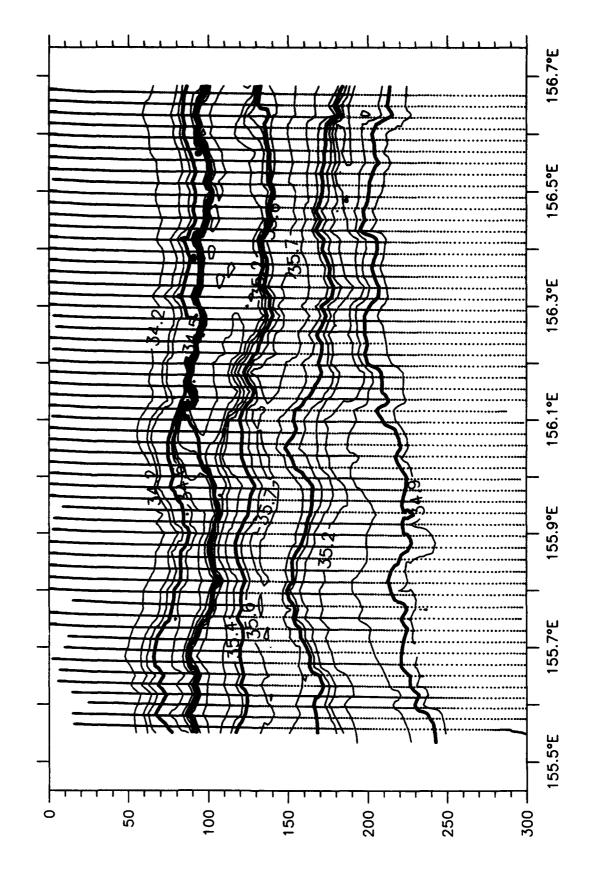
S(psu), W2E, 29 January 1993



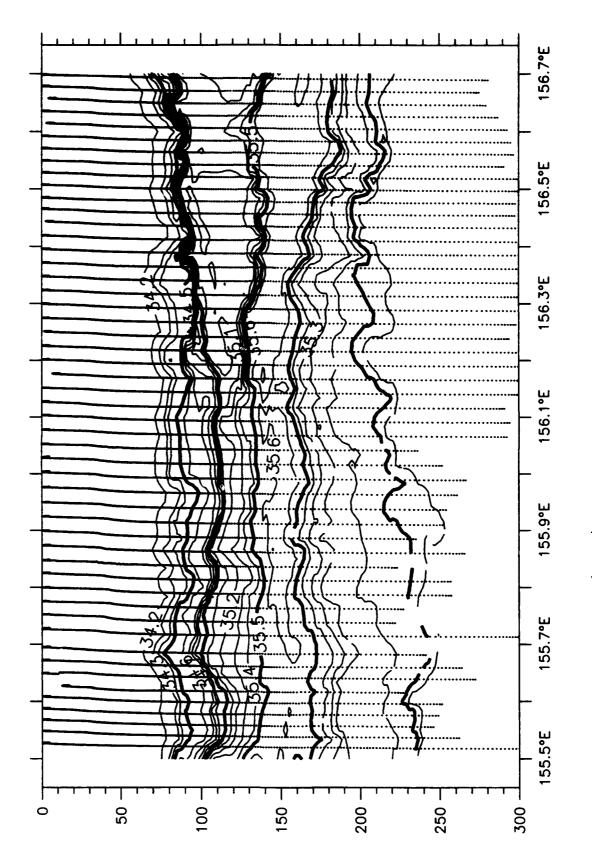
S(psu), W2E, 31 January 1993



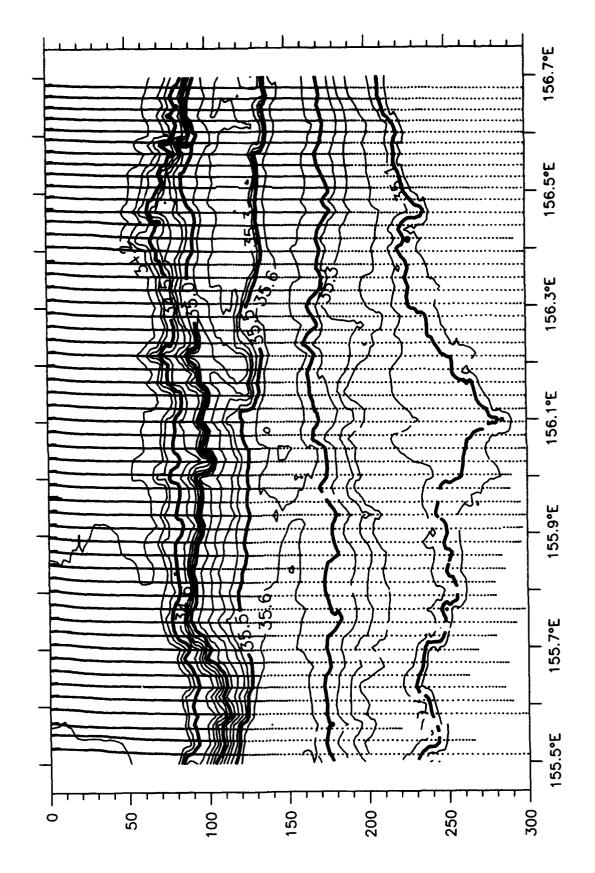
S(psu), W2E, 1 February 1993



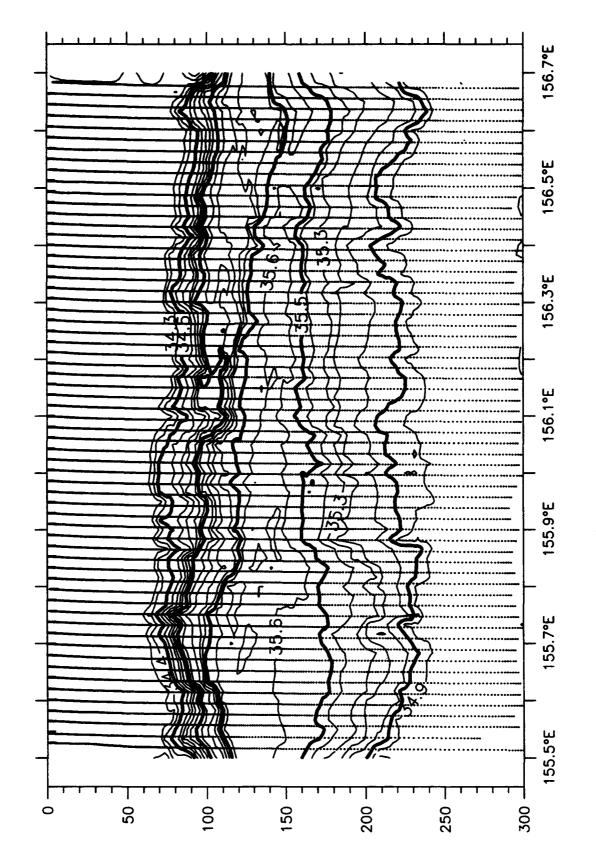
S(psu), W2E, 3 February 1993



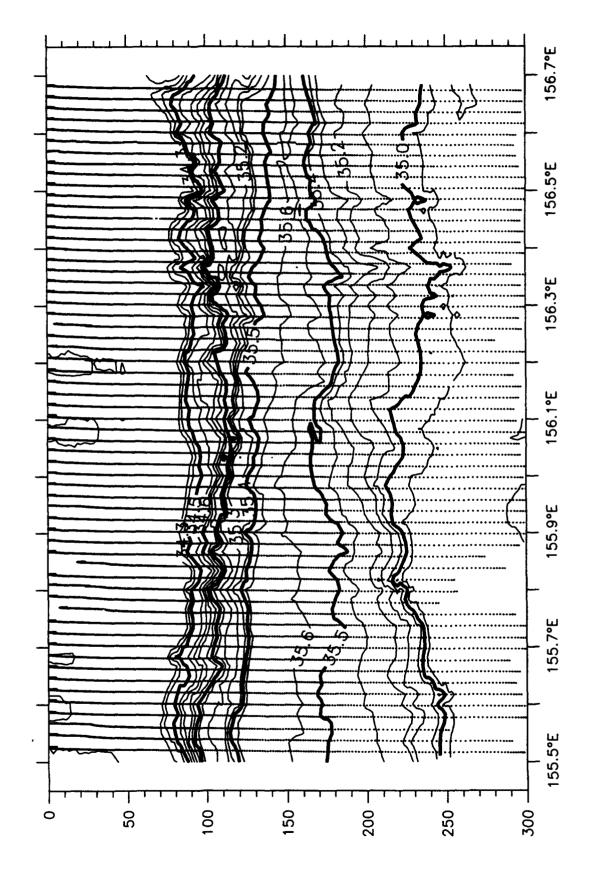
S(psu), W2E, 04 February 1993



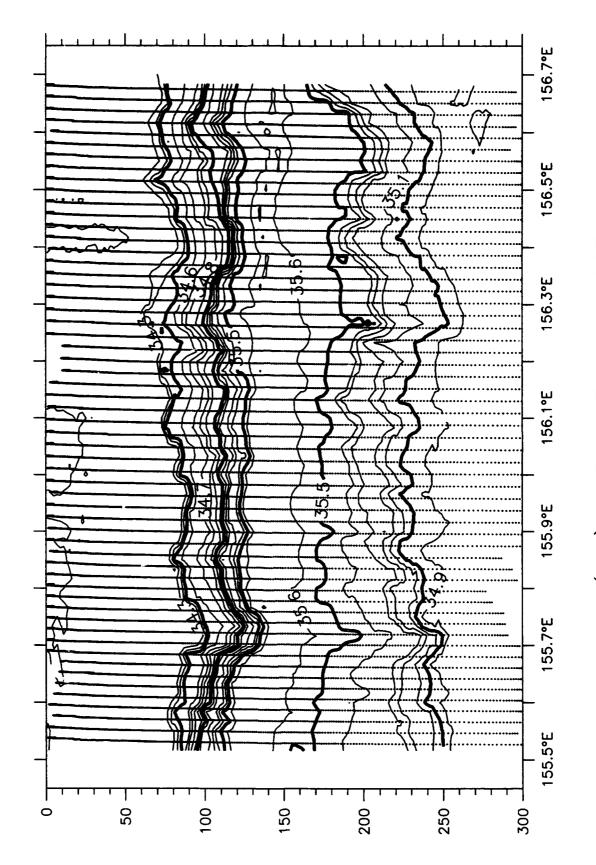
S(psu), W2E, 06 February 1993



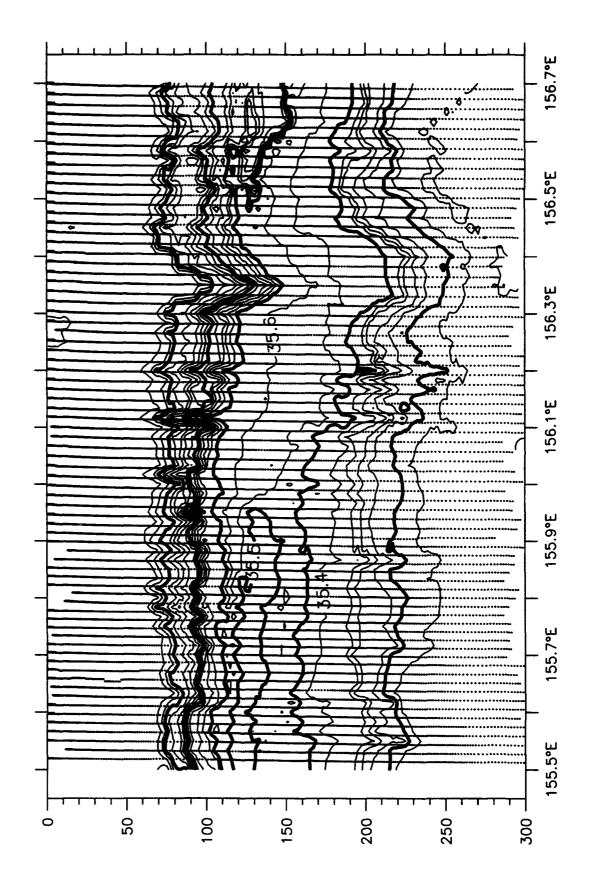
S(psu), W2E, 08 February 1993



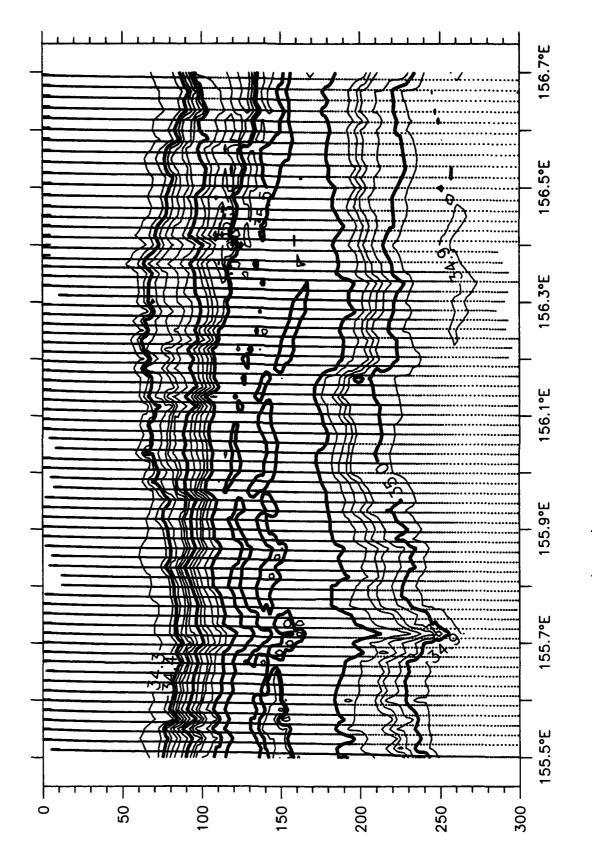
S(psu), W2E, 10 February 1993



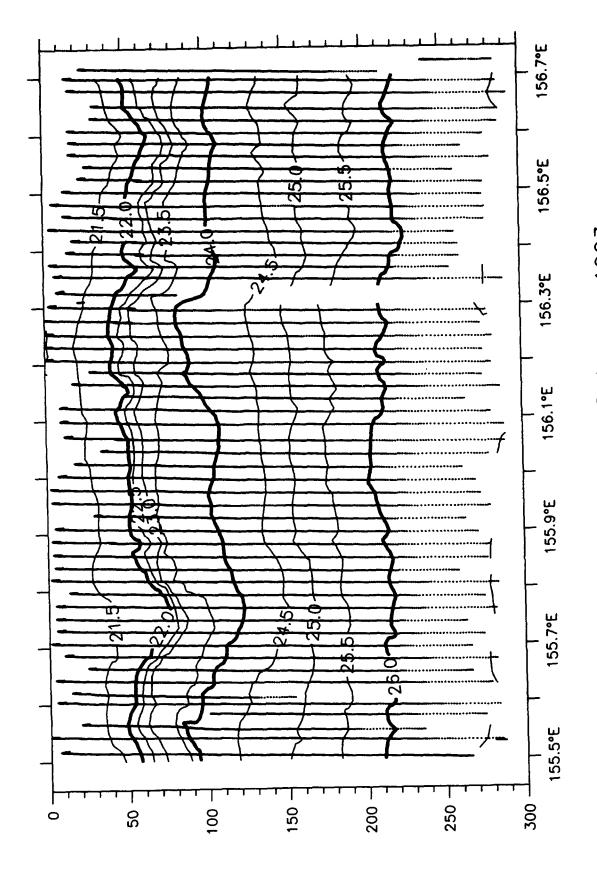
S(psu), W2E, 11 February 1993



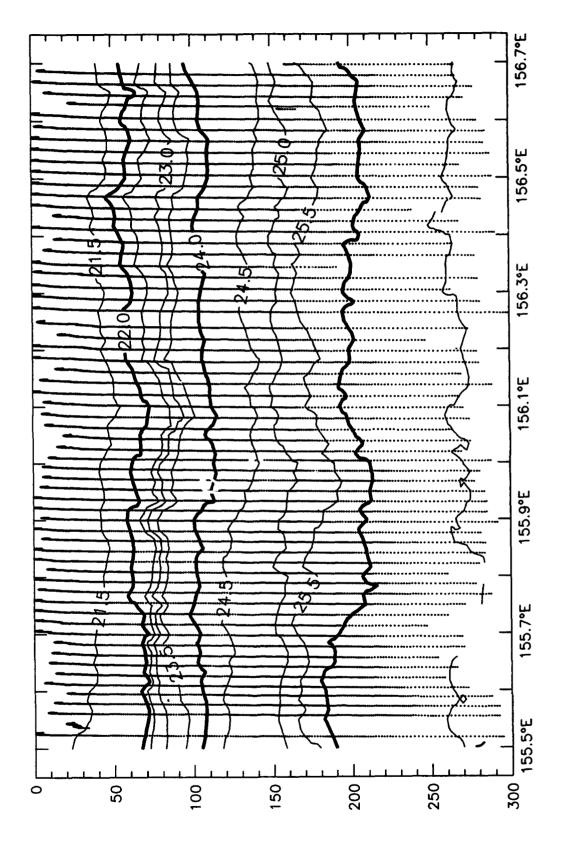
S(psu), W2E, 13 February 1993



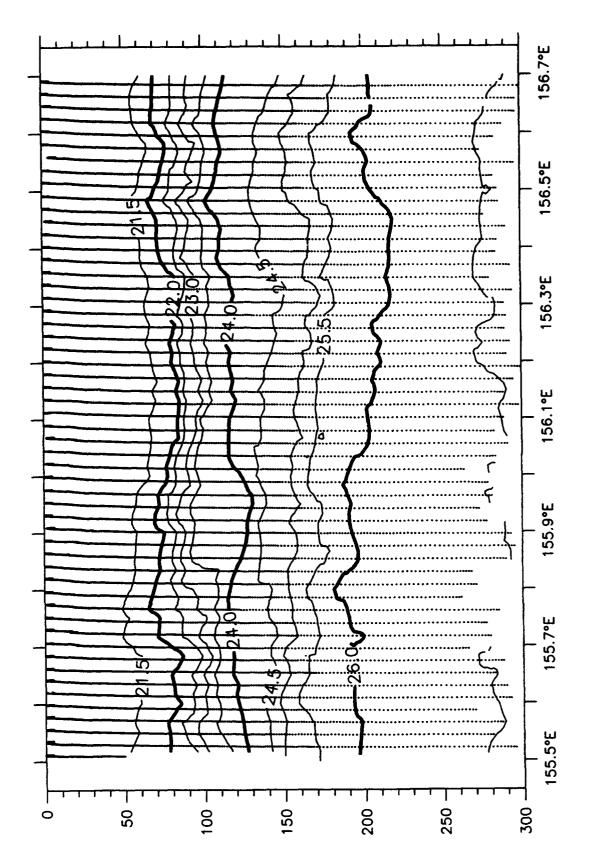
S(psu), W2E, 14 February 1993



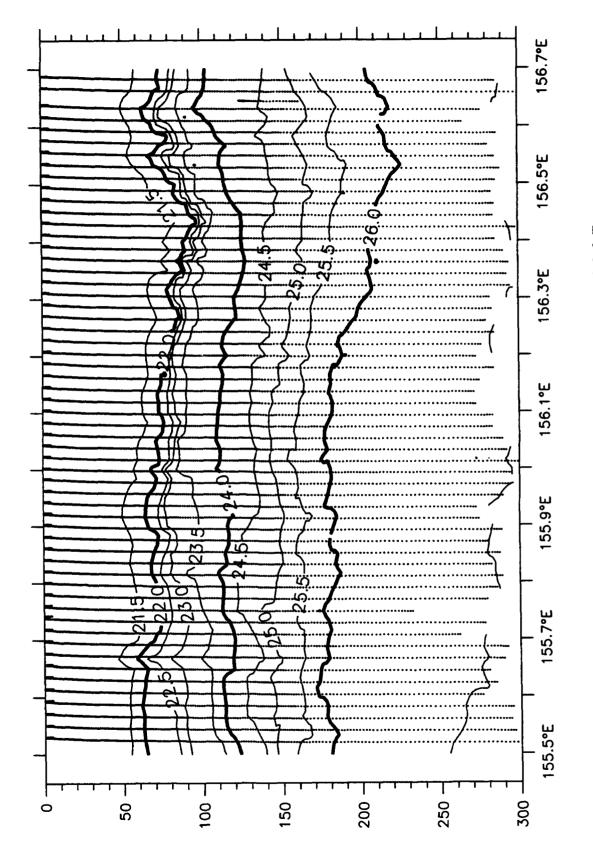
Sigma—t, W2E, 28 January 1993



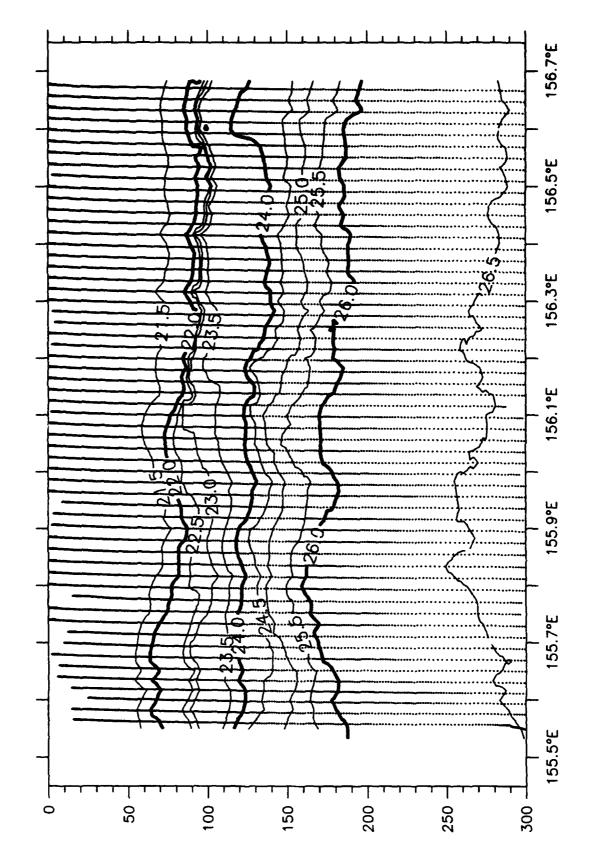
Sigma—t, W2E, 29 January 1993



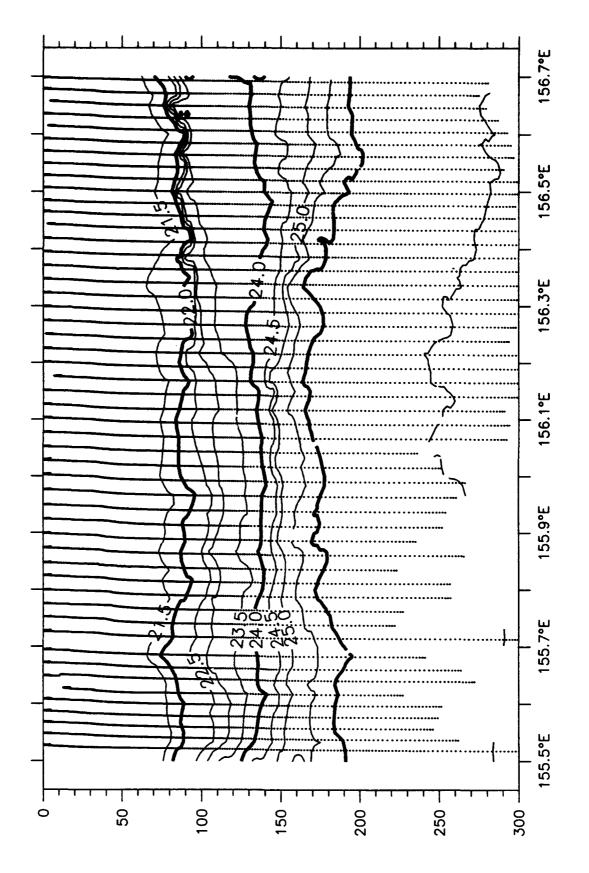
Sigma-t, W2E, 31 January 1993



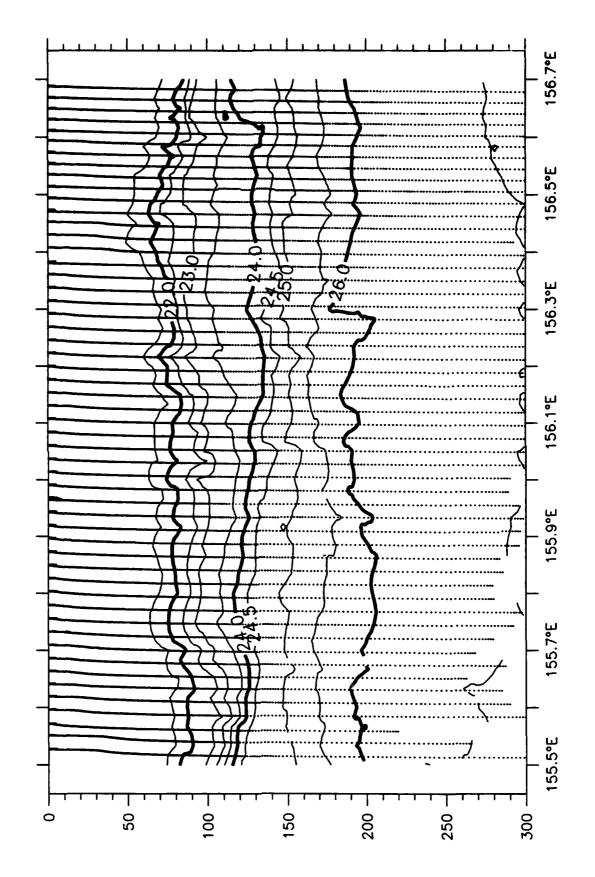
Sigma—t, W2E, 1 February 1993



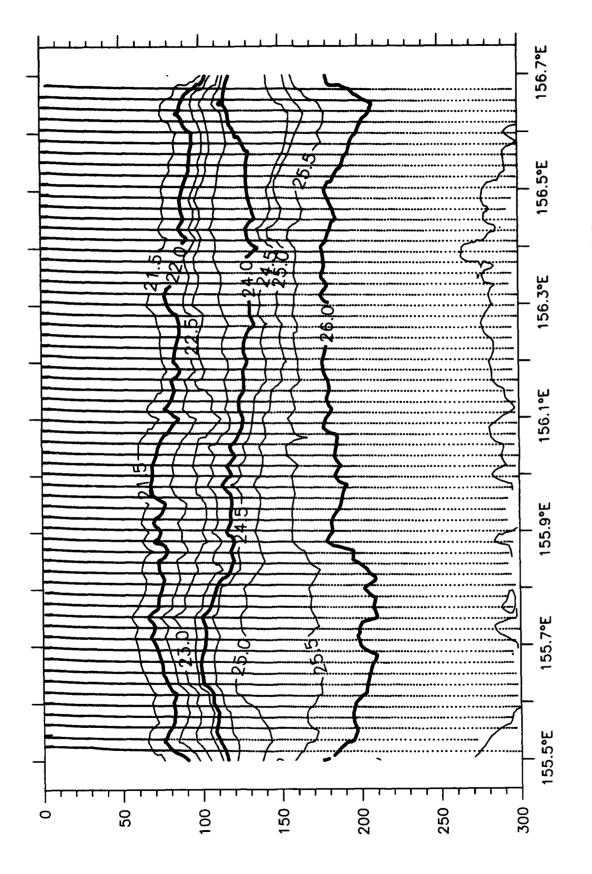
Sigma-t, W2E, 3 February 1993



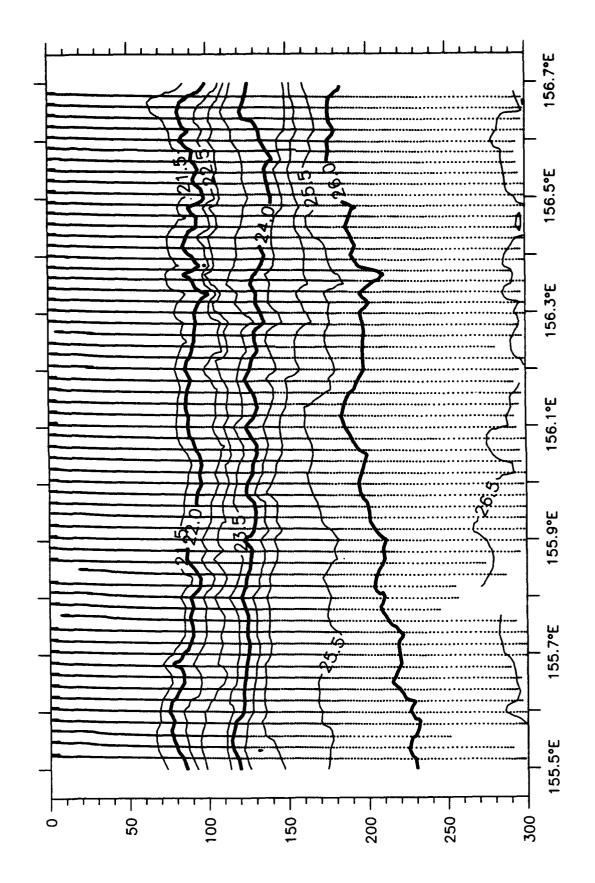
Sigma—t, W2E, 04 February 1993



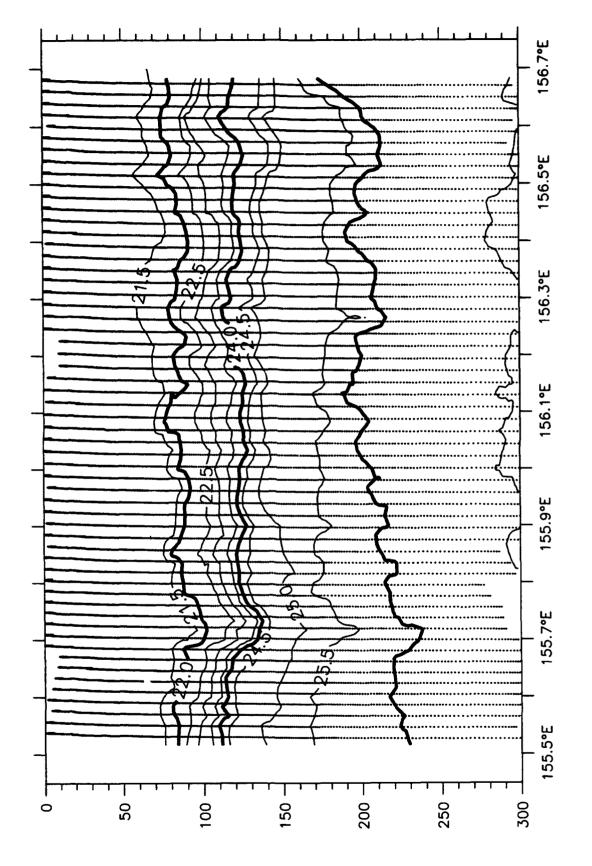
Sigma-t, W2E, 06 February 1993



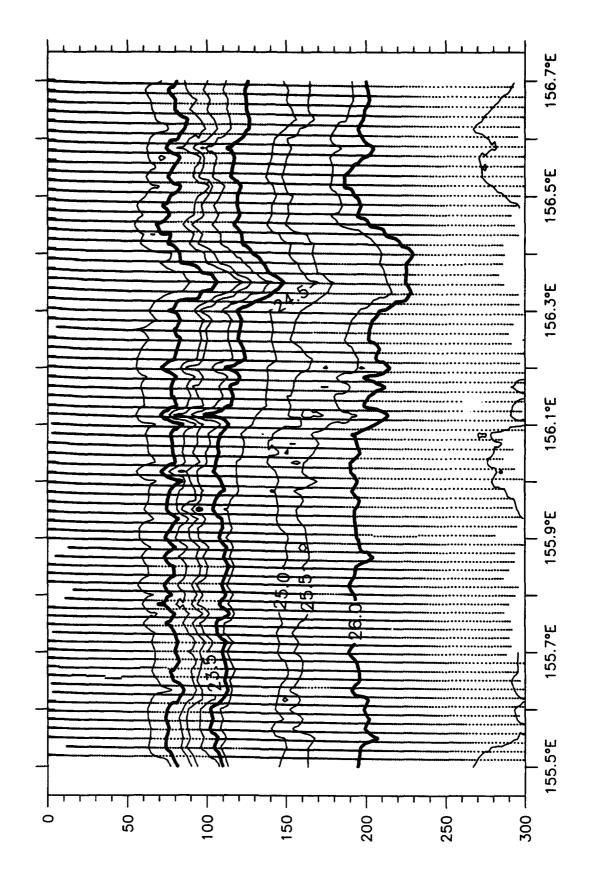
Sigma—t, W2E, 08 February 1993



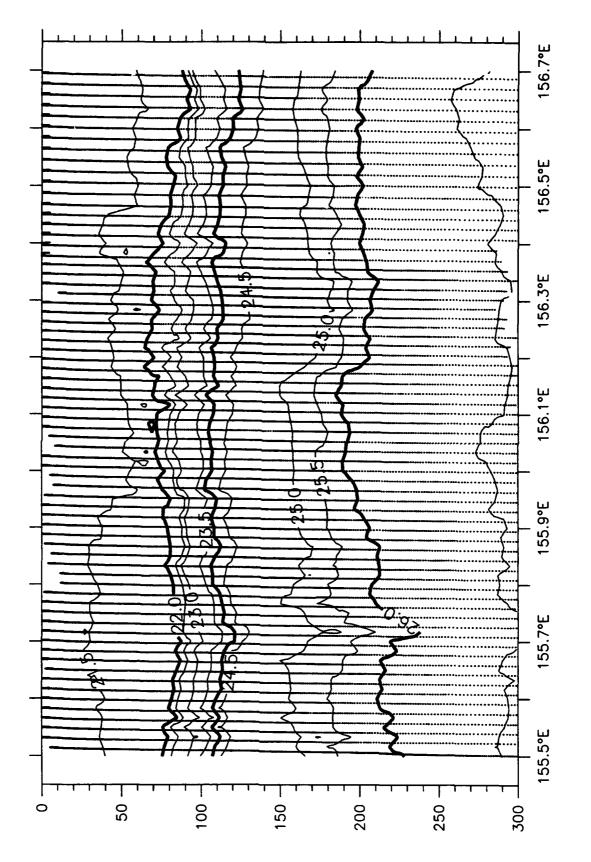
Sigma-t, W2E, 10 February 1993



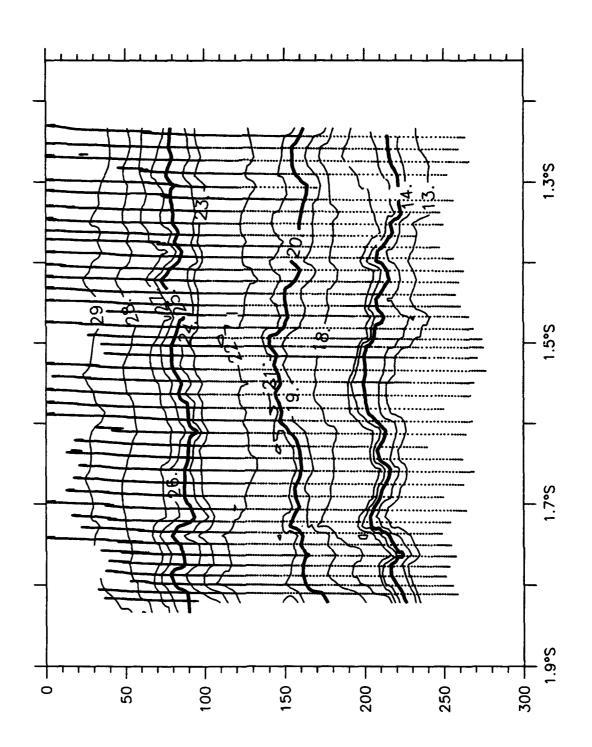
Sigma—t, W2E, 11 February 1993



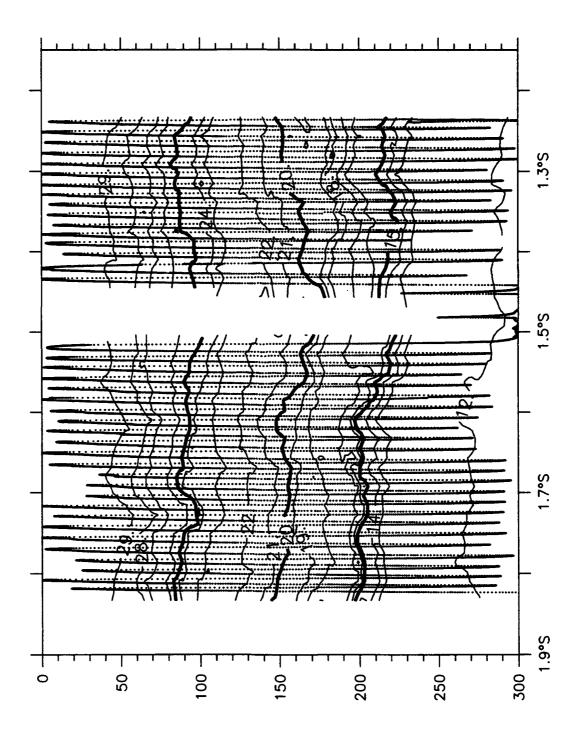
Sigma-t, W2E, 13 February 1993



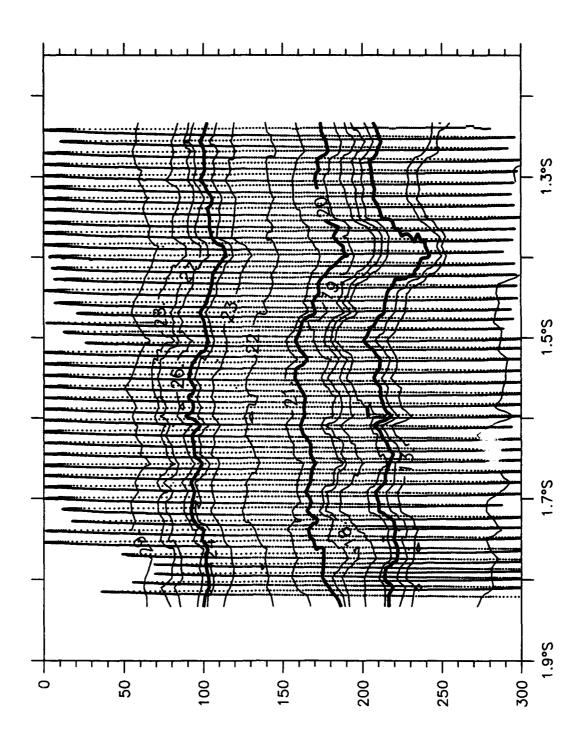
Sigma—t, W2E, 14 February 1993



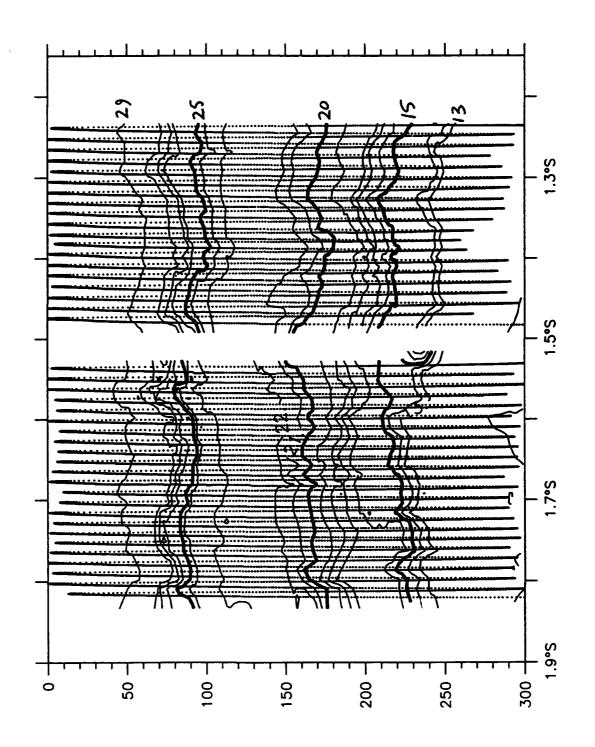
T(°C), E2N, 28 January 1993



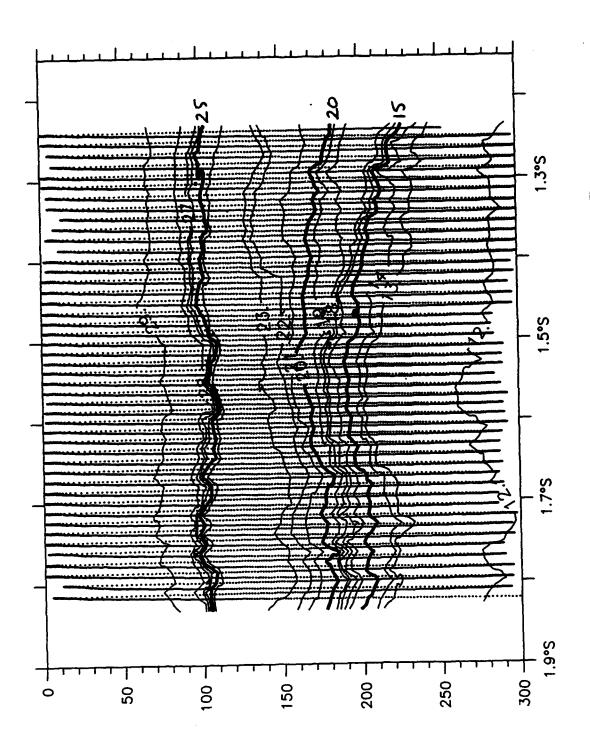
T(°C), E2N, 30 January 1993



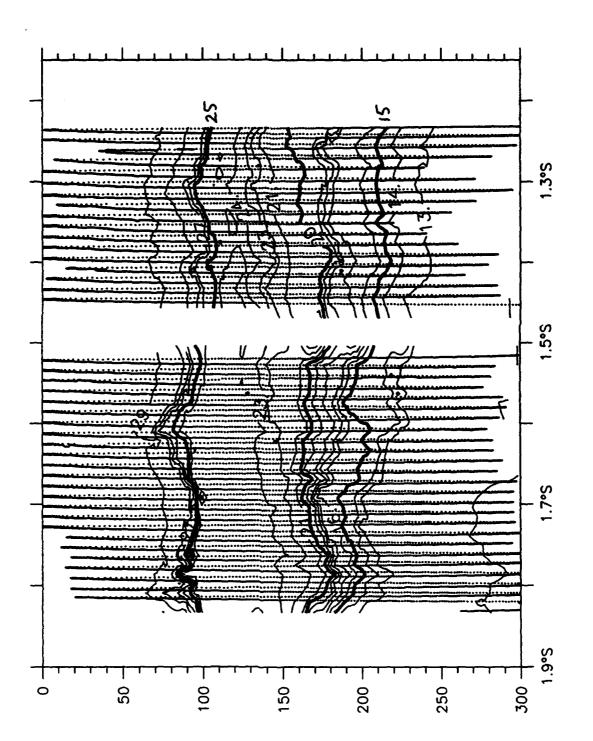
T(°C), E2N, 31 January 1993



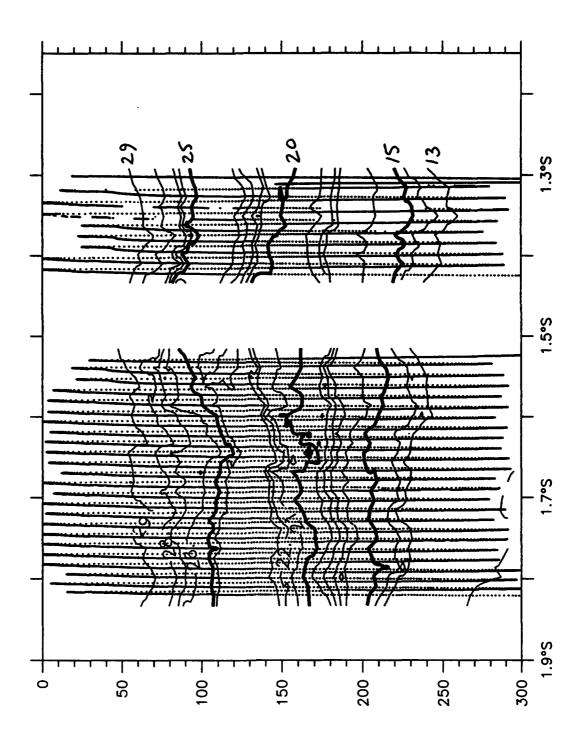
T(°C), E2N, 1 February 1993



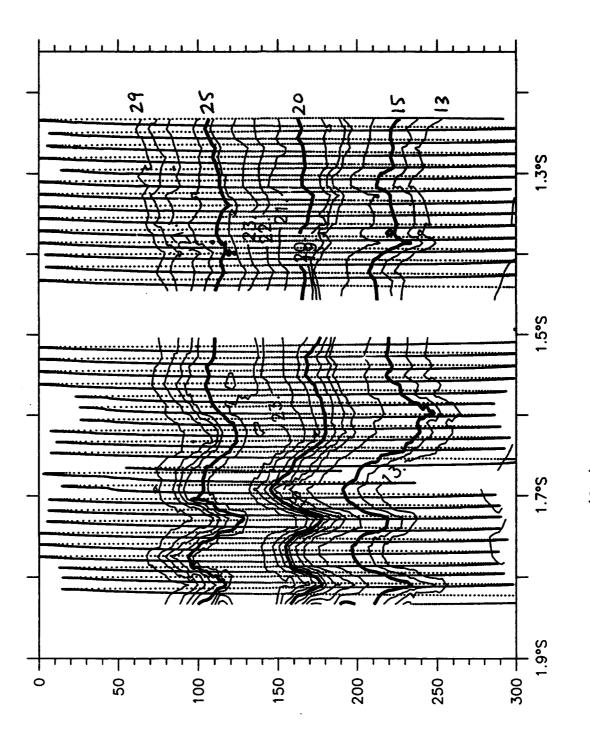
T(°C), E2N, 3 February 1993



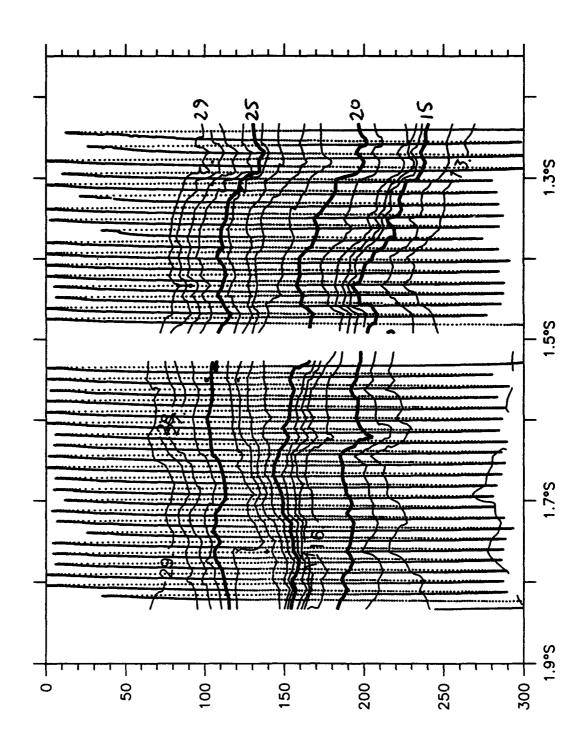
T(°C), E2N, 5 February 1993



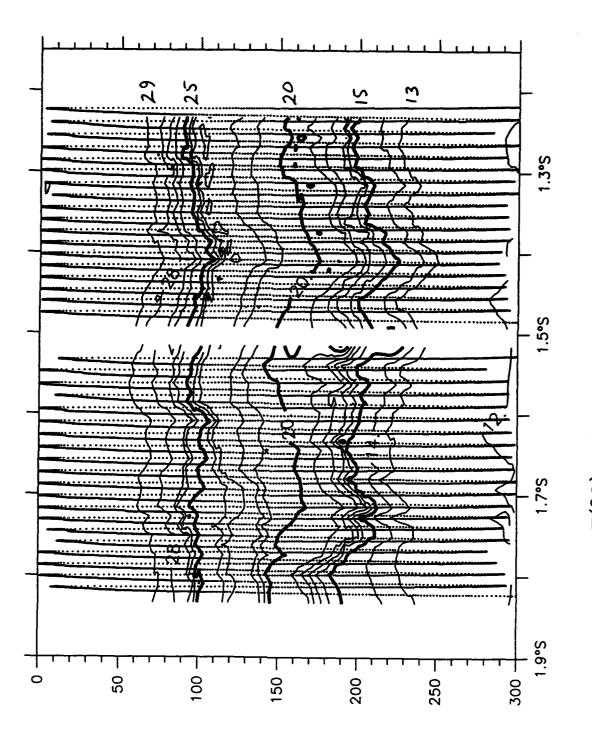
T(°C), E2N, 6 February 1993



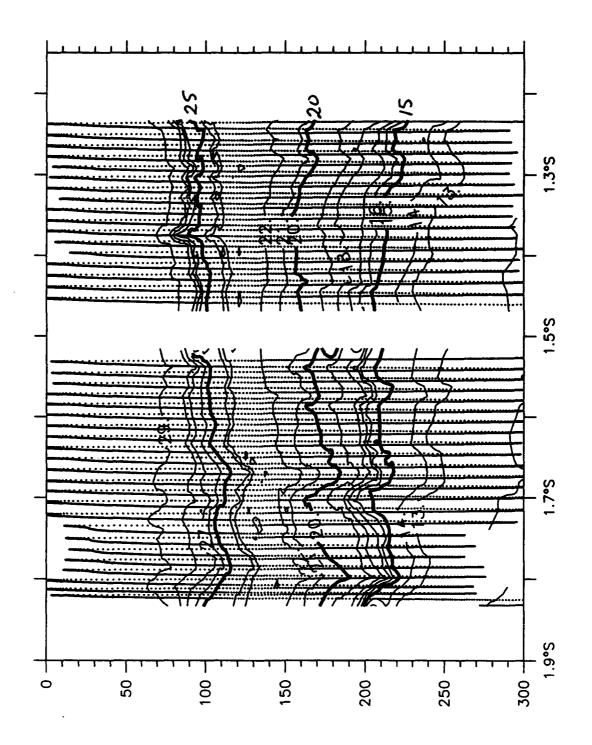
T(°C), E2N, 9 February 1993



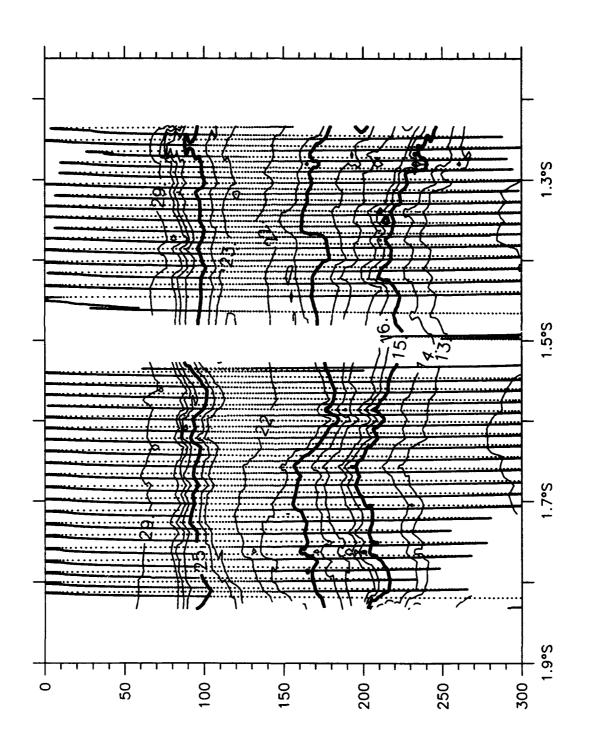
T(°C), E2N, 10 February 1993



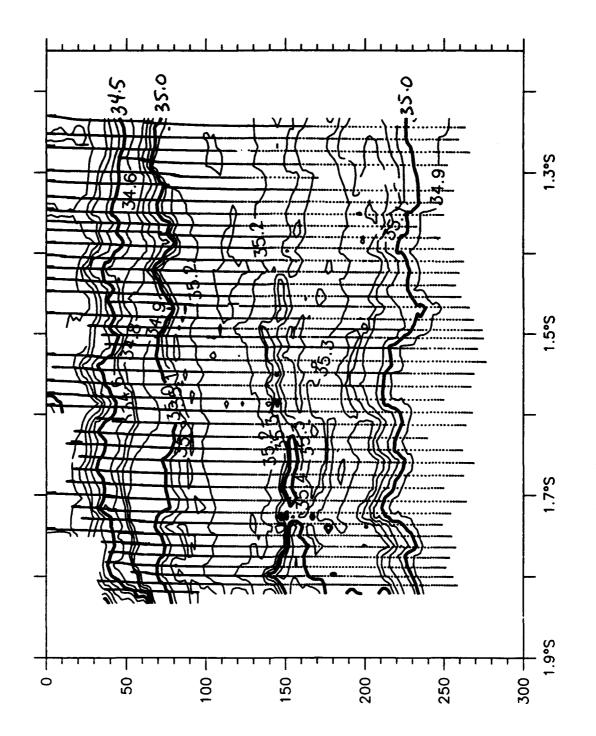
T(°C), E2N, 11 February 1993



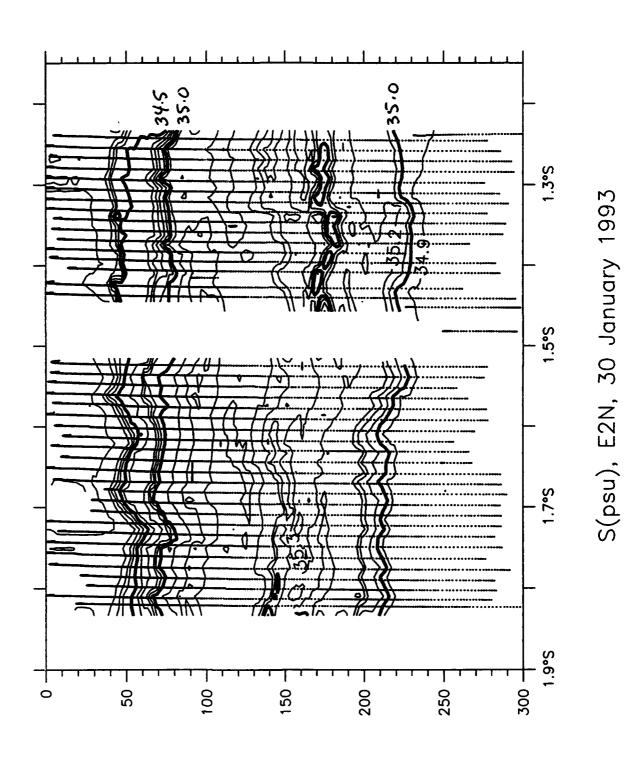
T(°C), E2N, 13 February 1993

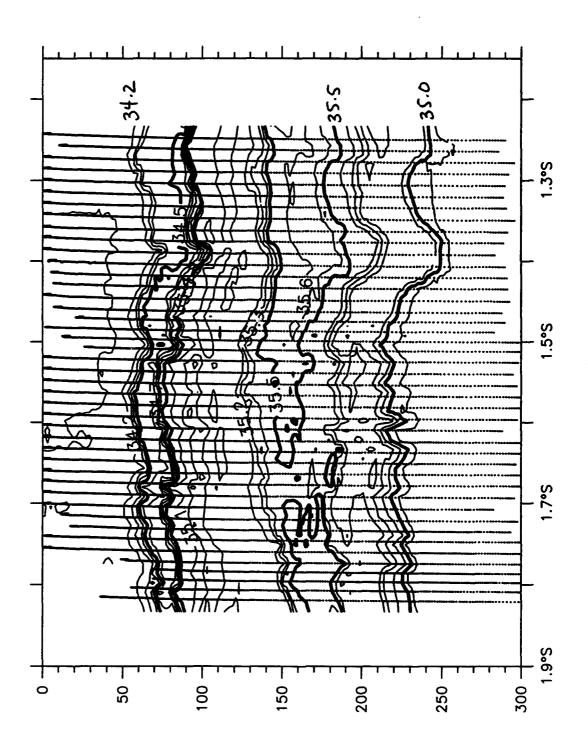


T(°C), E2N, 15 February 1993

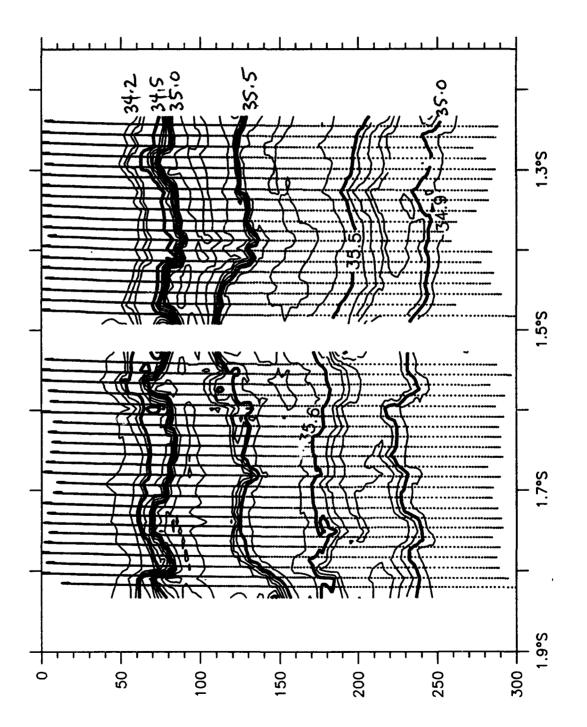


S(psu), E2N, 28 January 1993

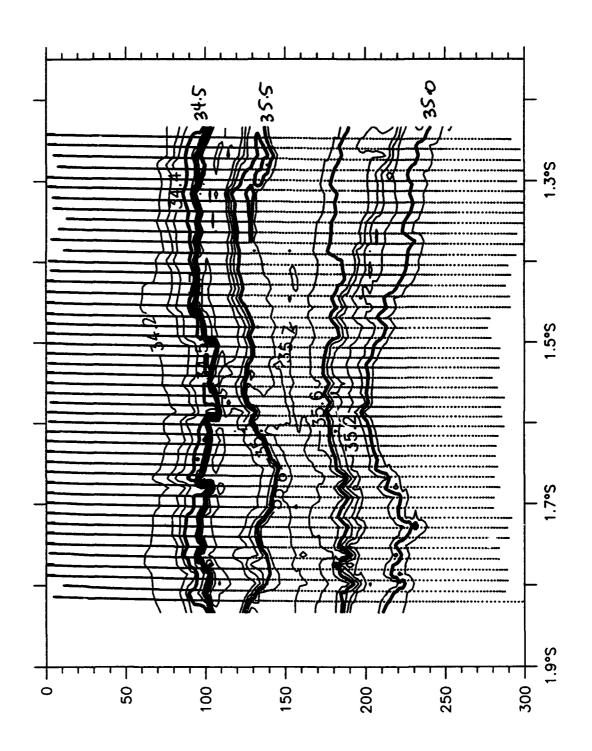




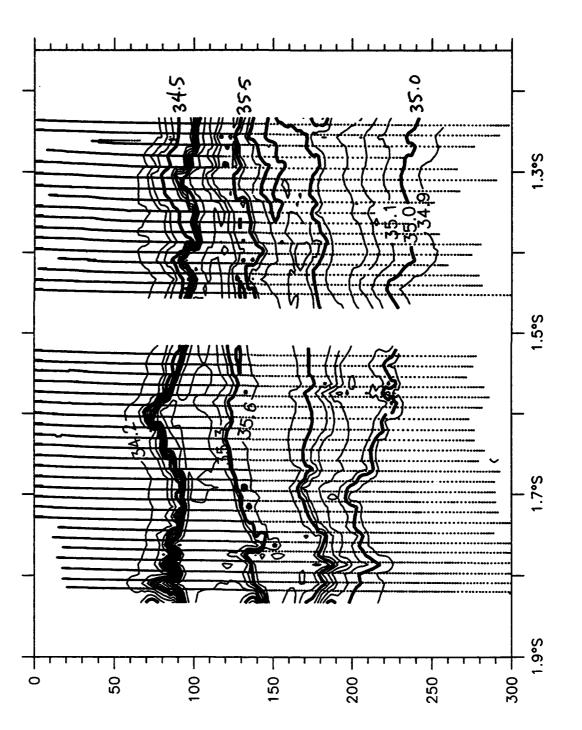
S(psu), E2N, 31 January 1993



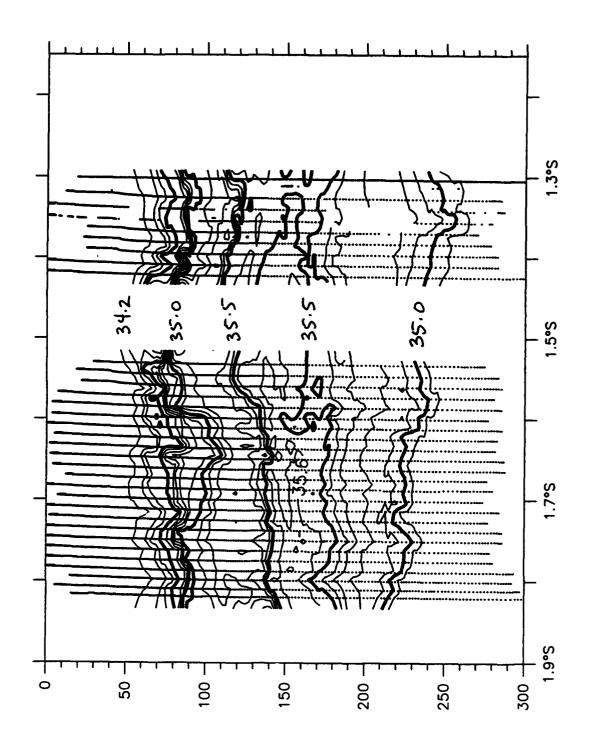
S(psu), E2N, 1 February 1993



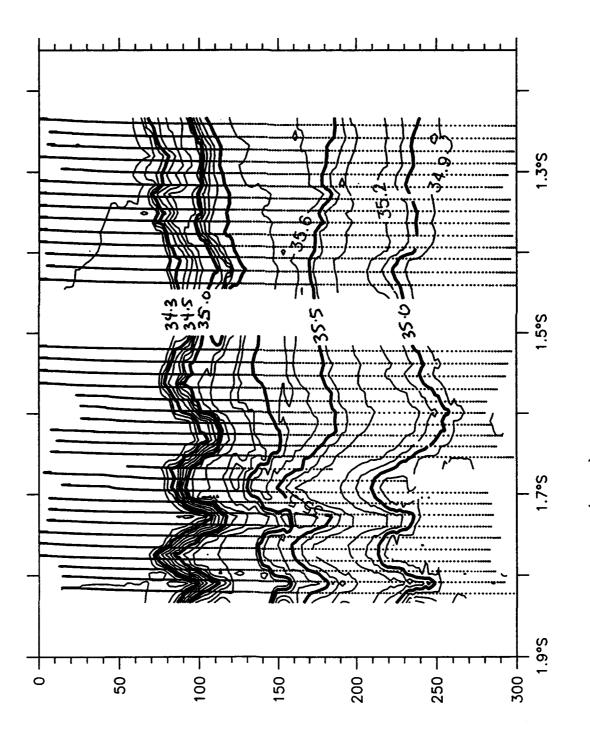
S(psu), E2N, 3 February 1993



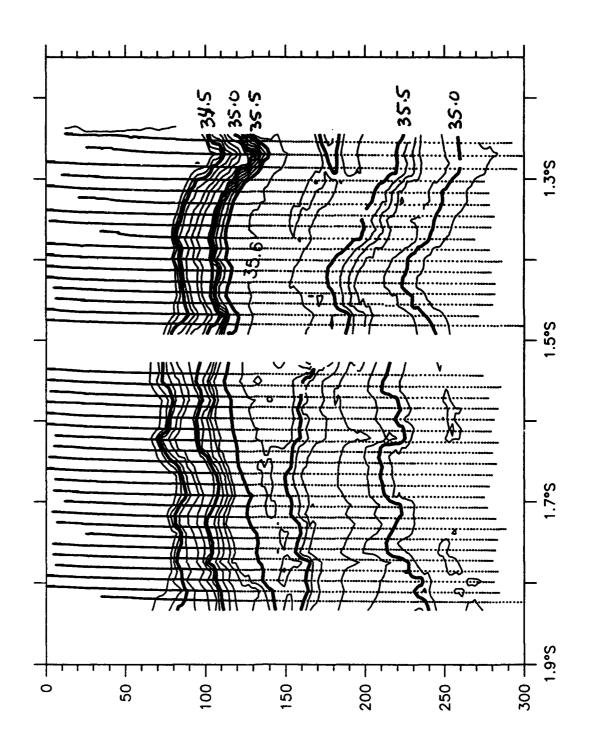
S(psu), E2N, 5 February 1993



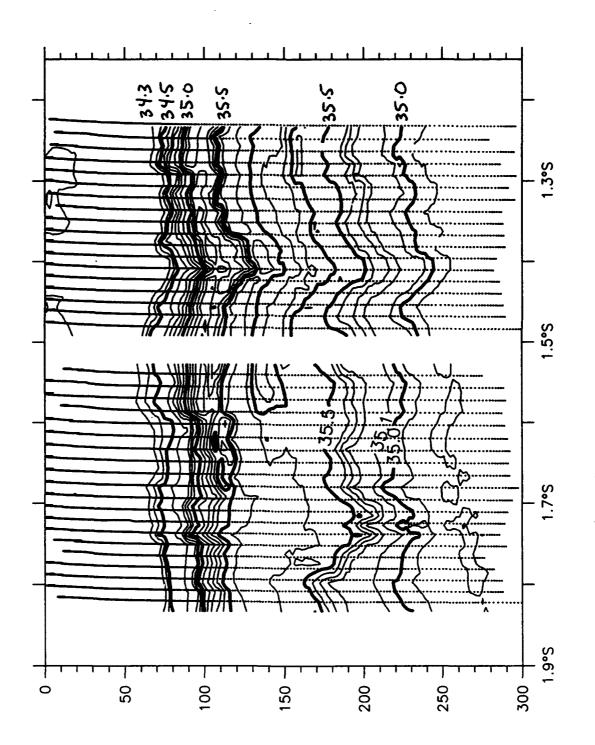
S(psu), E2N, 6 February 1993



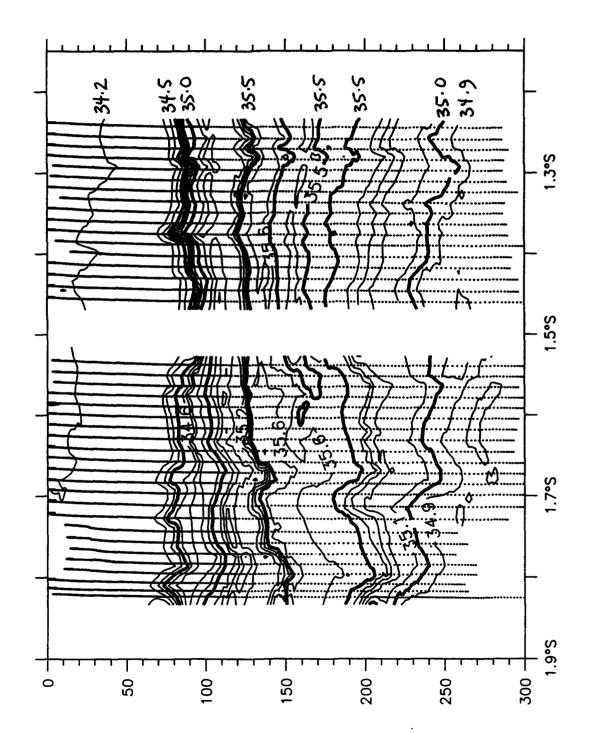
S(psu), E2N, 9 February 1993



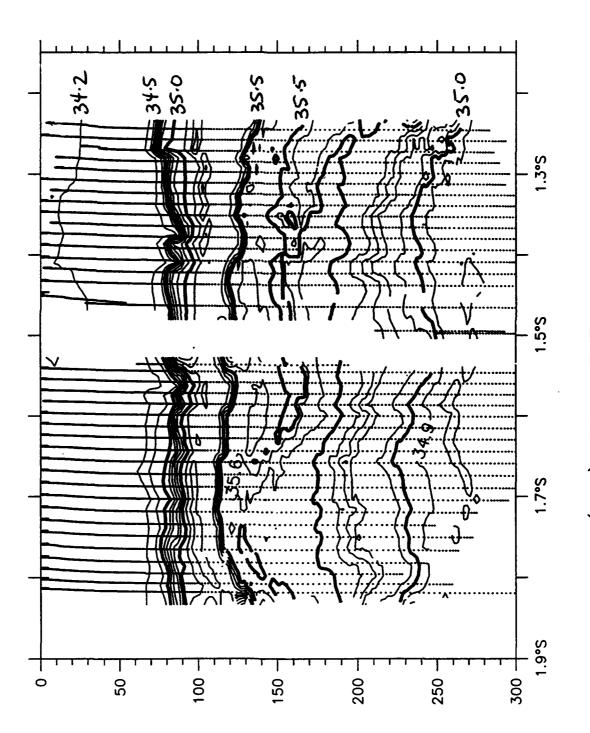
S(psu), E2N, 10 February 1993



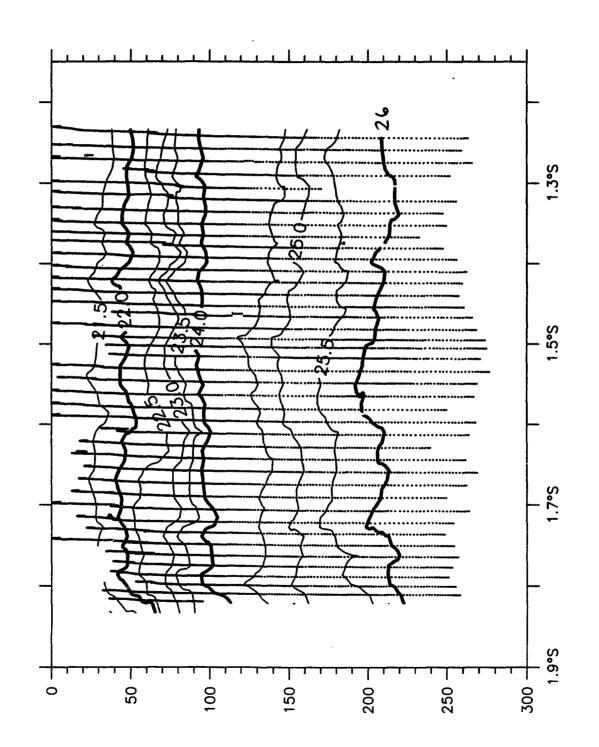
S(psu), E2N, 11 February 1993



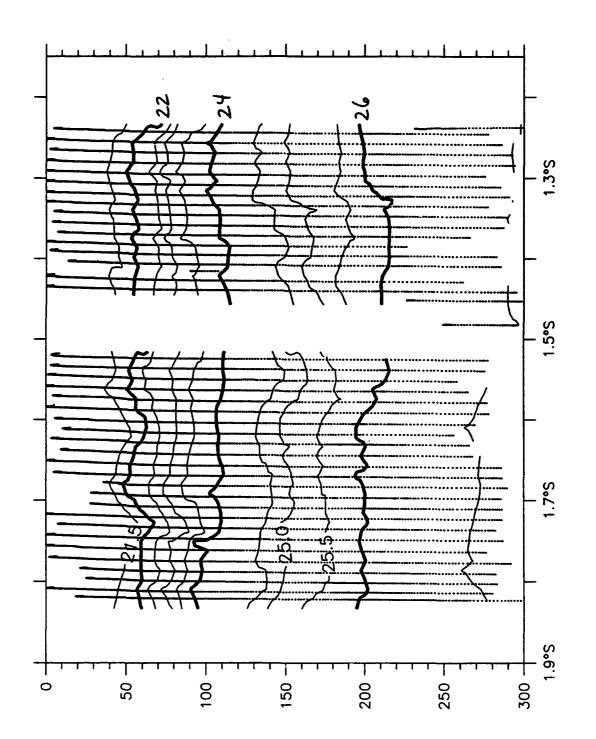
S(psu), E2N, 13 February 1993



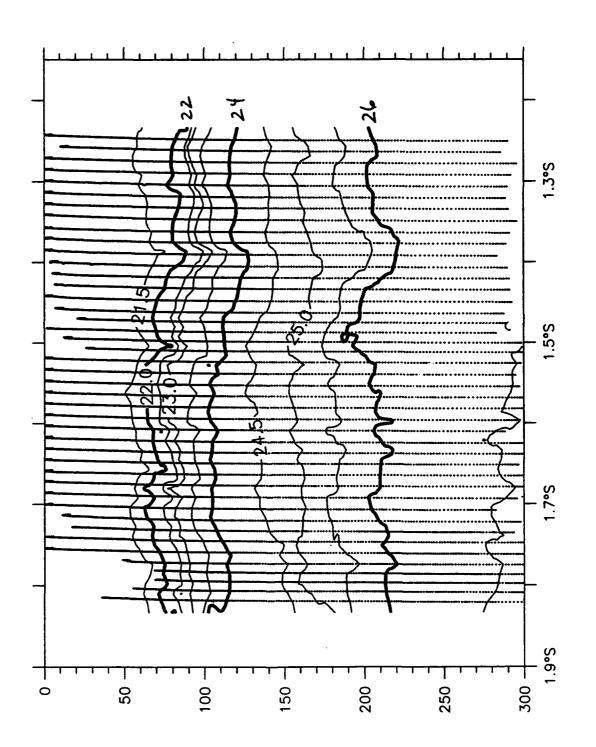
S(psu), E2N, 15 February 1993



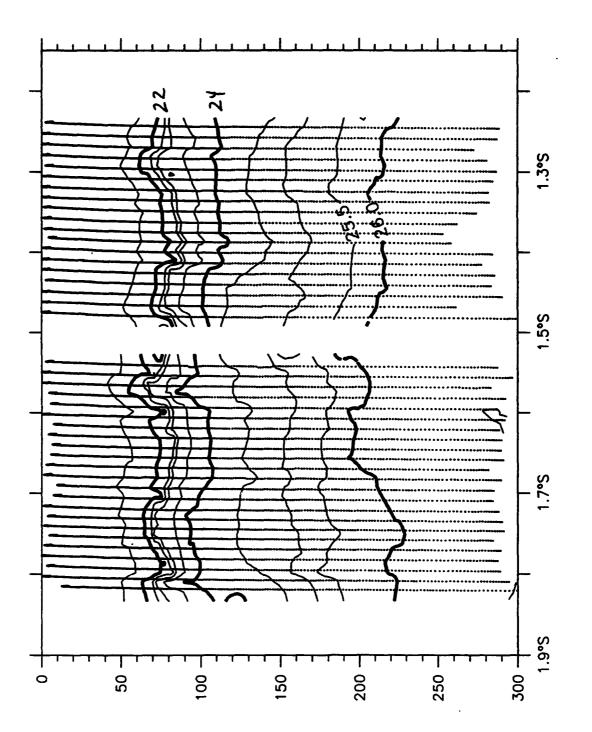
Sigma—t, E2N, 28 January 1993



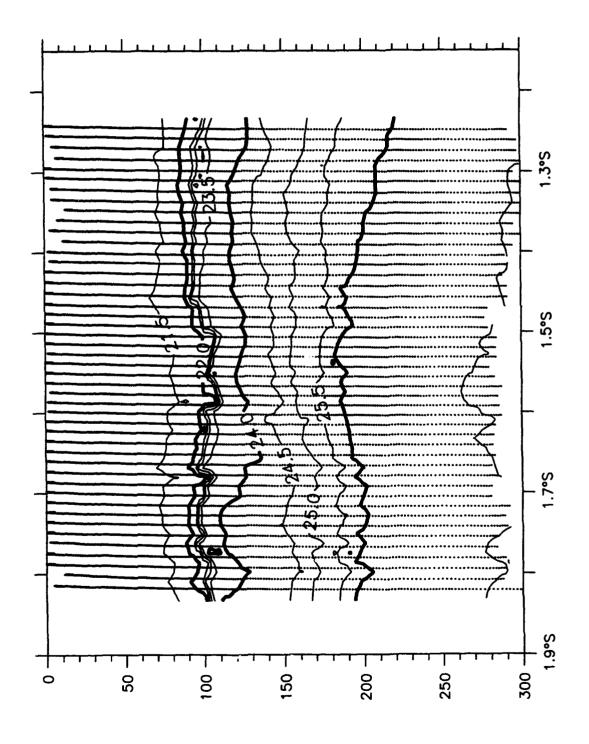
Sigma-t, E2N, 30 January 1993



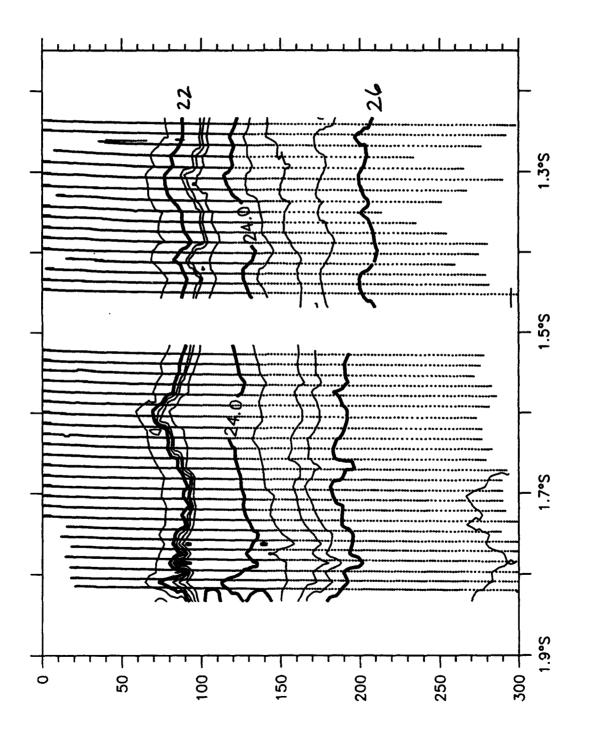
Sigma-t, E2N, 31 January 1993



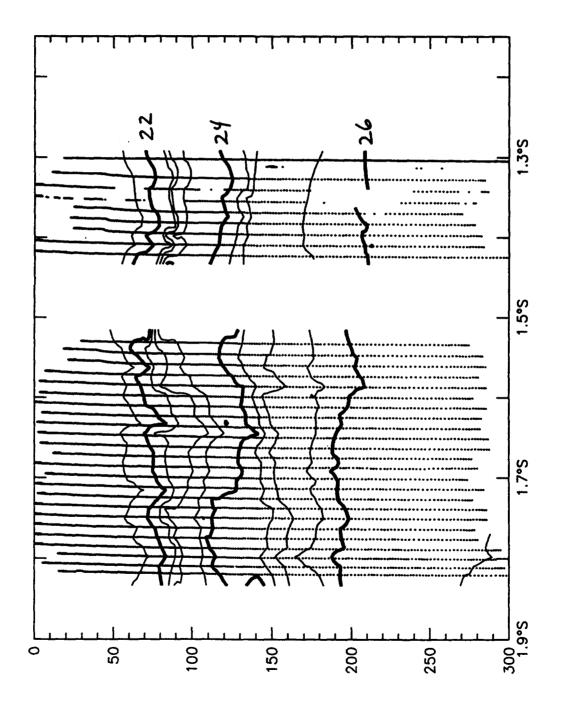
Sigma-t, E2N, 1 February 1993



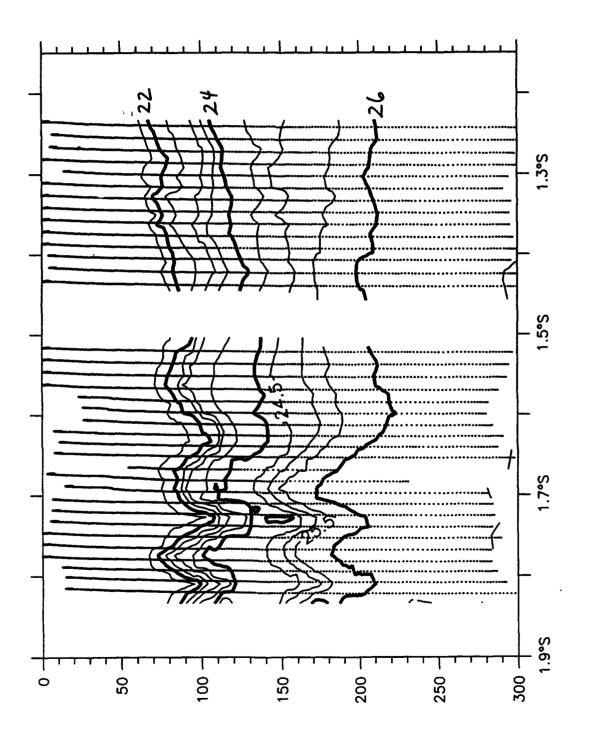
Sigma—t, E2N, 3 February 1993



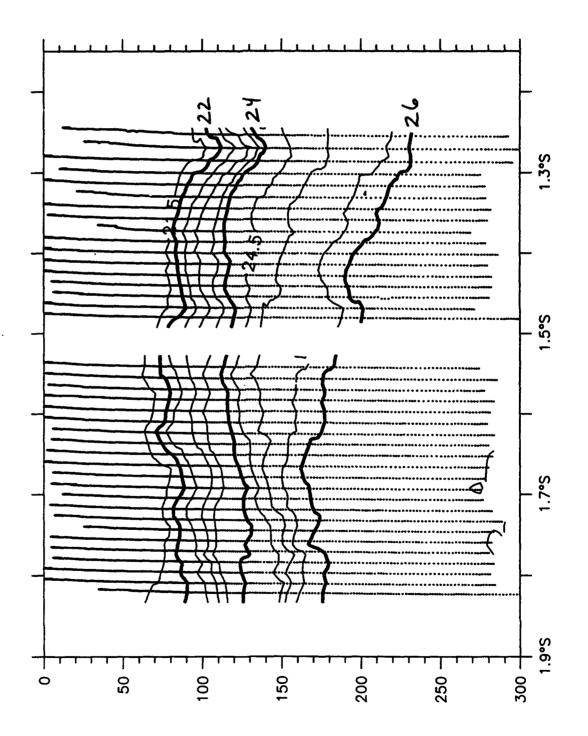
Sigma—t, E2N, 5 February 1993



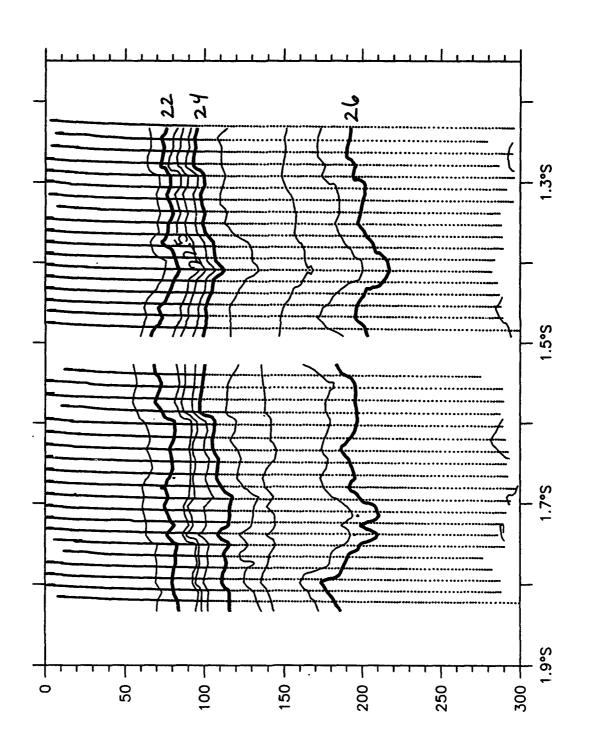
Sigma—t, E2N, 06 February 1993



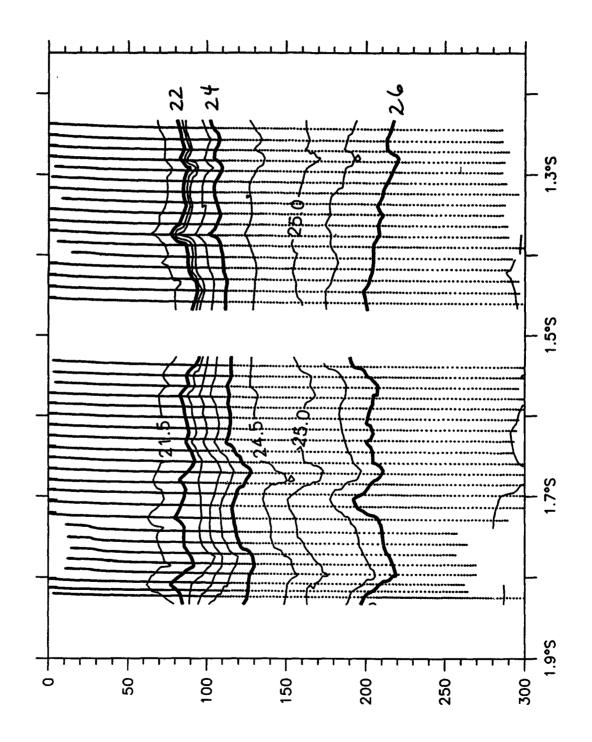
Sigma—t, E2N, 9 February 1993



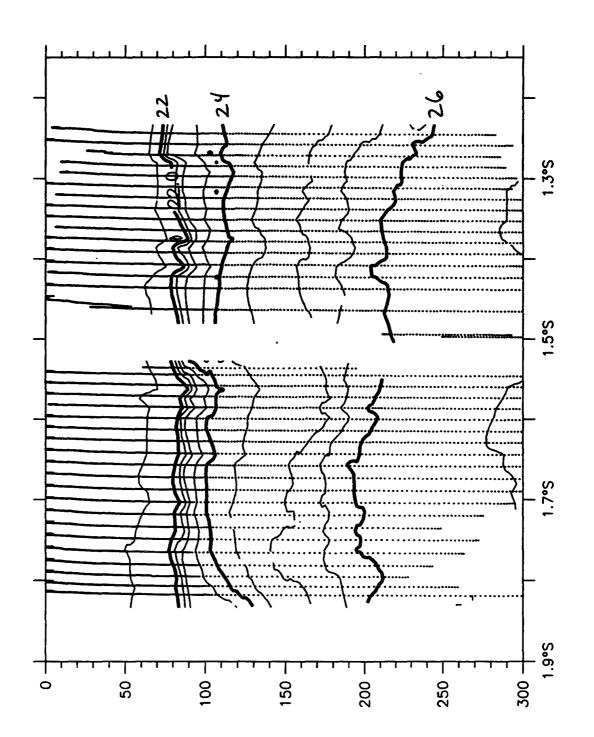
Sigma-t, E2N, 10 February 1993



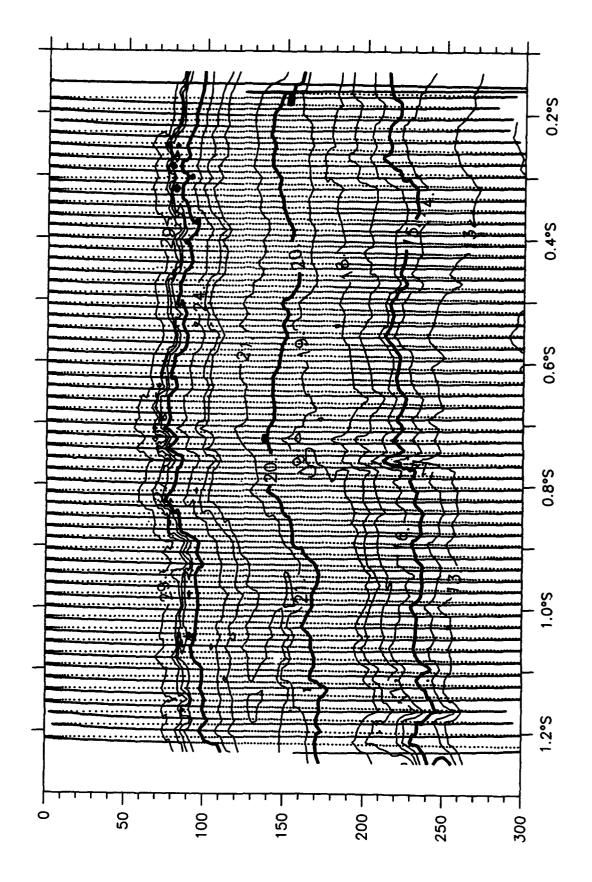
Sigma—t, E2N, 11 February 1993



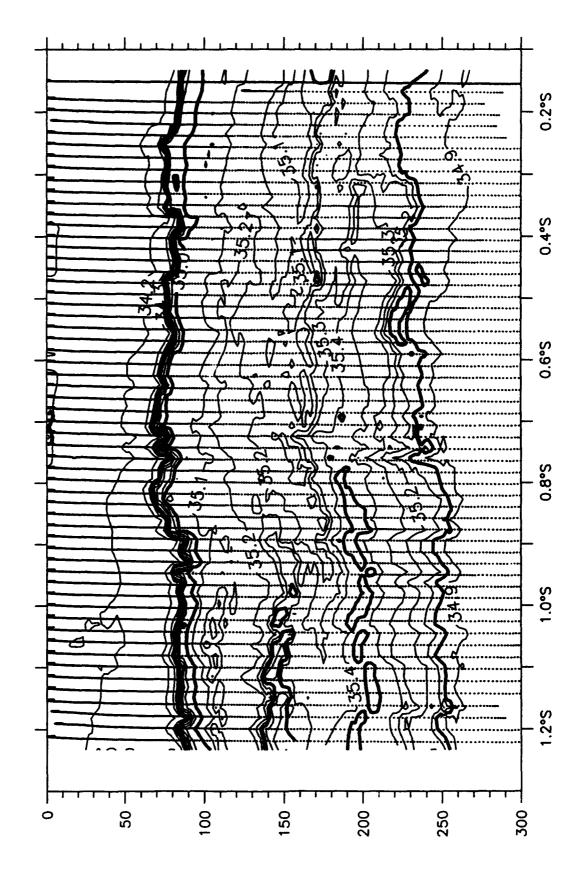
Sigma-t, E2N, 13 February 1993



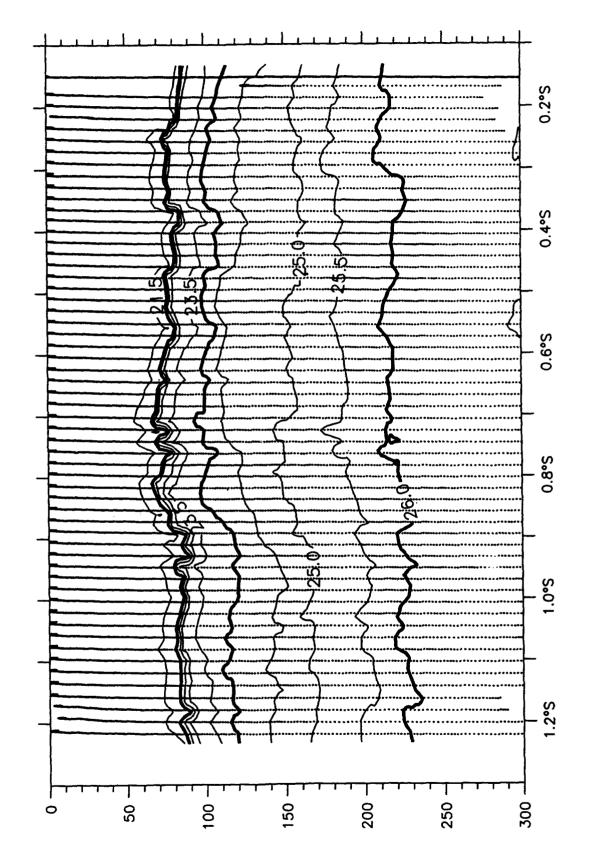
Sigma-t, E2N, 15 February 1993



T(°C), SBN to Equator, 15 February 1993



S(psu), SBN to Equator, 15 February 1993

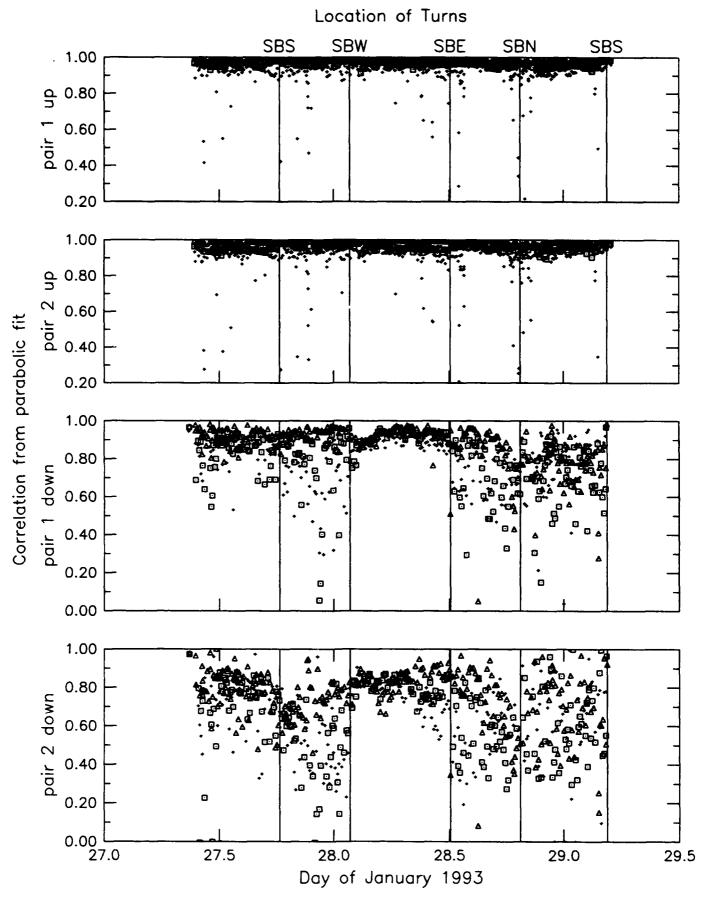


Sigma-t, SBN to Equator, 15 February 1993

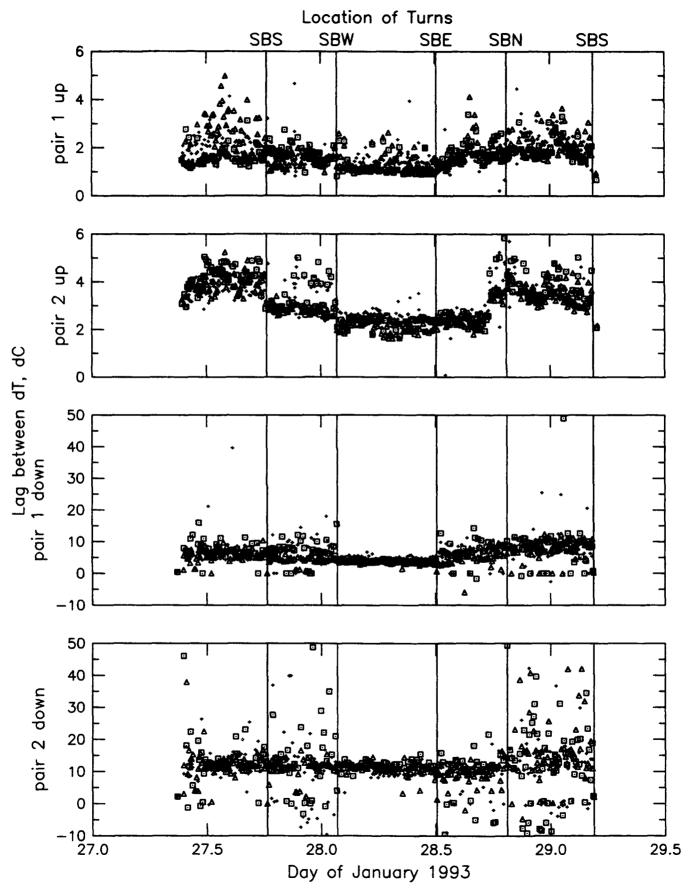
## APPENDIX A:

Time Series of Lag of Maximum T/C Correlation

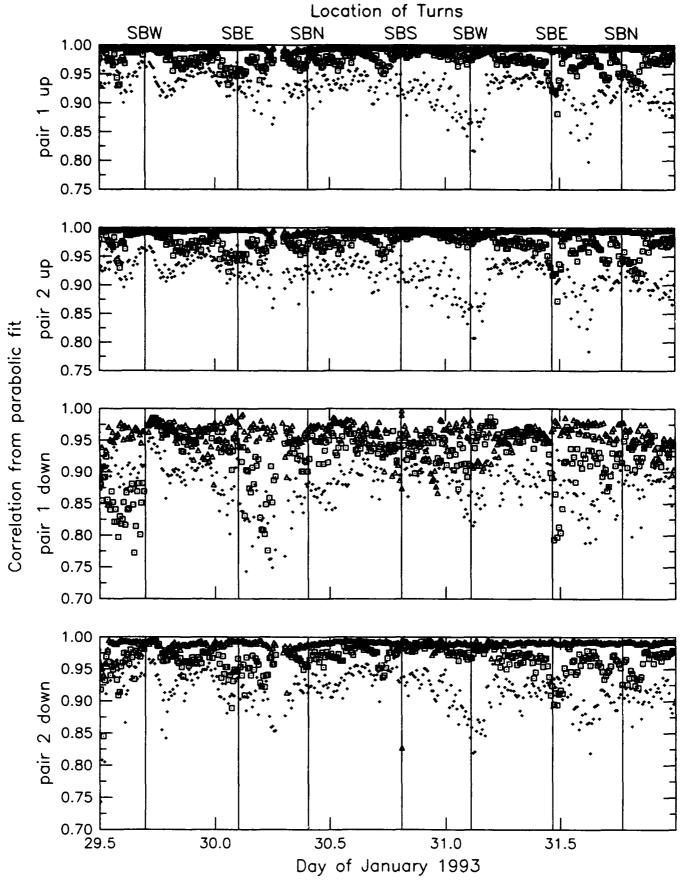
for Seasoar Tows 2-6



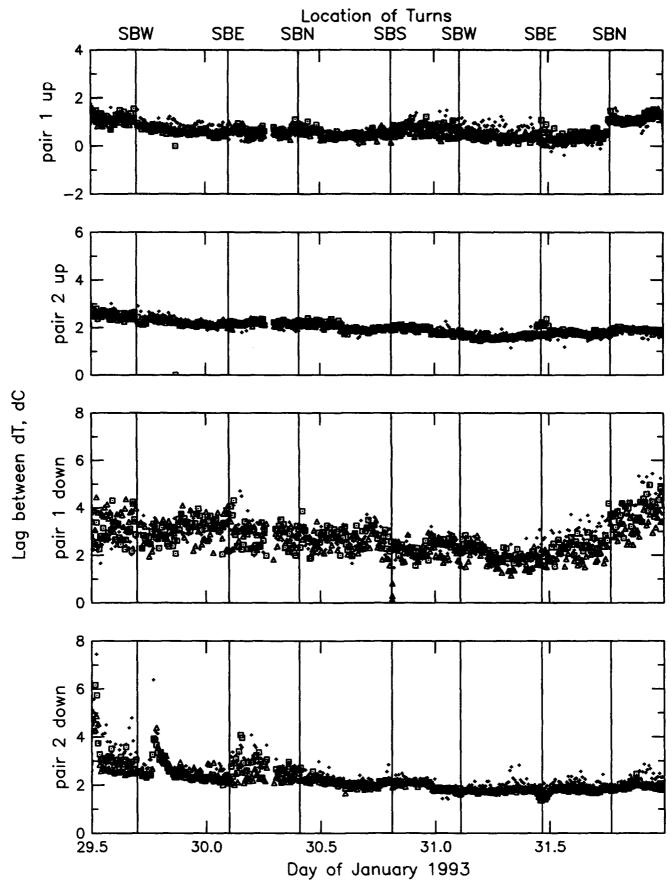
Leg 3 Tow 2, 50—120 db (plus), 120—180 db (square), 180—240 db (triangle



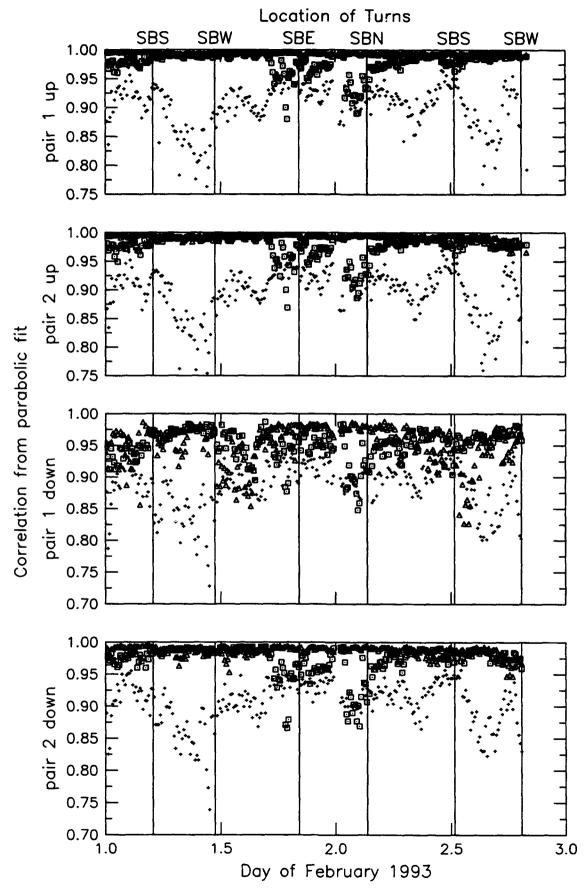
Leg 3 Tow 2, 50-120 db (plus), 120-180 db (square), 180-240 db (triangle



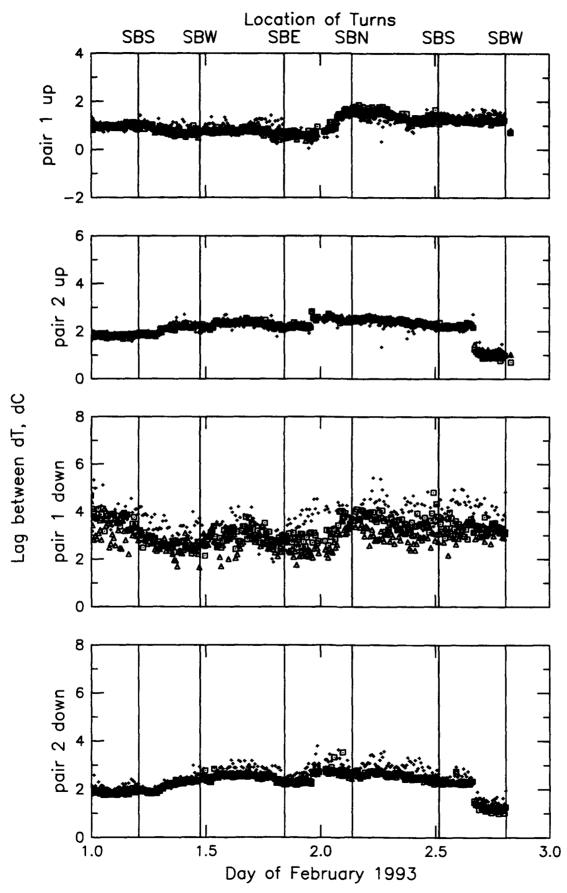
Leg 3 Tow 3, 50-120 db (plus), 120-180 db (square), 180-240 db (triangl



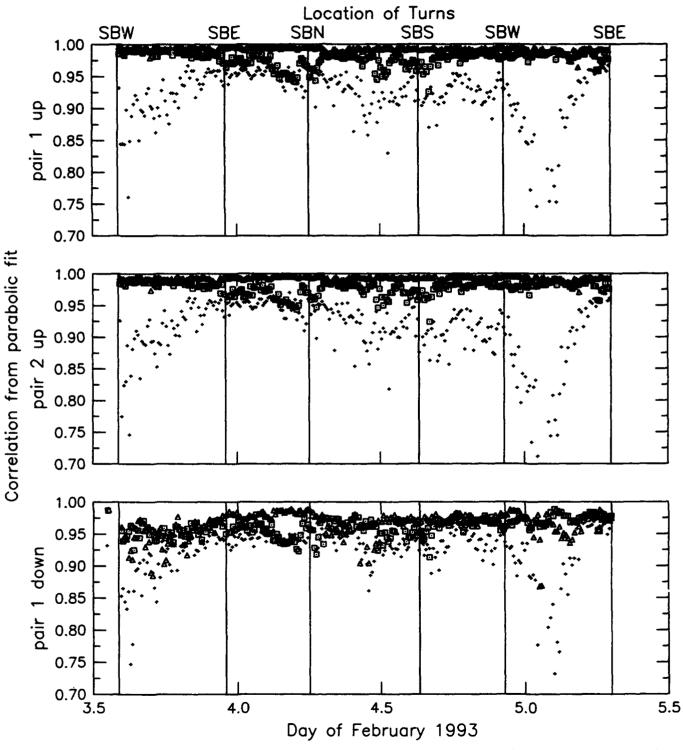
Leg 3 Tow 3, 50-120 db (plus), 120-180 db (square), 180-240 db (triangle



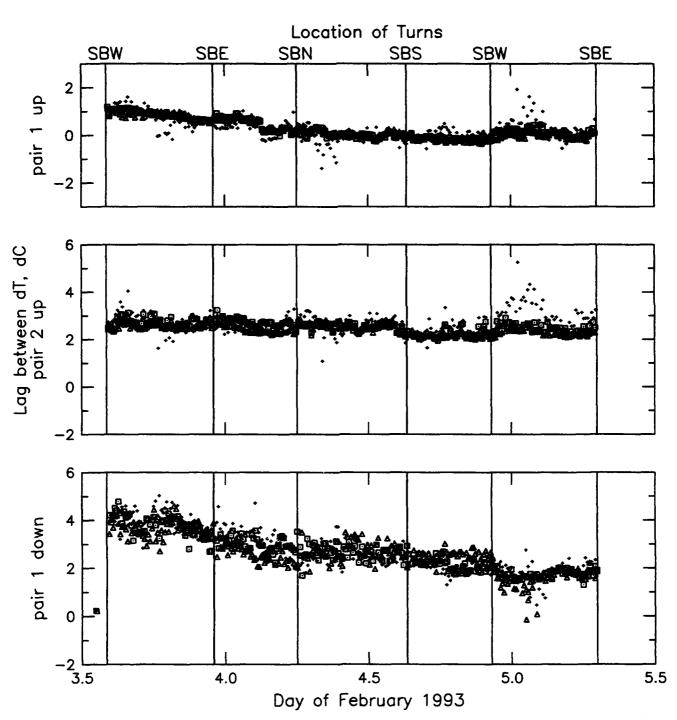
Leg 3 Tow 3, 50-120 db (plus), 120-180 db (square), 180-240 db (triangle)



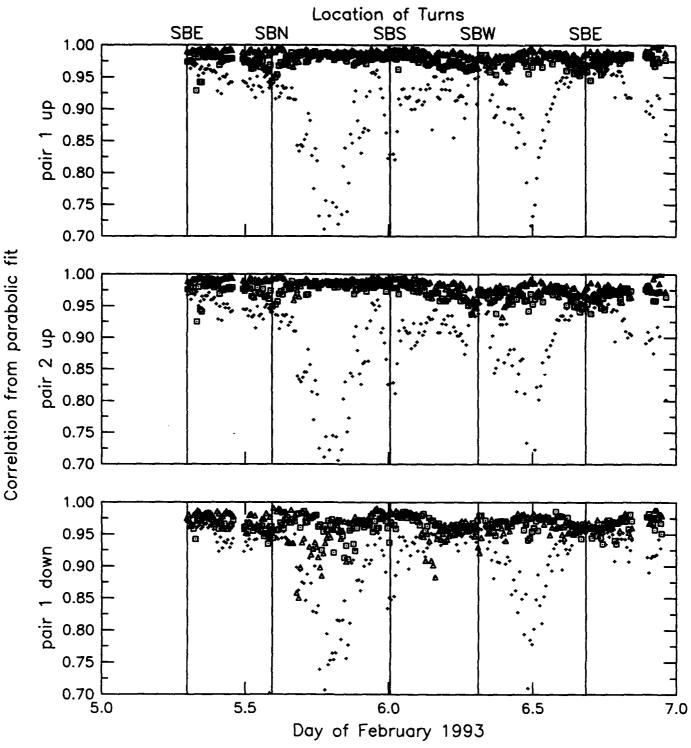
reg 3 Tow 3, 50−120 db (plus), 120−180 db (square), 180−240 db (triangle)



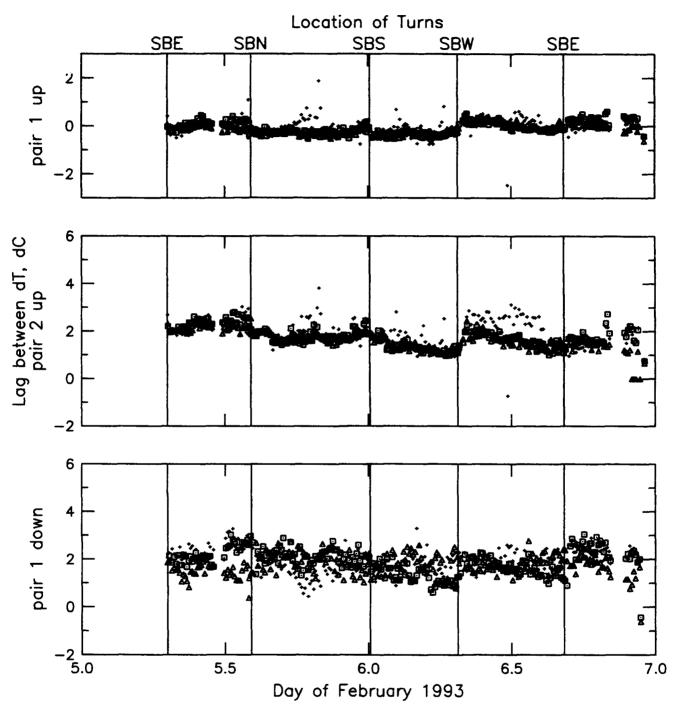
Leg 3 Tow 4, 50-120 db (plus), 120-180 db (square), 180-240 db (triangle



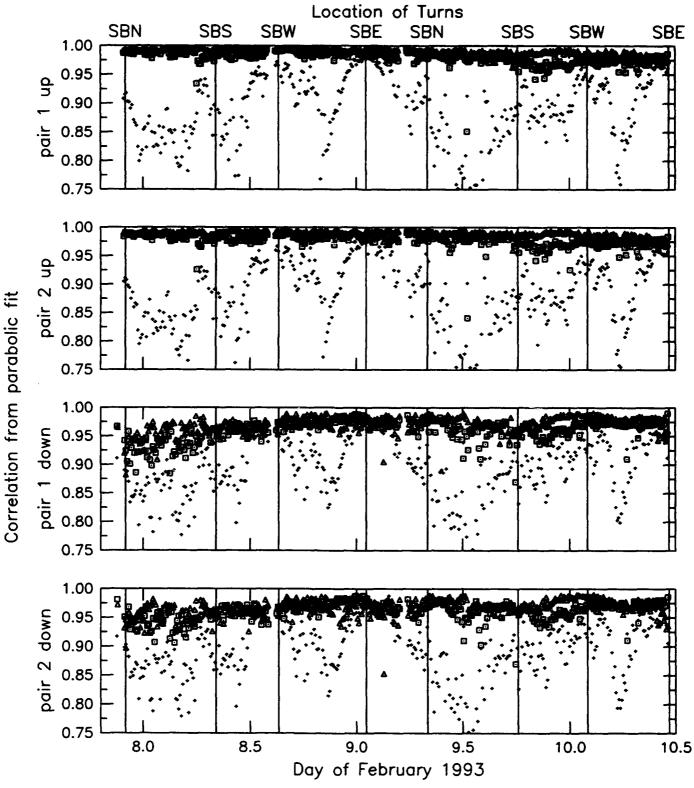
Leg 3 Tow 4, 50-120 db (plus), 120-180 db (square), 180-240 db (triangle



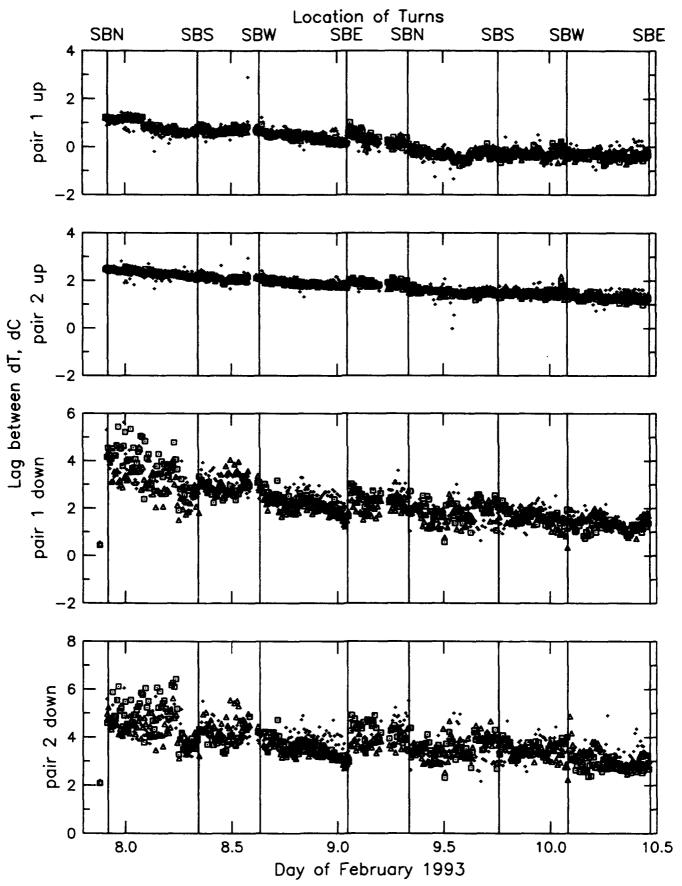
Leg 3 Tow 4, 50-120 db (plus), 120-180 db (square), 180-240 db (triangle



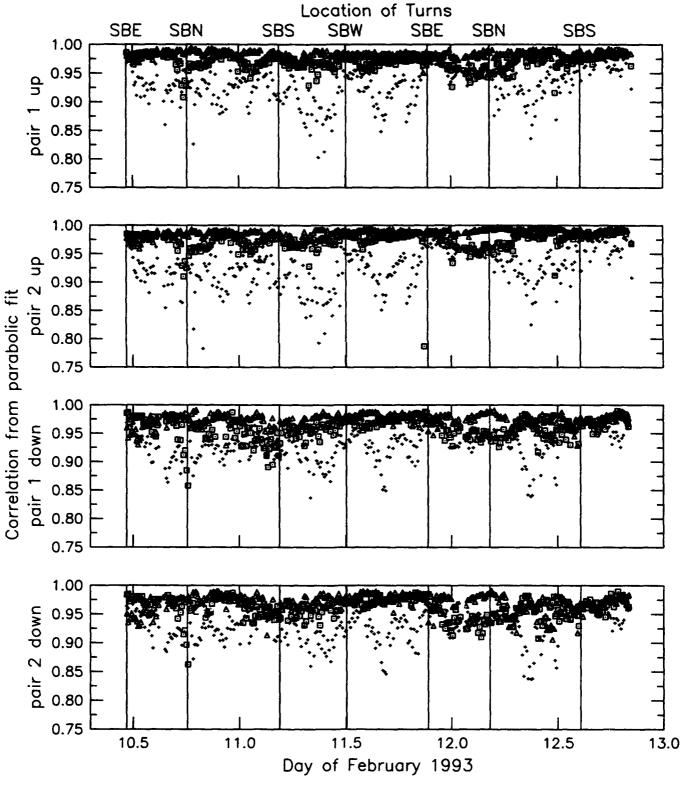
Leg 3 Tow 4, 50-120 db (plus), 120-180 db (square), 180-240 db (triangle



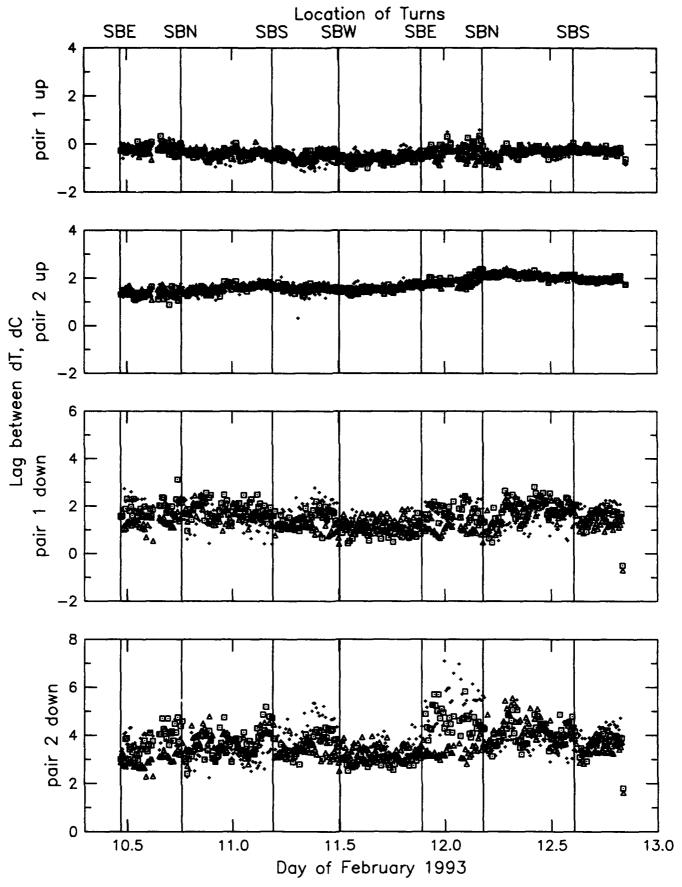
Leg 3 Tow 5, 50-120 db (plus), 120-180 db (square), 180-240 db (triangle



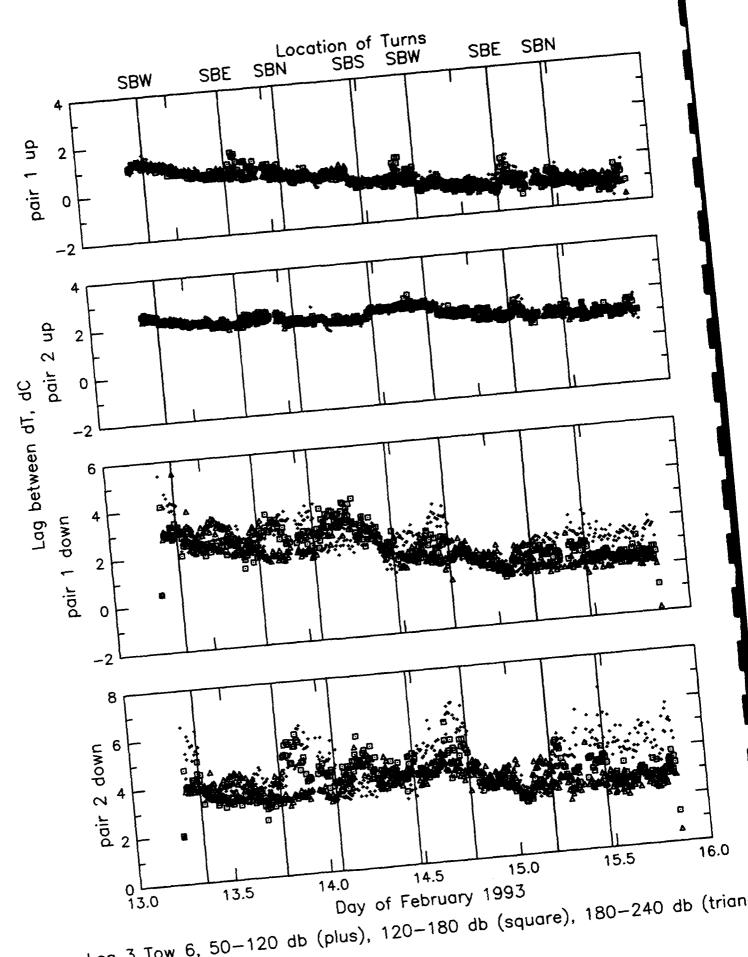
Leg 3 Tow 5, 50-120 db (plus), 120-180 db (square), 180-240 db (triangle



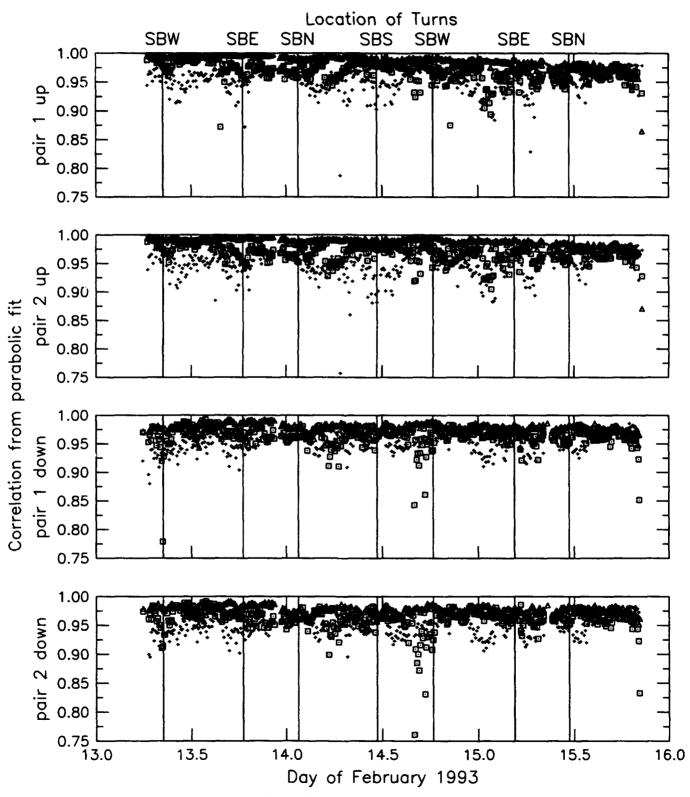
Leg 3 Tow 5, 50-120 db (plus), 120-180 db (square), 180-240 db (triangle



Leg 3 Tow 5, 50-120 db (plus), 120-180 db (square), 180-240 db (triangle



Leg 3 Tow 6, 50-120 db (plus), 120-180 db (square), 180-240 db (triangl



Leg 3 Tow 6, 50-120 db (plus), 120-180 db (square), 180-240 db (triangle

## APPENDIX B:

T-S Diagrams from CTD and Seasoar at Start and End of Tows 2-6.

